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GEORGIA INSTITUTE OF TECHNOLOGY
OFFICE OF CONTRACT ADMINISTRATION
SPONSORED PROJECT INITIATION

Date: November 28, 1978

Project Title: *Interactive Heuristics for Large Scale Transportation Models*

Project No: *E-24-682 Green card*

Co-Project Directors: *Dr. J. J. Jarvis and Dr. H. D. Ratliff*

Sponsor: *U. S. Department of Transportation; Transportation Systems Center*

Agreement Period: From 9/27/78 Until 12/31/79 (Performance Period)

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Sponsor Contact Person (s): *Manual, Operations Manual, etc.); Computer Tapes; Final Tech. Rpt.*

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Defense Priority Rating: *n/a*

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GEORGIA INSTITUTE OF TECHNOLOGY
OFFICE OF CONTRACT ADMINISTRATION
SPONSORED PROJECT TERMINATION

Date: 11/17/80

Project Title: Interactive Heuristics for Large Scale Transportation Models

Project No: E-24-682

Co-Project Directors: Drs. J.J. Jarvis & H.D. Ratliff

Sponsor: U.S. Department of Transportation

Effective Termination Date: 6/30/80

Clearance of Accounting Charges: 9/30/80 (for reporting)

Grant/Contract Closeout Actions Remaining:

- ☐ Final Invoice and Closing Documents
- ☐ Final Fiscal Report
- ☒ Final Report of Inventions
- ☐ Govt. Property Inventory & Related Certificate
- ☐ Classified Material Certificate
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DOT-TSC-T618 Progress Report
J. J. Jarvis and H. D. Ratliff

October 1st

Since the abstract was not finalized until after the start of classes, other commitments prevented Dr. Jarvis from beginning full participation in the project until January 1979. Airline crew scheduling problems as well as a number of local and through freight train scheduling problems were considered as possible demonstration projects for the interactive approach to scheduling being researched. We made several visits with Southern Railway as well as preliminary contacts with Delta Airlines. We determined that both the airline crew scheduling problem, and the train work scheduling problem would be satisfactory problems to demonstrate feasibility of our approach.

Because of the good working relationship we had established with Southern Railway, we decided that the train work scheduling problem was our first choice as a demonstration project. We began considering the various modeling constraints unique to this problem. We also began investigating the various graphic display devices available for implementation of our interactive system once it is developed. We determined that the Chromatics systems would suit our needs very well.

DOT-TSC-T618 PROGRESS REPORT
J. J. Jarvis and H. D. Ratliff

November 14

At our meeting at TSC it was decided that we would delay for the present our selection of a demonstration project. Our efforts would instead be directed toward development of the optimization methodology. The methodology required is a column generation scheme for the underlying set covering problem and a good heuristic for solving the resulting set covering problem.

Since a row pricing scheme is central to both the column generation and the heuristic, we have concentrated our effort on a study of the various pricing mechanisms which we might use. We have determined that a variation of the involutory basic pricing mechanism is superior in several respects to the original method. There is still a lot of work to be done related to what pricing mechanism is best. However, we feel that we have developed considerable insight into possible pricing structure.

DOT-TSC-T618 Progress Report
J. J. Jarvis and H. D. Ratliff

December 76

We continued our exploration of pricing mechanisms. We have proved a theorem which gives necessary conditions for the prices to satisfy in order that we will not exclude in optimum solution as a result of the column generation. We are now trying to determine what form these prices should take in order to be of value to a human interactor.

At the request of Dr. Ted Glickman, we began investigating Dial-A-Ride as a possible demonstration project. Preliminary examination indicates that the static version of this problem may be amenable to the kind of approach that we are studying. At this time, we do not see how to modify our approach to include in a reasonable fashion the dynamic aspects of this problem. We are continuing to study the Dial-A-Ride scheduling problem.

E-24-682

DOT-TSC-T618 Progress Report

J. J. Jarvis and H. D. Ratliff

January *Fl*

Dr. Jarvis will be 50% time for the winter quarter, Dr. Ratliff will remain 25% time. Two Ph.D students are working 1/3 time and one undergraduate student is working 1/3 time. In addition, another Ph.D student is affiliating with the project even though he is not being paid. He is currently on a presidential fellowship but would like to work on the project starting next fall, if it continues.

Georgia Tech has agreed to purchase a chromatics color graphics system (approximate cost - \$26,000) for use on this and other contracts. Several graduate assistants began orientation on utilizing the system to display and process the networks. The system is expected to be available sometime in May.

The entire team held several meetings on the design of the overall procedure. One subgroup is focusing on heuristics for improving the solution times for the covering problem component; another subgroup is concentrating on the display mechanisms and formats which would facilitate effective column generation (new candidate routes by the human component). The groups are currently testing and evaluating several alternatives for both parts of the system. All members of the team are also in the process of reading several dozen papers, from the literature, on various aspects of the problem.

The team concentrated on the Dial-A-Ride application. Dr. Ted Glickman arranged a meeting with John Wilson of the Atlanta Regional Commission (ARC) on the Dial-A-Ride systems in the Atlanta area. A meeting was held with Mr. Wilson at which time he gave an overview of the current systems. He also identified a candidate application and is arranging for the Tech team to meet with the operating agency to obtain specific data.

DOT-TSC-1618 PROGRESS REPORT

J. J. Jarvis and H. D. Ratliff

February

Drs. Jarvis and Ratliff met with Fred Coleman of Marietta-Cobb Community Service Center, and separately with Ruth Zaleon of Senior Citizen Services. Each of these agencies provides demand responsive transportation systems.

We discussed at length the currently operational procedures for the two demand responsive systems. We were able to gain considerable insight into dial-a-ride as these people see it. We concluded that some additional methodology is required if these systems are to be run as envisioned. We also concluded that any consolidation of systems will require a better scheduling methodology than the present if the combined system is to function at any reasonable level. The primary reason that those systems work as currently constituted is that they are small.

We have also been working on price directed heuristics for set covering problem. This class of heuristics appears to have great potential.

DOT-TSC-1618 PROGRESS REPORT

J. J. Jarvis and H. D. Ratliff

March

Our emphasis this month has been on the development of models which can aid in the interactive column generation process. We have broken the column generation process into three components: pricing, clustering, and chaining. We have previously developed some heuristics for pricing. This month we developed three fundamental models as candidates to aid in clustering. All three are variants of location/allocation models. We are modifying them to take advantage of human interaction. We have developed an assignment based model to "chain" together the clusters. The chained clusters will then go into the set covering model.

E-24-682

DOT-TSC-1618 PROGRESS REPORT

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J. J. Jarvis and H. D. Ratliff

April

Considerable time was spent in early April preparing for the conference on Transportation, Network Analysis and Control at the Transportation System Center. Drs. Jarvis and Ratliff had been invited to present their research at that conference.

Also during April, the Georgia Tech team received its Chromatics Colorgraphics terminal. Two of the graduate research assistants were assigned the duties of learning to operate this system and to integrate it into the overall scheduling system.

Effort continued on refining the pricing mechanisms as well as gaining additional experience with the clustering models. Feedback from individuals at TSC, responsible for dial-a-ride, indicated that the Georgia Tech team were developing promising models and methods for routing and scheduling dial-a-ride vehicles. Some consideration was also given to the larger class of problems solvable by the techniques being developed. Example applications in this class include: the moving van problem, train work scheduling, freight haul scheduling, and certain military logistics applications.

xc: Al Becker

6-13-79

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DOT-TSC-1618 PROGRESS REPORT

J. J. Jarvis and H. D. Ratliff

May

During this month, substantial progress was made in developing and testing computerized codes for clustering, and for network generation and human interface with the Chromatics Colorgraphics terminal. Testing of the computer code for clustering uncovered several difficulties with the basic clustering model. Various mathematical approaches to modifying these models to alleviate these difficulties were tried.

As the team gained more experience with the Colorgraphics terminal, the overall interactive philosophy began to take on new direction. In addition, prototype testing of example dial-a-ride problems with fifty trips indicated difficulties with parts of the overall scheduling system. This led to revisions of portions of the interactive philosophy.

Several new results were developed, with necessary proofs, for improving the pricing mechanism associated with the covering model. In addition, the emerging interactive philosophy, now encompasses two covering models: one associated with clustering and the other associated with chaining.

xc: Al Becker

6-13-79
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DOT-TSC-1618 PROGRESS REPORT
J. J. Jarvis and H. D. Ratliff

June, 1979 Thru August, 1979

These summer months were spent developing the demonstration software packages, as per contract requirements. The demonstration was conducted on August 24 with TSC and UMTA/NBS Officials present. The software links the Chromatic Colorgraphics computer to the CYBER 74 computer located on the Georgia Tech campus.

The software residing on the CYBER 74 consist of a number of program modules. One program module, the driver, handles all information flows between the Chromatics and the CYBER. This driver module generates and maintains all of the necessary data base for the operation of the dial-a-ride routing and scheduling system. As second program module on the CYBER handles the solution of the associated covering problems generated in the dial-a-ride scheduling process. This same module also develops the necessary prices used in other portions of the algorithm. A third module handles all of the clustering requirements. This includes implementation of the location allocation model as well as implementation of the pricing concept. The clustering module is particularly flexible in that it permits fixed point as well as Euclidean clustering approaches. It also accepts varying parameters in each of these models. A fourth program module residing on the CYBER, handles all of the routing requirements within the various clusters. This module consists of a branch and bound superimposed on a travelling salesman algorithm. The branch and bound is necessary because of the sequencing constraints resulting from the fact a patron must be first

picked up before he/she is dropped off. The last major module in the CYBER package consist of a network flow algorithm for the chaining process. This algorithm is variant of the out-of-kilter algorithm for network flows.

The software residing on the Chromatics is designed to handle all of the display capability on the screen, the acceptance of information from the CYBER, and the acceptance of input from the human, through light pen and/or keyboard. The data base requirements and associated software on the Chromatics side of the total interactive optimization system are much more complex. This is a result of the fact that the human can perform certain functions (e.g. routing) himself or he can request routing from the CYBER. This same flexibility extends to other aspects of the scheduling system including clustering and chaining.

The data base for the August 24 demonstration consisted of 27 randomly generated trips in a typical dial-a-ride example. During the demonstration it was suggested that the system might be best tested on a set of real data coming out of either Cobb County Georgia, which the Georgia Tech team has visited, or Rochester, New York, which TSC officials had data for.

September 1979 Thru December, 1979

During these fall months the Georgia Tech team concentrated its effort in three distinct areas. Graduate students revisited the Cobb County agency and collected data on several weeks request for dial-a-ride service. Members of the Georgia Tech team are involved in reducing and coding the data obtained. Officials from TSC supplied the Georgia Tech team with a tape of data on the Rochester dial-a-ride system. Others members of the team are involved in stripping the data off this

tape and processing it into a form suitable for input to the interactive optimization package. A second major effort of the team has been the continued development and refinement of modules and systems for the interactive optimization package. A linear clustering model has been designed, developed and is in the process of being tested. Rather than clustering to a trip or a pseudo trip, the concept here is projection on to a straight line which would represent essentially the mean locations among the trips. The expectation is that all of the models for clustering will be subjected to a rigorous analysis and testing phase to determine those most appropriate for the optimization package.

Continued development and refinement of the chaining model has progressed along the lines of application of penalty function concepts. Such techniques are under consideration to handle the side constraints generated by the requirement that a trip not be in more than one cluster in a given chain. In the penalty function approach these "nasty" constraints are multiplied by an appropriate penalty and combined into the objective function, leaving a "nice" network flow problem remaining for which efficient solution techniques exist. The penalty function procedure proceeds with a search over appropriate values for the penalties.

The third major thrust during the fall months has been a concentration on the development of techniques and modules which are based on more intuitive insights into the dial-a-ride scheduling process. This focus on intuitive algorithm development is necessitated by a desire to develop scheduling packages that can be implemented totally on the Chromatic Colorgraphics system, without requirement for utilization of the CYBER computer. A savings heuristic has been developed for clustering

in the dial-a-ride process. This savings approach implements the pricing mechanism to aid in adding one trip at a time to a cluster being built. Initial testing of the savings approach appears to be very favorable.

ACTUAL & PROJECTED EXPENDITURES ON CONTRACT TSC/22-0029-RN

June 13, 1979

(GEORGIA TECH #E-24-682)
J. J. JARVIS & H. D. RATLIFF
(AMOUNT/CUMULATIVE AMOUNT)

Month	(1) Personal Services Principal Investigators	(2) Personal Services Graduate Assistants	(3) Retirement on (1)	(4) Overhead on (1)+(2)	(5) Travel	(6) Computer	(7) Materials & Supplies	(8) Total
October, 1978	\$ 698 (43 hrs.) 698	\$ 0 0	\$ 69 69	\$ 530 530	\$ 0 0	\$ 0 0	\$ 0 0	\$ 1,297 1,297
November	698 (43 hrs.) 1,396	0 0	69 138	530 1,060	462 462	0 0	0 0	1,759 3,056
December	698 (43 hrs.) 2,094	0 0	69 207	530 1,590	0 462	0 0	3 3	1,300 4,356
January, 1979	1,890 (130 hrs.) 3,984	0 0	186 393	1,436 3,026	0 462	0 0	2 5	3,514 7,870
February	1,890 (130 hrs.) 5,874	0 0	186 579	1,436 4,462	0 462	0 0	0 5	3,512 11,382
March	1,890 (130 hrs.) 7,764	0 0	186 765	1,436 5,898	0 462	0 0	147 152	3,659 15,041
April	1,890 (130 hrs.) 9,654	933 (116 hrs.) 933	186 951	2,145 8,043	567 1,029	0 0	57 209	5,778 20,819
May	1,294 (87 hrs.) \$10,948	933 (116 hrs.) \$1,866	127 \$1,078	1,693 \$ 9,736	182 \$1,211	0 \$ 0	250 \$459	4,479 \$25,298
PROJECTED THROUGH CONTRACT DURATION								
June	\$ 3,881* (87 hrs.) 14,829	\$1,185 (151 hrs.) 3,051	\$ 381 1,459	\$ 3,851 13,587	\$ 0 1,211	\$1,500 1,500	\$ 37 496	\$10,835 36,133
July	5,402 (260 hrs.) 20,231	1,875 (134 hrs.) 4,926	568 2,027	5,531 19,118	0 1,211	1,500 3,000	0 496	14,876 51,009
August	5,402 (260 hrs.) 25,633	1,875 (134 hrs.) 6,801	568 2,595	5,531 24,649	750 1,961	1,500 4,500	0 496	15,626 66,635
September	5,402 (260 hrs.) \$31,035	0 \$6,801	568 \$3,163	4,106 \$28,755	0 \$1,961	0 \$4,500	300 \$796	10,376 \$77,011 [†]

* This amount includes three (3) checks paid to individuals on academic year contracts, since these contracts are paid in twelve (12) checks.

† Some adjustment in individual category amounts will be necessary to bring this figure to within allocated contract amount.

cc: Al Becker

Master Cost Schedule

Monthly cost rpts thru May 1979

FINAL REPORT

**INTERACTIVE HEURISTICS FOR LARGE
SCALE TRANSPORTATION MODELS**

Submitted By:

Principal Investigators

John J. Jarvis

H. Donald Ratliff

Graduate Research Assistants

Frank H. Cullen

David J. Friedman

Robert T. Lewis

Submitted To:

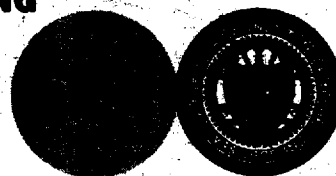
**U.S. DEPARTMENT OF TRANSPORTATION
TRANSPORTATION SYSTEMS CENTER**

Under

Contract No. DOT-TSC-1618

August 1980

GEORGIA INSTITUTE OF TECHNOLOGY
SCHOOL OF INDUSTRIAL & SYSTEMS ENGINEERING
ATLANTA, GEORGIA 30332



FINAL REPORT

CONTRACT NO. DOT-TSC-1618

INTERACTIVE HEURISTICS FOR
LARGE SCALE TRANSPORTATION MODELS

Submitted To:

U. S. Department of Transportation
Transportation Systems Center

Submitted By:

John J. Jarvis

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August 1980

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The research team wishes to thank Bob Crosby of the United States Department of Transportation (U.S. D.O.T.) and to Ed Roberts and Ted Glickman of U.S. D.O.T.'s Transportation Systems Center in Cambridge, Massachusetts for their guidance, support and encouragement. They provided the framework and insights into the Dial-A-Ride application area.

The project team also wishes to thank Paul Connolly of the Transportation System Center for providing dial-a-ride data for Rochester, New York. He and his staff were extremely helpful in coding and interpreting the data for the CYBER 74 computer at Georgia Tech.

Finally, the team acknowledges the tremendous help of Fred Coleman and his staff at Marietta - Cobb Community Service Center in Cobb County, Georgia for supplying insights and data on their dial-a-ride system.

ABSTRACT

This report summarizes the results of an intensive study into the application of interactive heuristics in transportation systems design and analysis. Project results include (1) the development of new methodology to aid researchers and practitioners and (2) a set of computer codes which were used to test concepts and to demonstrate the potential usefulness of the approach. Human Aided Optimization/Heuristics will clearly prove more important in the 1980's as we learn more about those functions which humans can perform better than computers (such as spatial pattern processing), and find unique ways to integrate these capabilities into a human/computer system.

In the area of methodology, the project has resulted in the development of new theorems and lemmas detailing the concept of "prices" for set covering and set partitioning problems. The prices are similar to those for linear programs, however, because they have been developed for integer programs they don't enjoy some of the nicer properties of linear programming dual variables. Set partitioning models are developed for the dial-a-ride and delivery problems. The research suggests a decomposition of these complex problems by employing two concepts called "clustering" and "chaining".

Clustering involves the grouping of trips, bus stops, demand points, etc. into logical subsets which should be served by the same vehicles. The report presents several models for clustering, as well as supporting theorems and lemmas. The application of clustering models to United States Department of Transportation data for the Rochester, NY Dial-A-Ride transit system are also presented. Our tests indicate that there is significant potential for this kind of approach to demand responsive transportation routing and scheduling.

The concept of chaining was developed to provide a means for linking the clusters into logical vehicle routes. Several models were developed and tested for chaining. A Lagrangian relaxation approach has been developed and tested on sample data. More research is required before chaining can become a function useful for immediate practical implementation.

To test the methodology and concepts developed, a human aided (heuristic) optimization system was developed for the dial-a-ride and delivery problems. The computer system consisted of a Chromatics Color Graphics (high resolution) computer system for presentation of visual/spatial information to the human and a CDC CYBER 74 computer system to perform the optimization functions in support of the human aided optimization process. For dial-a-ride problems, these codes were tested on sample data sets and on data sets for Rochester, New York and Cobb County, Georgia.

The project also tested the feasibility of a stand alone mini computer interactive heuristics system for transportation systems analysis. Codes, which reside entirely on the Chromatics computer, were developed and tested on a series of delivery problems. Three "classic" delivery test problems - a 50-point, a 75-point, and a 100-point problem - were used. These three problems have been tried, during the last decade, by dozens of researchers with different approaches to (fully automatic) computer systems. Due to their complexity, the optimal solutions to these problems are not known. This report shows that, in the 50 and 75-point problems, after a few iterations the human aided computer system was able to obtain the best known solution. In the case of the 100-point problem the system was able to obtain a better solution than any yet obtained. These results provide significant encouragement for the approach outlined in this report.

I. INTRODUCTION

This report summarizes research into interactive heuristics for large scale transportation systems analysis and design. The research suggests that by employing the human capability for spatial pattern processing together with the immense computing power of today's computers, both the human's and computer's ability to handle complex transportation problems is enhanced.

The bulk of this final report consists of three technical reports which were produced in the three major areas of research on the project. These three areas include: (1) an overall modeling process for interactive heuristics in routing, (2) concepts and models in clustering and (3) concepts and models in chaining. The technical reports detailing each of these areas are contained in Appendix A of this final report.

Certain of the models developed under this contract were coded in FORTRAN for a CDC CYBER 74 and BASIC for a Chromatics CG 1999 color graphics computer. These codes were tested against (1) routing data from the literature, (2) data from Rochester, NY and (3) data from Cobb County, GA. These codes are presented in Appendix B of this report.

II. METHODOLOGY

The fundamental modeling approach taken in this research is to employ a set partitioning formulation of the routing problems studied (dial-a-ride and delivery). A set partitioning matrix has one row for each trip (or point to be visited) and one column for each feasible route. Thus, while the matrix has a reasonable number of rows it has an enormous number of columns.

To circumvent the column difficulty we have suggested a column generation approach which only identifies columns as they appear to be favorable to producing a better solution. In order to accomplish this, quantities called "row prices" have been developed. These prices act like dual variables in linear programming except that they are associated with integer programs (the set partitioning problem).

The details of the modeling methodology are given in technical report #J-80-1 in Appendix A. In the interactive process, the computer solves the set partitioning problem at hand, generates the row prices and suggests candidate trips or delivery points to examine next (based on a savings approach). The human guides the overall process, accepts, rejects or develops candidate routes, and provides the stopping criteria for the algorithm.

Especially important in the dial-a-ride problem, is the need to decompose the complex task of developing good candidate routes. Thus, two decomposition concepts - clustering and chaining - were developed. In clustering we seek to identify those trips whose origins and whose destinations are reasonably close together so that they would logically be picked up and delivered by the same vehicle. These individual trips are then replaced by a single pseudo (cluster) trip. Technical report #J-80-15,

in Appendix A, describes several models and procedures for clustering.

Once good cluster trips are identified the focus is then shifted to chaining (linking) these clusters into feasible routes. Models and algorithms for chaining are developed in technical report #J-80-16, in Appendix A.

The dial-a-ride procedure has been coded for a linking of a Chromatics CG 1999 color graphics computer with a CDC CYBER 74 computer. The cyber performs large scale computing functions such as set partitioning solution generation, minimal cost network flow computation, solution of certain clustering models, and application of a traveling salesman algorithm. The Chromatics color graphics computer handles various display functions and simple data manipulation. In addition, a special data development program was coded for Cobb County, GA dial-a-ride data.

A delivery algorithm has also been coded for the same computer combination. The cyber generates traveling salesman solutions as required, and the chromatics performs all other functions. The current operating version does not employ the set partition solution procedure. Instead entire new solutions are generated at each iteration.

III. MICROCOMPUTER STAND ALONE CAPABILITY

A version of the dial-a-ride algorithm which resides entirely on the chromatics color graphics computer, was coded and tested. This version does not use the sophisticated minimal cost network flow algorithmic, traveling salesman procedure in set partitioning algorithm. Instead it utilizes the human to perform these functions.

Moderate testing of the stand alone code indicates that it can perform reasonably well in a dial-a-ride routing and scheduling environment. However, this version does require much greater involvement of the human in solution development.

The delivery code was developed in such a way that, if the human did not request a traveling salesman solution, the chromatics computer could act independently. The only purpose of the traveling salesman procedure is to guarantee an optimum route among the set of selected delivery points. Since the human usually does a very good job at developing new optimal routes as he/she is building them, this procedure currently acts much better as a stand alone method.

IV. APPLICATION OF THE METHODOLOGY

Each of the computer codes was thoroughly tested on a number of randomly generated test problems. In addition, tests were conducted with data provided from three other sources: the literature, U. S. Department of Transportation officials, and local Atlanta dial-a-ride administrators.

The delivery algorithm was tested on three problems from the literature (see report #J-80-1). These were a 50-city, 75-city and 100-city delivery problem. As indicated in the report, the delivery algorithm performed quite well in every case (equaling or exceeding the best known solution). These results provide much encouragement for further development and testing of the method.

As a first test of the dial-a-ride procedure, several weeks data was taken for a dial-a-ride transit system in Cobb County, GA. The system consists of 4 vehicles and handles approximately 50 daily trips.

A special data input program (see Appendix B) was developed to allow the graphical input of data for this system. Figure 1 gives an example of the input data. The computer generates the area maps and the human operator inputs the trips (straight lines and boxes) by simply pointing a light pen at the origin and destination of each trip.

Data was entered for a typical weekday a.m. operation (8:00 a.m. - 12:00 noon) of the Cobb County dial-a-ride system. While comparison data was unavailable, the computerized dial-a-ride procedure appeared to perform quite well in generating good vehicle routes.

Finally, the models were applied to a sample cluster set for the Rochester, NY dial-a-ride system. Particular emphasis was given to the applicability of the clustering models in a "real-world" environment. The following figures illustrate results of the application. In

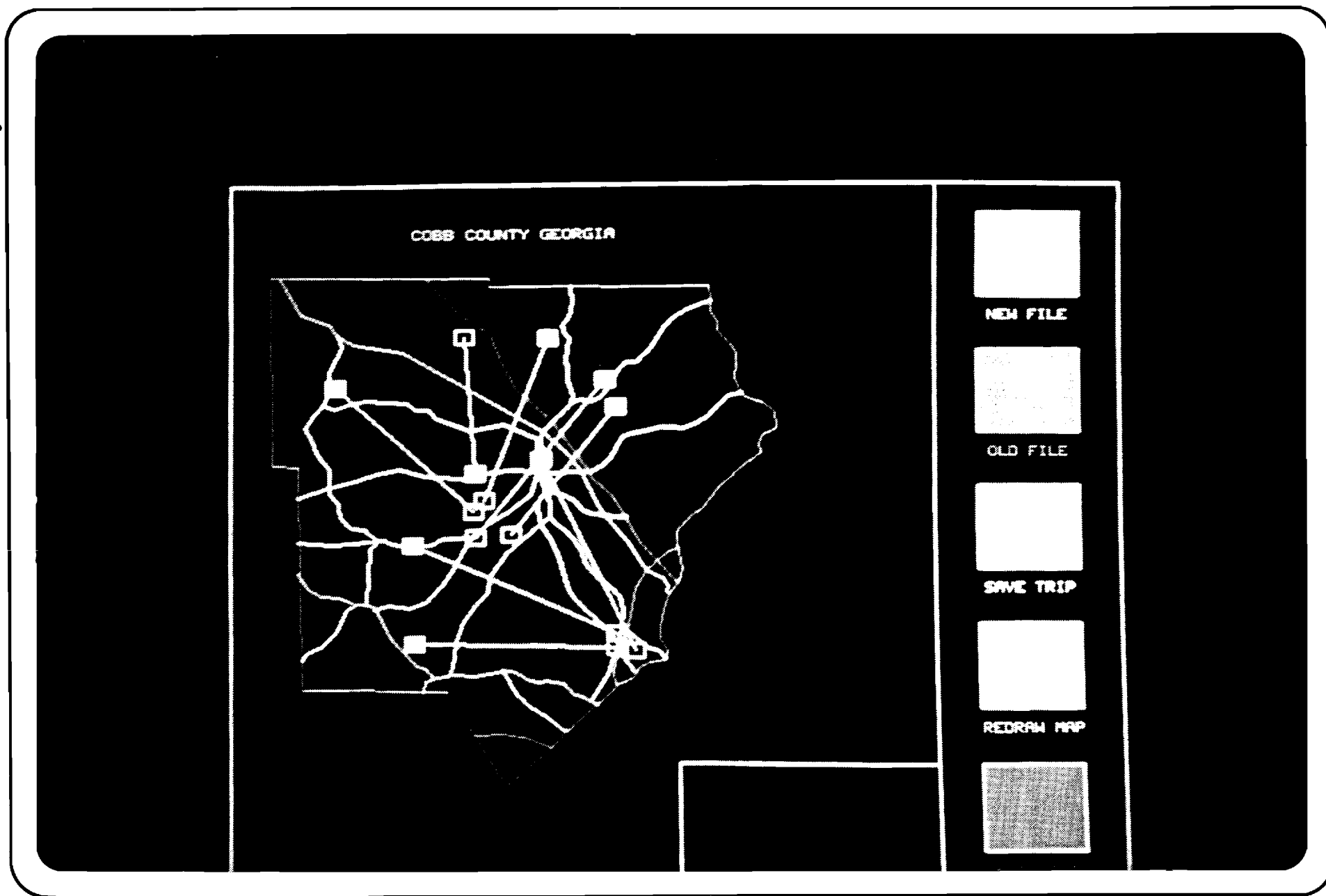


Figure 1. An Example of the Cobb County Data Input Program

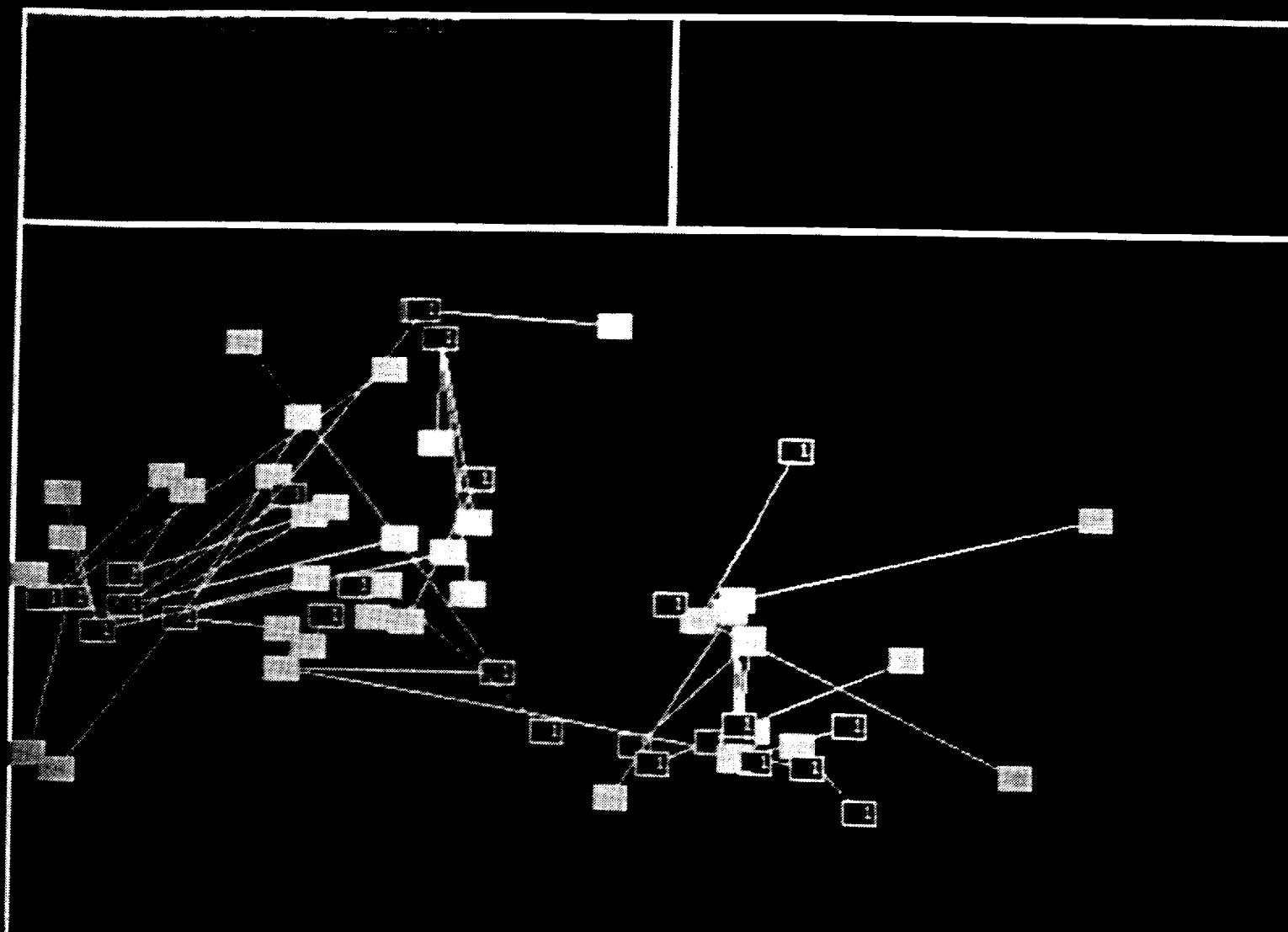


Figure 2. A Sample of 42 Trips for the Rochester Dial-A-Ride System

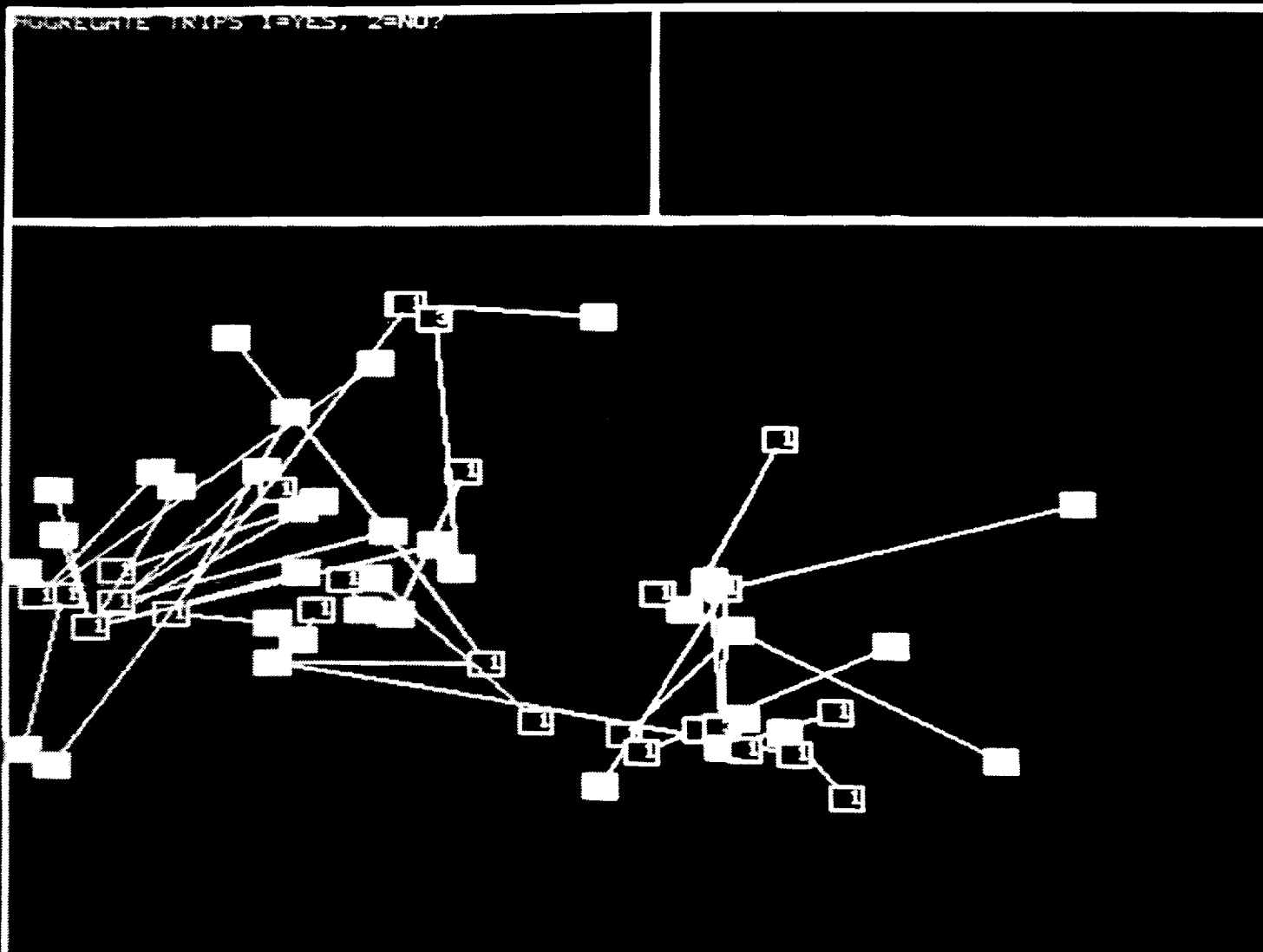


Figure 3. Preprocessed Rochester Dial-A-Ride Data

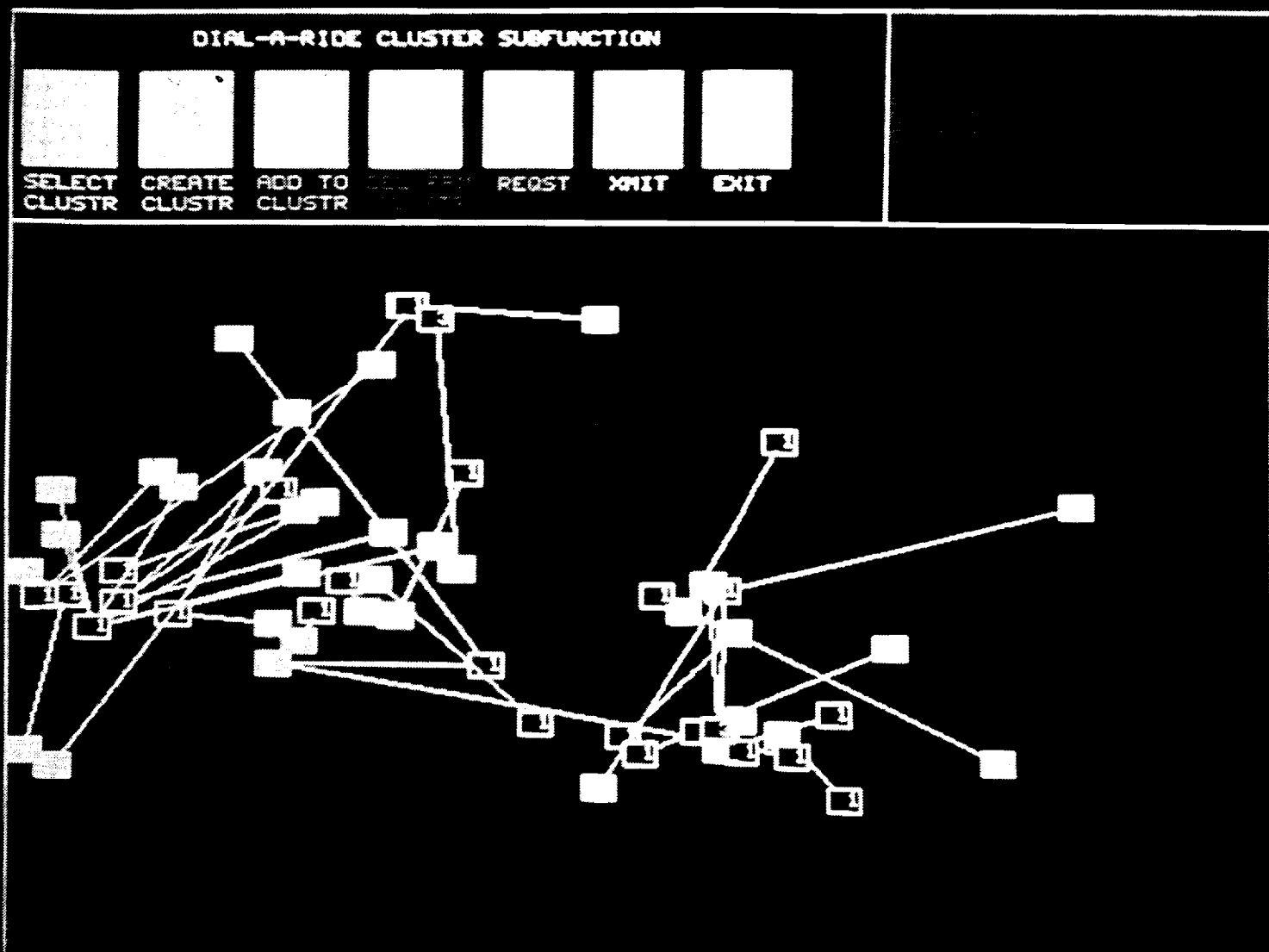


Figure 4. A Request for Six Clusters of Not More Than 10 Trips Each

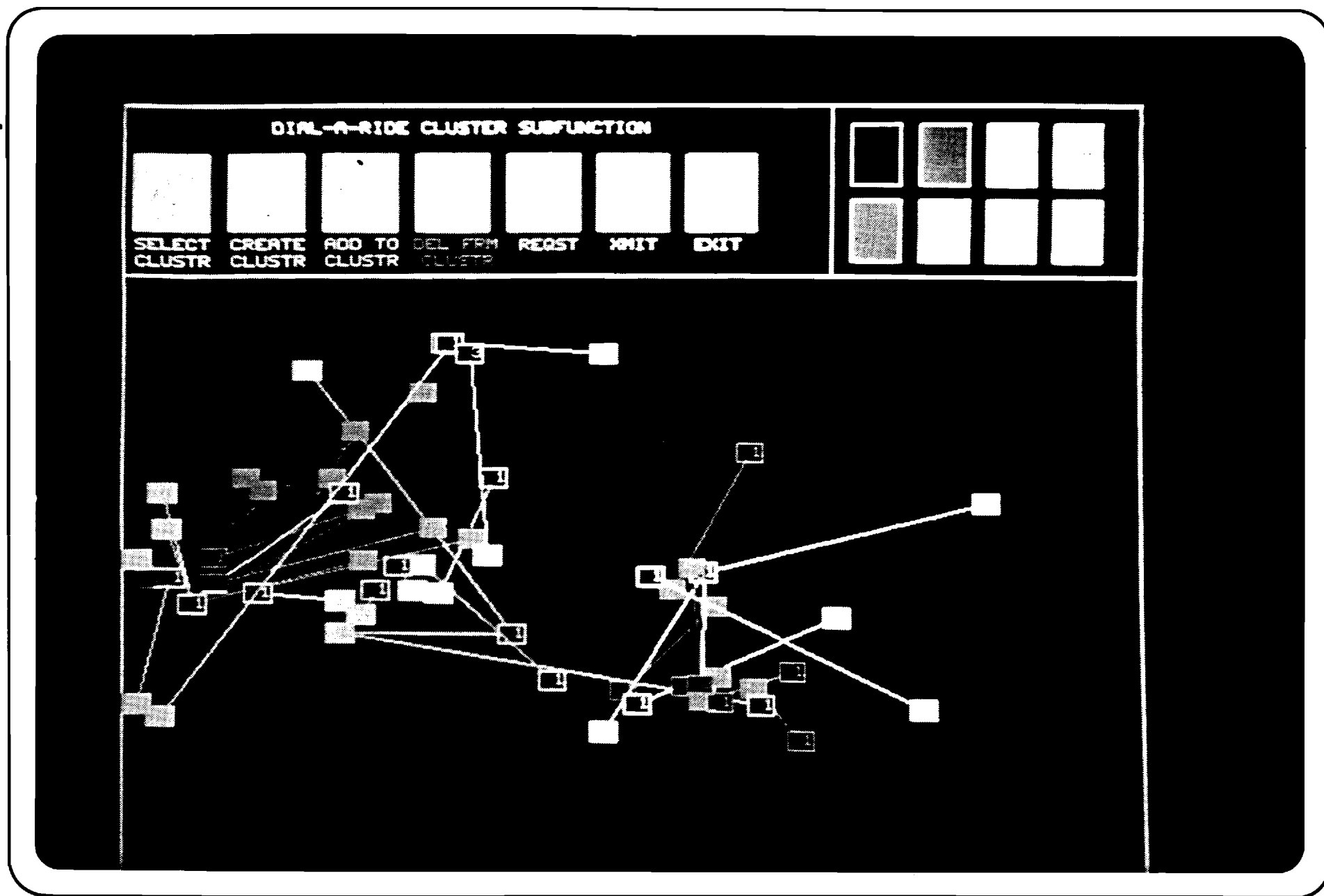


Figure 5. Results of the Cluster Request of Figure 4

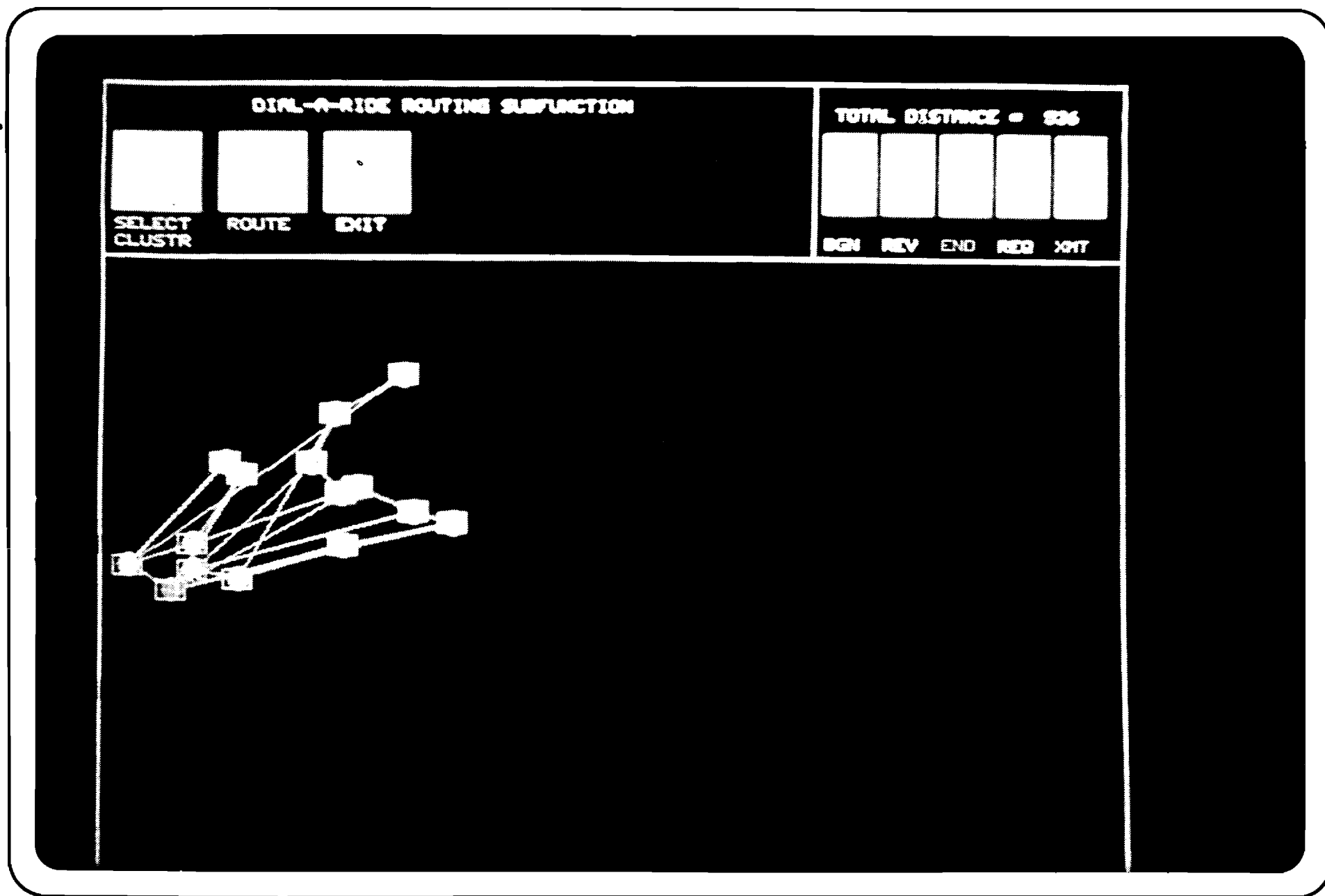


Figure 6. Routing Through A Cluster

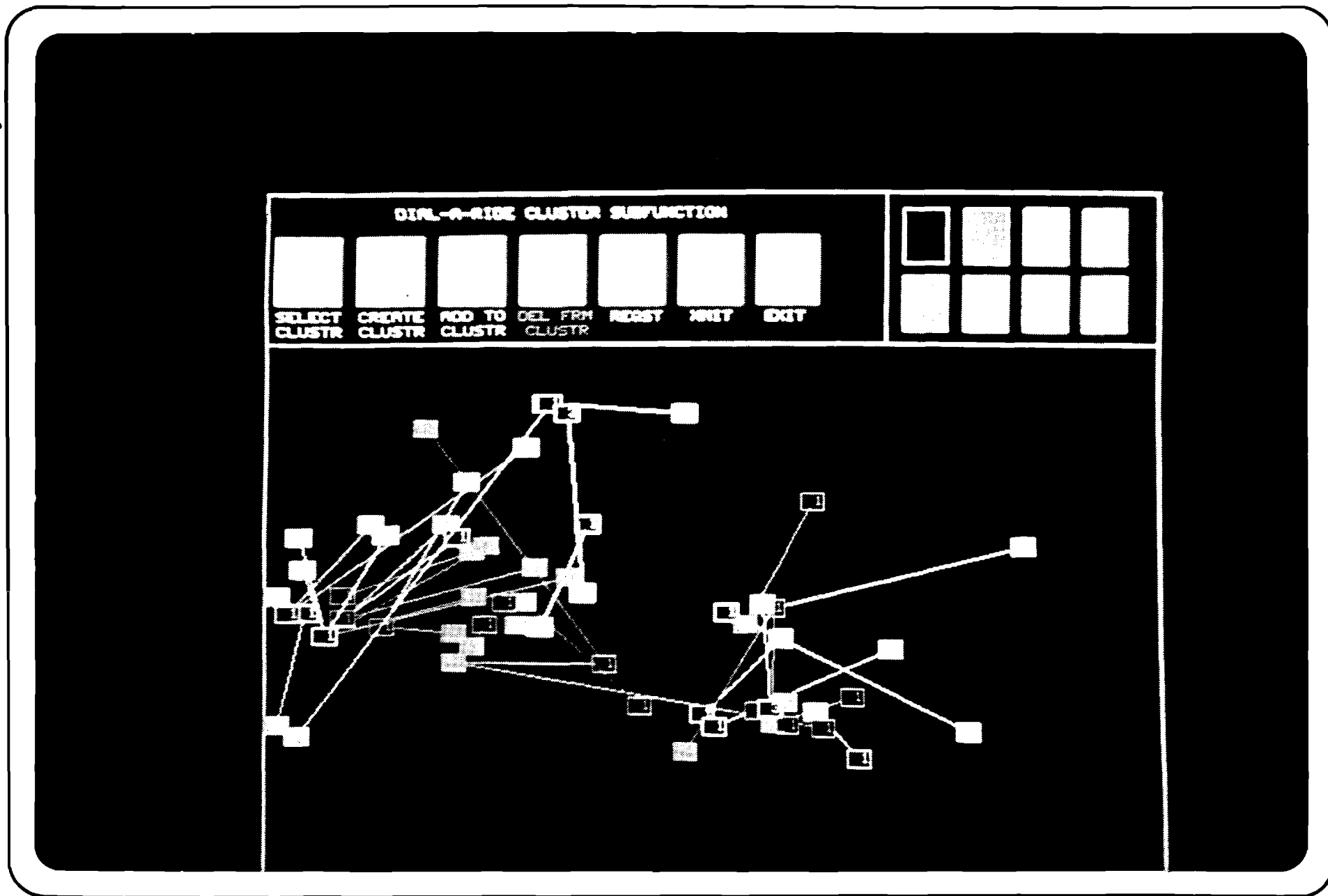


Figure 7. Results of a Ten Cluster Request (Dark Blue, Light Blue, Red and Green Repeated)

general, the models performed quite well. However, this application pointed to a special difficulty which had to be overcome before the application could be completed.

In the Rochester data selected, many of the origins and many of the destinations were the same. While this enhanced the capability of the clustering algorithms, the human was subjected to problems of clutter due to the closeness of different trips. A special preprocessing program was developed which combined several trips into a single cluster trip for further processing. After this was accomplished the procedure functioned well.

V. FURTHER RESEARCH

The results of this research demonstrate the applicability of interactive heuristics for transportation design. However, much additional research must be conducted before definitive conclusions can be drawn of which models should be employed and how great a role the human should play in the process.

APPENDIX A

TECHNICAL REPORTS

APPENDIX A-1

TECHNICAL REPORT:

SET PARTITIONING BASED HEURISTICS
FOR INTERACTIVE ROUTING

SET PARTITIONING BASED HEURISTICS
FOR INTERACTIVE ROUTING

by

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ABSTRACT

The set partitioning model is used as the basis for an interactive approach for solving a broad class of routing problems. A pricing mechanism is developed which can be used with a variety of methods in generating improving solutions. A version of the approach for delivery problems has been implemented via a colorgraphics display. The Human Aided Optimization procedure was tested on the standard 50-point, 75-point and 100-point test problems of Eilon, Watson-Gandy and Christofides [6]. In the case of the first two test problems, the procedure was able to generate the best known solutions. In the 100-point problem, a better solution was generated than the current best known solution.

1. INTRODUCTION

We will consider here a set partitioning based approach for solving a broad class of routing problems. The approach is designed to take advantage of a high level of human interaction; the current implementation is interactive via a colorgraphics display. However, many of the concepts discussed here could be easily implemented in an automatic system.

The routing problem which motivated much of this work is what is called the static or subscriber dial-a-ride problem. This problem will be discussed in detail in later sections. It is one of the more complex members of the class of routing problems which are amenable to the approach presented here. This class also includes many practical delivery problems.

In order to introduce the underlying methodology which provides the basis for the approach, consider a very simple delivery example. Assume that a depot is located at the square box labeled D in Figure 1. From this depot a single delivery is to be made to each of the points represented by numbered circles. The numbers on arcs connecting the circles represents the travel distance between delivery points. Assume also that each vehicle (e.g. truck) can deliver to a maximum of two points on a single trip. The objective is to determine which vehicle should deliver to each point and the routing for the vehicles which minimizes the total distance travelled.

Each column in the matrix of Table 1 represents one possible vehicle route. For example, column one represents a vehicle travelling from the depot to delivery point (1) and returning. The c_j row indicates the

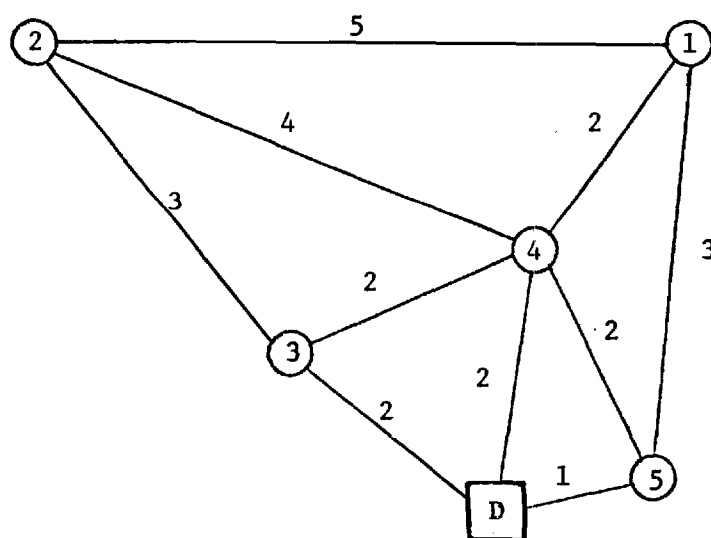


Figure 1. Delivery Example Network

route	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
c_j	8	10	4	4	2	14	10	8	8	10	11	12	6	6	5
	1	0	0	0	0	1	1	1	1	0	0	0	0	0	0
	0	1	0	0	0	1	0	0	0	1	1	1	0	0	0
	0	0	1	0	0	0	1	0	0	1	0	0	1	1	0
	0	0	0	1	0	0	0	1	0	0	1	0	1	0	1
	0	0	0	0	1	0	0	0	1	0	0	1	0	1	1

Table 1. Matrix Corresponding to Routes in the Delivery
Example of Figure 1.

distance travelled for each trip. For example, column six represents a vehicle proceeding from the depot to delivery point (1), on to delivery point (2) and from there, back to the depot. The value of c_6 is 14, the total distance travelled for this trip. By enumerating each of the possibilities, as has been done for this matrix, the problem becomes one of selecting a set of columns such that every row is represented in exactly one column and the sum of the costs of the columns selected is the smallest possible. This integer program is called a "set partitioning model".

The set partitioning model was originally proposed for a similar class of routing problems by Charnes and Miller [3] and for this specific problem by Balinski and Quandt [2]. The model is very powerful in the sense that many realistic route constraints and cost functions can be handled easily in the column enumeration process. The obvious shortcoming of the model is that there are typically a very large number of columns to be enumerated and the resulting integer program is very large. The approach presented here is heuristic in the sense that we generate only a subset of the possible columns or routes and in general we do not solve the set partitioning model to optimality.

The set partitioning model has two very desirable features for interactive optimization. The first is that any route generated can be included as a column in the model. This allows the human interactor to utilize his/her intuition and spatial perception as well as a wide spectrum of mathematical techniques to generate new routes. The second feature is that, unlike more general integer programs, a feasible solution to the set partitioning model provides the basis for pricing

information which can be used to generate new candidate columns.

We will restrict the class of routing problems considered here to be those for which any subroute of a feasible route is also a feasible route with cost less than or equal to the cost of the original route. By imposing this restriction, as long as there is at least one 1 in every row of the partial set partitioning model that we have enumerated, we can easily generate feasible partitions. The only other restriction that we put on the class of routing problems is that we be able to pose them in a natural way as set partitioning problems. However, it should be noted that if there is not a nice spatial representation of the routing problem, the human interactor is much more restricted in his/her contribution.

2. SET PARTITIONING AND ROW PRICES

The set partitioning problem can be stated as

$$\text{minimize} \quad Z = \sum_{j=1}^n c_j x_j \quad (1)$$

$$\text{subject to} \quad \sum_{j=1}^n a_{ij} x_j = 1 \quad \text{for } i = 1, 2, \dots, m \quad (2)$$

$$x_j = 0 \text{ or } 1 \quad \text{for } j = 1, 2, \dots, n. \quad (3)$$

For the delivery example in Table 1, the set partitioning model has the second row as the value of the c_j and rows three through seven as the values of the a_{ij} . The variables which are set to one in a solution to the set partitioning problem will be called a "partition." We will denote a partition as $J^k = \{j | x_j^k = 1\}$. Balas and Padberg [1] provide a recent survey of results related to set partitioning problems.

A fundamental idea underlying much of the work presented here is the concept of "row prices."

Definition: $P^1 = (p_1^1, p_2^1, \dots, p_m^1)$ is a set of feasible row prices corresponding to the partition J^1 if

$$\sum_{i=1}^m p_i^1 a_{ij} = c_j \quad \text{for } j \in J^1. \quad (4)$$

It will be useful to interpret the price p_i^1 as an estimate of the cost to satisfy constraint i using solution X^1 . For the delivery problem,

p_i^1 is then an estimate of the cost of satisfying the requirement of delivery point i using the route corresponding to partition J^1 .

Theorem 1: Given a set of feasible row prices $(p_1^1, p_2^1, \dots, p_m^1)$ corresponding to partition J^1 with value Z^1 , any other partition J^2 has value.

$$Z^2 = Z^1 - \sum_{j \in J^2} \sum_{i=1}^m (p_i^1 a_{ij} - c_j) \quad (5)$$

Proof:

$$\sum_{j \in J^2} \left(\sum_{i=1}^m p_i^1 a_{ij} - c_j \right) = \sum_{i=1}^m p_i^1 \sum_{j \in J^2} a_{ij} - Z^2$$

Since J^2 is a partition, $\sum_{j \in J^2} a_{ij} = 1$ for each $i = 1, 2, \dots, m$. Also, since $(p_1^1, p_2^1, \dots, p_m^1)$ are feasible row prices corresponding to X^1 we have $\sum_{i=1}^m p_i^1 = Z^1$. Hence the result follows.

Corollary 1: For any set of feasible row prices P^1 corresponding to a partition J^1 if

$$\sum_{i=1}^m (p_i^1 a_{ij} - c_j) \leq 0 \quad (6)$$

for $j = 1, 2, \dots, n$ then X^1 is optimum.

It can also be shown, using linear programming duality, that a set of feasible row prices P^1 satisfying Corollary 1 exists if and only if X^1 is an optimum solution with the constraints $x_j = 0$ or 1 replaced by $x_j \geq 0$ for $j = 1, 2, \dots, n$.

The quantity $\sum_{i=1}^m p_i^1 a_{ij} - c_j$ will be interpreted as the "potential" savings over the value of Z^1 which can result from constructing a partition that includes column j . Note from Theorem 1 that the potential savings can actually be achieved only if a partition can be constructed from columns with nonnegative potential savings.

3. POTENTIAL SAVINGS HEURISTIC

Given a partition J^1 and a corresponding set of feasible row prices P^1 , an attractive heuristic for attempting to generate a better partition is the following:

Step (0): Let $J^2 \neq \emptyset$ (J^2 will be the indices of columns in the new partition) and $N = \{1, 2, \dots, n\}$, (N will be the indices of columns which are candidates for inclusion in J^2)

Step (1): Calculate the potential savings $\sum_{i=1}^m p_i^1 a_{ij} - c_j$ for $j = 1, 2, \dots, n$.

Step (2): Pick the column k in N with the largest potential savings, $\sum_{i=1}^m p_i^1 a_{ik} - c_k$

Step (3): For $i = 1, 2, \dots, n$, if $a_{ik} = 1$ set $a_{ij} = 0$ for all $j \neq k$.
(Note from the assumption of section 1 that any subroute of a feasible route is also a feasible route, the new columns are legitimate)

Step (4): Let $J^2 = J^2 \cup \{k\}$ (i.e., put column k in the new partition) and $N = N - \{k\}$

Step (5): Delete from N all j for which $a_{ij} = 0$ for all $i = 1, 2, \dots, m$.

Step (6): If $N = \emptyset$ stop. Otherwise go to step (2).

Note that under the assumption that any subset of a route is also a feasible route (discussed in section 1) this procedure will always terminated with J^2 as a partition although not necessarily a better partition than J^1 . If convenient, c_j should be recomputed whenever step (3) affects a change in column j , as the actual route may change. Computation to date indicates that an optimum or near

optimum solution to the set partitioning problem is determined very quickly by repeated application of the potential savings heuristic (note that the a_{ij} should be reset to their original values after each repetition). The heuristic is repeated until either optimality is proven (i.e., for some X^k all $\sum_{i=1}^m p_i^k a_{ij} - c_j \leq 0$) or until some specified number of partitions has been generated.

To illustrate the potential savings heuristic, consider again the delivery example depicted in Figure 1 and Table 1. Suppose that we select $J^1 = \{1, 2, \dots, 5\}$ as an initial partition. A set of feasible row prices P^1 is given in Table 2. (The question of how to generate "good" feasible row prices will be addressed in the next section.) The corresponding potential savings $\sum_{i=1}^m p_i^1 a_{ij} - c_j$ are also given in Table 2. Applying the potential savings heuristic and breaking ties by selecting the column with the lowest index yields the new partition $J^2 = \{6, 13, 5\}$. The new partition has a cost of $Z^2 = 22$ as compared to a cost $Z^1 = 28$ for the initial solution.

Using the row prices P^2 and potential savings $\sum_{i=1}^m p_i^2 a_{ij} - c_j$ of Table 2 and reapplying the potential savings heuristic yields the partition $J^3 = \{8, 10, 5\}$ which has a cost of $Z^3 = 20$. Again, from Table 2 we find that using the row prices P^3 gives potential savings $\sum_{i=1}^m p_i^3 a_{ij} - c_j \leq 0$ for $j = 1, 2, \dots, n$. Hence, from Corollary 1 the partition J^3 is optimum.

j	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15			
c_j	8	10	4	4	2	14	10	8	8	10	11	12	6	6	5	P^1	P^2	P^3
	1					1	1	1	1							8.0	6.2	5.3
		1				1				1	1	1				10.0	7.8	7.1
			1				1			1			1	1		4.0	3.0	2.9
				1				1			1		1		1	4.0	3.0	2.7
					1				1			1		1	1	2.0	2.0	2.0
$p_{ij}^1 - c_j$	0	0	0	0	0	4	2	4	2	4	3	0	2	0	1	$x_6 = 1$		
	-	-	0	0	0	-	-6	-4	-6	-6	-7	-10	2	0	1	$x_{13} = 1$		
	-	-	-	-	0	-	-	-	-6	-	-	-10	-	-4	-3	$x_5 = 1$		
$p_{ij}^2 - c_j$	-1.8	-2.2	-1	-1	0	0	-0.8	1.2	.2	.8	-0.2	-2.2	0	-1	0	$x_8 = 1$		
	-	-2.2	-1	-	0	-6.2	-7	-	-6	.8	-3.2	-2.2	-3	-1	-3	$x_{10} = 1$		
	-	-	-	-	0	-	-	-	-6	-	-	-10	-	-4	-3	$x_5 = 1$		
$p_{ij}^3 - c_j$	-2.7	-2.9	-1.1	-1.3	0	-1.6	-1.8	0	-0.7	0	-1.2	-2.9	-0.4	-1.1	-0.3			

Table 2. An Example Illustrating the Potential Saving Heuristic
with $J^1 = \{1, 2, 3, 4, 5\}$, $J^2 = \{6, 13, 5\}$, and $J^3 = \{8, 10, 5\}$

4. ROW PRICING

For a given partition X^k a set of feasible row prices is obtained by allocating the column cost c_j for each $j \in J^k$ among the rows having $a_{ij} = 1$. For the delivery example, this corresponds to allocating the trip cost among the delivery points of the trip. When a column $j \in J^k$ contains only one $a_{ij} = 1$, the row price is $p_i^k = c_j$. However, when a column j contains more than one $a_{ij} = 1$, there are an infinite number of possible sets of prices. As an example consider the partition $J^3 = \{8, 10, 5\}$ for the problem in Table 2. Since column 5 has only $a_{5,5} = 1$ the value $p_5^3 = 2$ is unique. Column 8 has both $a_{1,8} = 1$ and $a_{4,8} = 1$, hence the cost $c_8 = 8$ could be allocated between rows 1 and 4 in an infinite number of ways. Similarly, column 10 has both $a_{2,10} = 1$ and $a_{3,10} = 1$, hence $c_{10} = 10$ could be allocated between rows 2 and 3 in an infinite number of ways. If we allocate c_8 as $p_1^3 = 4$ and $p_4^3 = 4$ and allocate c_{10} as $p_2^3 = 5$ and $p_3^3 = 5$, the resulting $\sum_{i=1}^m p_i^3 a_{ij} - c_j$ do not indicate that J^3 is an optimum partition. Hence the set of prices P^3 given in Table 2 are clearly better since they do indicate that J^3 is an optimum partition.

Ideally, we would like a set of prices which would drive the potential savings heuristic toward an improving solution and would indicate optimality when no improving solution is possible (i.e., We would like the prices to be analogous to dual variables in linear programming). Unfortunately, it is easy to construct cases for which no such prices exist (i.e., any problem for which the integer and continuous solution differ). For the delivery problem and the more

complex dial-a-ride problem (to be discussed later), allocating column cost in proportion to the cost of serving the delivery points one-at-a-time is intuitively appealing and seems to work very well. As an illustration consider again the partition J^3 in Table 2. Column 8 has $a_{1,8} = 1$ and $a_{4,8} = 1$. The cost of serving delivery point 1 if it is the only point in a trip is $c_1 = 1$. The cost of serving delivery point 4 if it is the only point in a trip is $c_4 = 4$. The prices for rows 1 and 4 were determined as $p_1^3 = \frac{c_1 c_8}{c_1 + c_4} = 5.3$ and $p_4^3 = \frac{c_4 c_8}{c_1 + c_4} = 2.7$. The other prices in Table 2 were determined similarly.

When there are substantial differences in the amounts of vehicle capacity required by the delivery points, it seems reasonable to allocate column cost in proportion to the "weighted" cost of serving points one-at-a-time. Here the weights are the delivery sizes. For example if w_i is the vehicle capacity required by delivery point i , we specify the price of row 1 with respect to J^3 above as $P_1 = \frac{c_1 w_1 c_8}{c_1 w_1 + c_4 w_4}$. These and other pricing alternatives are currently being tested for delivery problems under various types of constraints.

There are a variety of other mechanisms for allocating the prices to the demand points. Some allocation procedures may work well in some situations while others may be suited to other problems. The human (or automatic algorithm) may wish to employ different pricing procedures as the algorithm progresses.

5. COLUMN GENERATION

For large scheduling and routing problems it is generally not practical to generate all columns of the corresponding set partitioning model. The remainder of this paper will be concerned with using information gleaned from one solution via Theorem 1 to generate a new and hopefully better solution. This is accomplished by either generating new columns, adding them to the current set partitioning model, and then resolving the model or by using the information from Theorem 1 directly to generate a new solution. In the latter case it is not necessary to retain the columns of the set partitioning model. However, if the columns are retained, it is possible to further improve the solution by periodically solving the set partitioning model.

We should note that for the class of scheduling and routing problems being considered here, it is very easy to generate an initial solution. For our examples we use the identity solution (e.g., in the delivery problem this is the solution which has each vehicle making a single delivery) as our initial solution. However, any feasible solution could be used as the initial solution.

Clearly there is a broad spectrum of possible approaches that one might use to generate new columns and/or new solutions to the set partitioning model. In fact, variations of many of the heuristics which have been applied to delivery problems can be used very effectively in conjunction with Theorem 1. In the next section we will discuss the use of the Clarke and Wright [3] savings procedure in conjunction with the delivery problem. In later sections we will discuss more complex clustering and chaining heuristics as we have applied them to the dial-a-ride problem.

6. CLARKE AND WRIGHT PROCEDURE WITH PRICING

The "savings" heuristic of Clarke and Wright [3] is the most widely known of the heuristics developed to date for delivery problems. The algorithm proceeds by calculating a savings for each pair of delivery points i and j defined as

$$s_0(i,j) = 2d_{0i} + 2d_{j0} - (d_{0i} + d_{ij} + d_{j0}) = d_{0i} + d_{j0} - d_{ij}$$

which is the savings in mileage of supplying delivery points i and j on the same route as opposed to supplying them individually directly from the depot (d_{0i} is the distance from the depot to delivery point i). Routes are then constructed either one-at-a-time or in parallel by considering pairs of points in order of decreasing savings and including them in the same route if such a route is feasible.

Suppose that we consider once more the delivery example in Figure 1 and the covering solution information in Table 2. Note that the Clarke and Wright savings values are exactly the values of $\sum_{i=1}^m p_i^1 a_{ij} - c_j$ in Table 2 since $d_{0i} = p_i^1/2$ for $i = 1, 2, \dots, m$. Applying the C-W savings algorithm yields the same routing configuration as $J^2 = \{6, 13, 5\}$. At this point, the C-W algorithm would terminate. However, suppose that we set $d_{0i} = p_i^2/2$ for $i = 1, 2, \dots, m$. The new savings are then exactly the $\sum_{i=1}^m p_i^2 a_{ij} - c_j$ in Table 2. Applying C-W algorithm yields the same routing configuration as $J^3 = \{8, 10, 5\}$ which as noted previously is the optimum solution to this delivery example. Hence, for this example at least the C-W algorithm without pricing did not yield an optimum solution while the same algorithm when combined with pricing did yield the optimum solution.

Note that when routes are allowed to contain more than two trips, only a small subset of the set partitioning columns would be generated using this procedure. Also, note that the prices and savings can be calculated without ever generating the set partitioning matrix.

When the number of points allowed in a route exceeds two, some interesting questions arise as to exactly how the algorithm should be implemented. As an illustration, suppose that in the example we allow a vehicle to deliver to at most three points rather than two. Now suppose that we start with the solution J^3 in Table 2. We see that the two-at-a-time potential savings are all non-positive. However, if we ignore this fact and proceed with the algorithm, we would put points 1 and 4 in the same route since their potential savings of zero is maximum. If we then consider adding a third point to this route, we find that adding point 5 has a potential savings of 2 which is maximum. Finally, we combine points 2 and 3 into a single route since this has a potential savings of zero. The resulting routes (4,1,5) and (2,3) has a length of 10. Therefore, in this case at least we can get better information by recalculating the potential savings after each augmentation of a route. This recalculation is not done in most implementations of the C-W algorithm.

Clearly, when constructing a route containing more than two points one must decide where in the route to put each additional point. The potential savings can be determined exactly only by solving a travelling salesmen problem over each new point which is a candidate to be added to the route. This is computationally expensive if a route can contain a large number of points. In most implementations of the C-W algorithm, new points are simply added on to the end of the route being constructed. When the

algorithm is implemented interactively using computer graphics, it appears that the human can perform an important role both in selecting candidate points and in inserting them logically into routes.

7. LOCATION - ALLOCATION WITH PRICING

Another procedure which Krolak and Nelson [5] have found effective in approaching the delivery problem utilizes the location - allocation model of Cooper [4]. This basic concept can also be used in conjunction with Theorem 1 to generate intuitively appealing columns to add to the set partitioning model.

To illustrate the procedure consider the delivery example illustrated in Figure 2. Again the circles represent delivery points and the square represents the depot. The basic idea is to use a surrogate distance rather than the actual distance in determining the points which are assigned to each vehicle. The surrogate distance is obtained by assuming that the vehicle travels from the depot to a specified cluster point, represented in Figure 2 by the dashed circles. It then makes the deliveries, returning after each delivery to the cluster point. After all deliveries have been made, the vehicle returns to the depot. Under this surrogate distance, the problem becomes one of locating the cluster points, one for each vehicle, and then assigning the delivery points to each vehicle.

If (a_0, b_0) represents the coordinates of the depot, (a_i, b_i) represents the coordinates of delivery point i , (x_j, y_j) represents the coordinates of cluster point j , and assuming Euclidean distance, the problem can be modeled as follows:

$$\min_{x,y,z} \sum_{i=0}^m \sum_{j=1}^n [2[(x_j - a_i)^2 + (y_j - b_i)^2]^{\frac{1}{2}} z_{ij}]$$

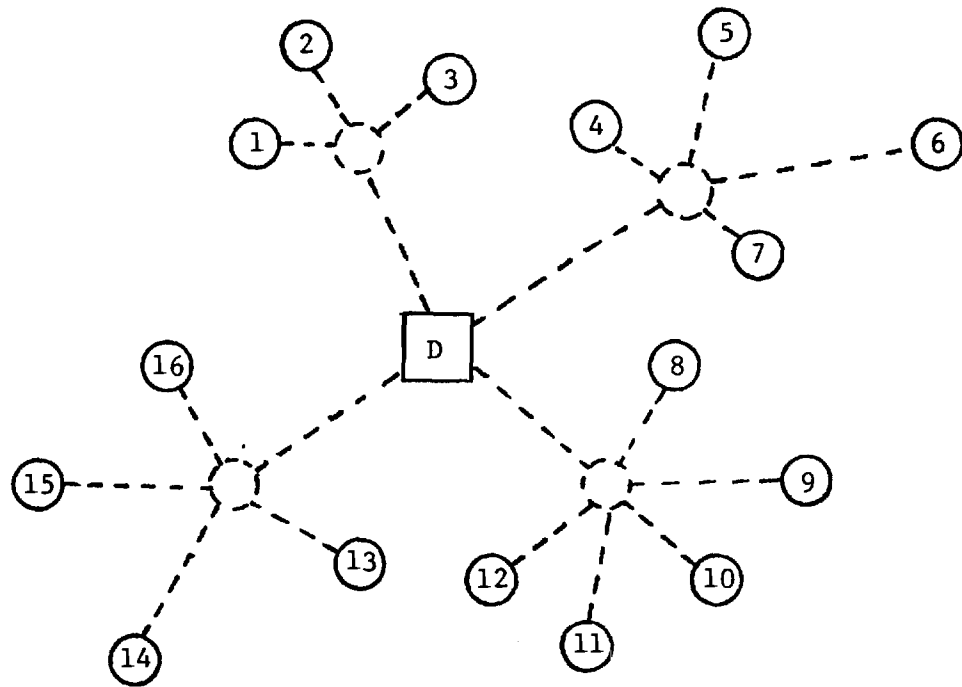


Figure 2. Delivery Example to Illustrate the Location - Allocation Model for Clustering.

$$\begin{aligned}
\text{s.t.} \quad & \sum_{i=1}^m z_{ij} \leq K & j = 1, 2, \dots, n \\
& \sum_{j=1}^n z_{ij} = 1 & i = 1, 2, \dots, m \\
& z_{ij} = 0 \text{ or } 1 & \text{all } i, j \\
& z_{0j} = 1 & j = 1, 2, \dots, n
\end{aligned}$$

where n is the number of vehicles and K is the vehicle capacity. When $z_{ij} = 1$, delivery point i is assigned to vehicle j and when $z_{ij} = 0$, delivery point i is not assigned to vehicle j .

While there is no method for efficiently solving this problem optimally, the following is an attractive heuristic. Pick a set of locations for the cluster points. With these coordinates fixed, solve the resulting assignment problem. With these values of z_{ij} fixed, solve the resulting location problem. Continue alternating between the assignment and location problems for some specified number of iterations or until there is no further improvement in the objective. Once a cluster has been determined, the vehicle is then routed among the points of the cluster.

A slight modification of this model, together with Theorem 1, allows us to generate attractive new columns for the set partitioning problem. Suppose that we have a solution to the set partitioning problem and a set of row prices p_1, p_2, \dots, p_m . Now consider the model

$$\min_{x,y,z} \sum_{i=0}^m \sum_{j=1}^n 2[(x_j - a_i)^2 + (y_j - b_i)^2]^{\frac{1}{2}} z_{ij} - \sum_{i=1}^m \sum_{j=1}^n p_i z_{ij}$$

$$\text{s.t.} \quad \sum_{i=1}^m z_{ij} \leq K \quad j = 1, 2, \dots, n$$

$$\sum_{j=1}^n z_{ij} \leq 1 \quad i = 1, 2, \dots, m$$

$$z_{ij} = 0 \text{ or } 1 \quad \text{all } i, j$$

$$z_{0j} = 1 \quad j = 1, 2, \dots, n$$

Any cluster generated by this model will have a positive potential savings, with respect to the surrogate distance. Hence, it corresponds to an attractive column to add to the set partitioning problem (considering surrogate distances).

Since the second constraint has been changed to an inequality, not all delivery points will be assigned to cluster points. This simply means that the current row price for the delivery point is more attractive than the cost of serving the delivery point in alternative clusters considered by the model. The model can be solved using the same heuristic discussed for the earlier location - allocation model.

8. DIAL-A-RIDE PROBLEM

The dial-a-ride problem is a much more complex routing problem than the delivery problem. In the dial-a-ride problem we are given an origin-destination trip matrix and an underlying network on which the trips are to be made. There is a single item (people, goods, etc.) (demand for service) at each origin that needs to be transported to its specified destination. The items are transported from origins to destinations on vehicles each having capacity K . We wish to satisfy the trip requirements while travelling the minimum distance.

This is a "static" version of the dial-a-ride problem since time is not considered. There are a number of more complex versions of this problem, but this version is sufficient to demonstrate the basic ideas of our approach.

The set partitioning model for the dial-a-ride problem is analogous to that of the delivery problem, but here rows represent trips rather than simple delivery points. The vehicle capacity constraints are handled by generating only routes which satisfy them.

9. DECOMPOSITION

In delivery problems, representative of the "one-ended" class of routing and scheduling problems, we need only be concerned with a single stop for a vehicle to satisfy a particular demand for service. In contrast, the "two-ended" class, which includes dial-a-ride problems, requires two stops in a specific order (sequence) to satisfy a specific demand for service. It is this requirement for sequencing of "pickup" and "dropoff" point pairs which adds greatly to the difficulty of handling the two-ended class of vehicle routing problems.

When one considers examples of two-ended problems, it becomes immediately apparent that the sequencing requirements greatly inhibit the complex pattern processing abilities of the human. Figure 3 illustrates an example of a 25 trip dial-a-ride problem. Rather than displaying order and structure, the problem resembles so much spaghetti. It is clear that for such problems the human interactor needs more help in generating good columns for the set partitioning model.

Unfortunately, it is also more difficult to apply straight forward methods such as the savings approach discussed earlier for the delivery example. In generating a dial-a-ride route one must be concerned with where both the origin and the destination occur in the sequence in order to calculate the potential savings. In addition, the capacity constraint may negate what otherwise appears to be good positions for the origin and destination in the sequence.

Because of this complexity, it is helpful to "decompose" the problem into two levels which we call "clustering" and "chaining". In essence, we consider a route to be made up of two components. Clusters

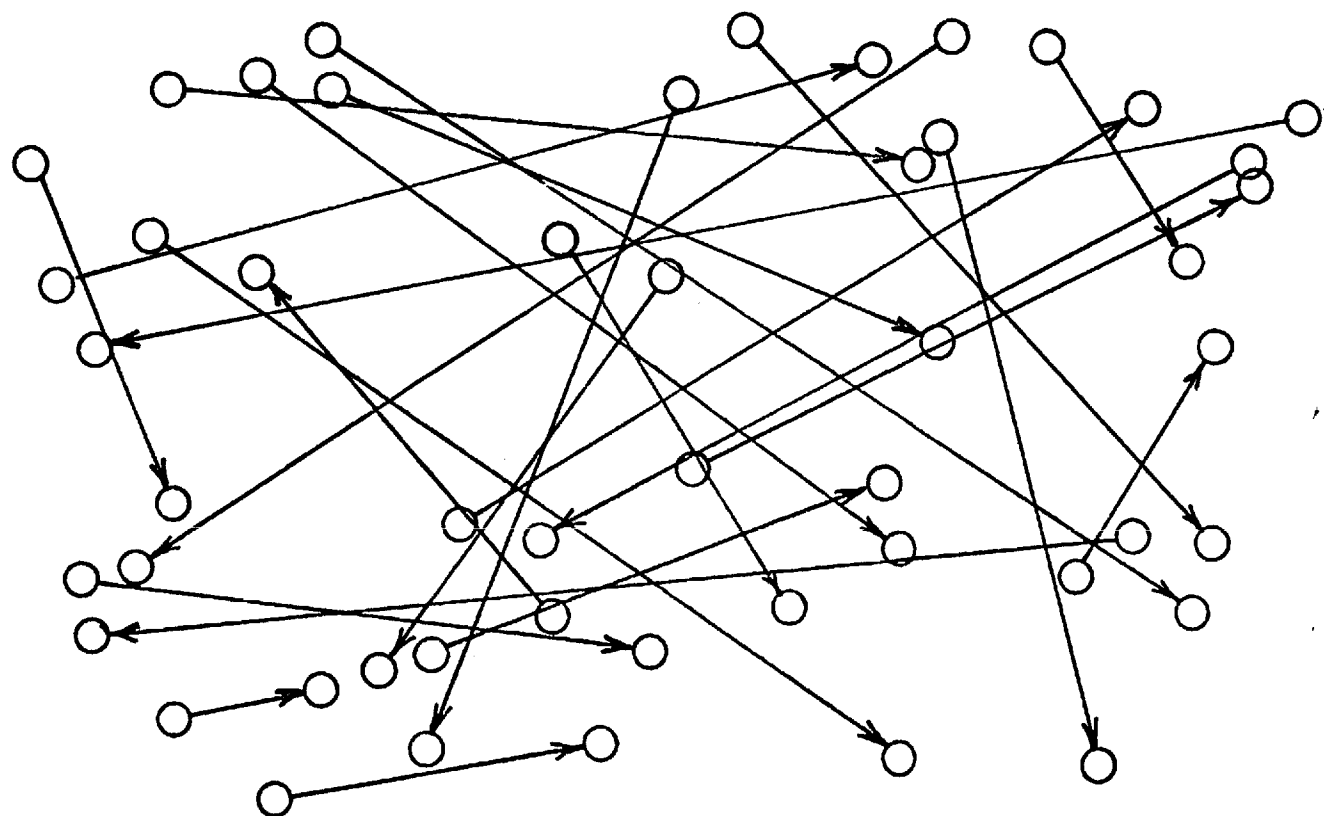


Figure 3. An Example of a 25 Trip Dial-a-Ride Problem

correspond to trips which can all be on a vehicle at one time, while chains correspond to movement from the end of one cluster to the beginning of the next. Figure 4 provides an example of five good clusters, while Figure 5 illustrates one way in which these five clusters might be linked into two chains.

The partitioning model and pricing concepts can be effectively exploited to aid in generating improving clusters and chains in a column generation approach to solving two-ended vehicle routing problems. One partitioning model can be utilized in generating improving clusters while another partitioning model helps identify better chains.

In the partitioning model for clustering, the columns represent clusters and the rows represent the individual trips (demand for service). We shall demonstrate, in the next section, just how the pricing information from the partitioning problem can be used to generate additional clusters.

In the partitioning model for chaining, the columns represent chains and the rows represent the individual trips. The function of the chaining partitioning model is to combine the clusters into good vehicle routes.

The overall solution procedure consists of linking the clustering models and chaining models together in an interactive manner. The clustering models, partitioning matrix and pricing information are used to generate good clusters. These clusters are then passed to the chaining phase where they are linked together via the chaining models, partitioning matrix and associated pricing information. After chaining, it is possible to return to the clustering phase to identify additional clusters.

The next two sections discuss the specifics of clustering and chaining

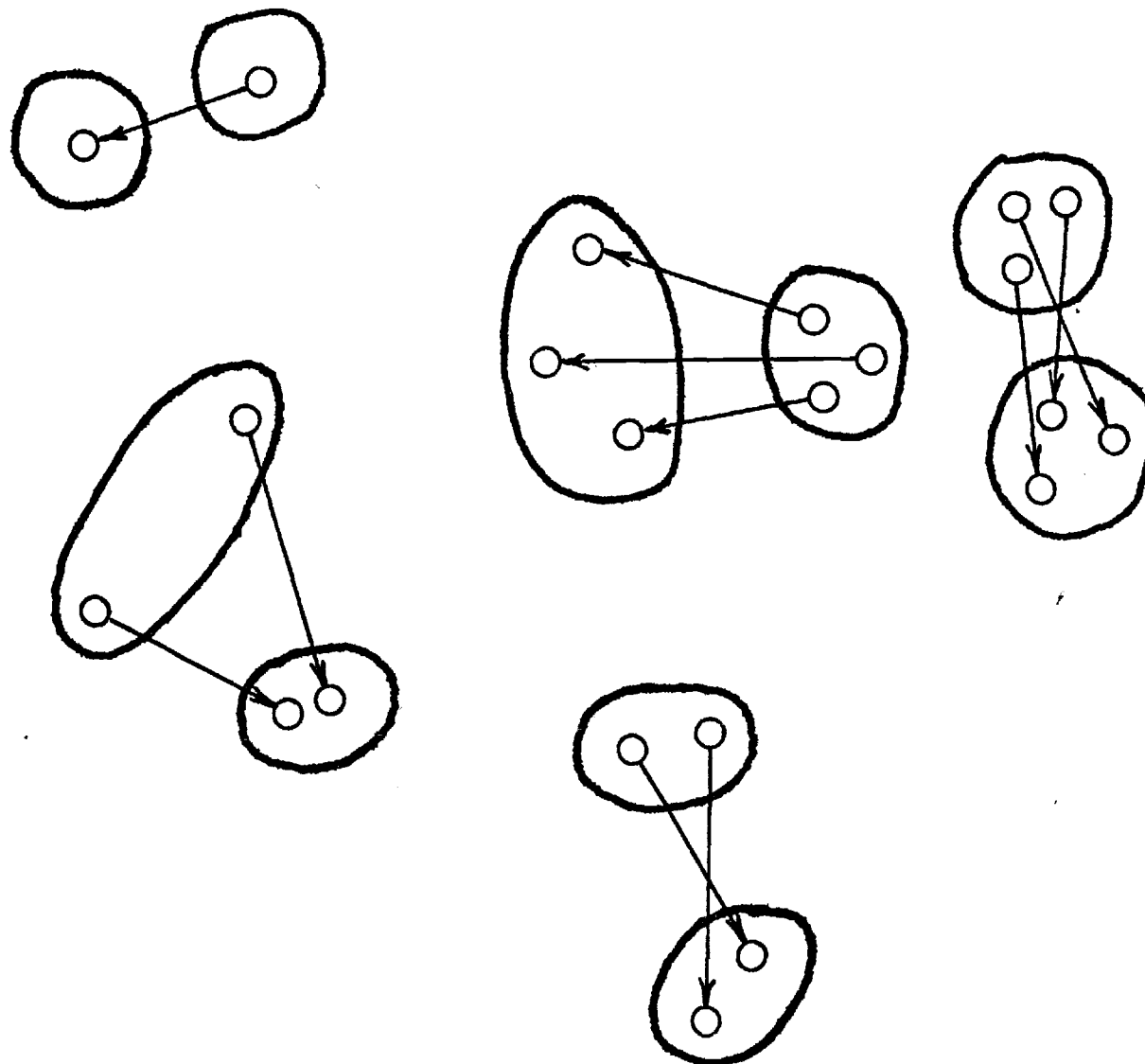


Figure 4. Example of Five Clusters

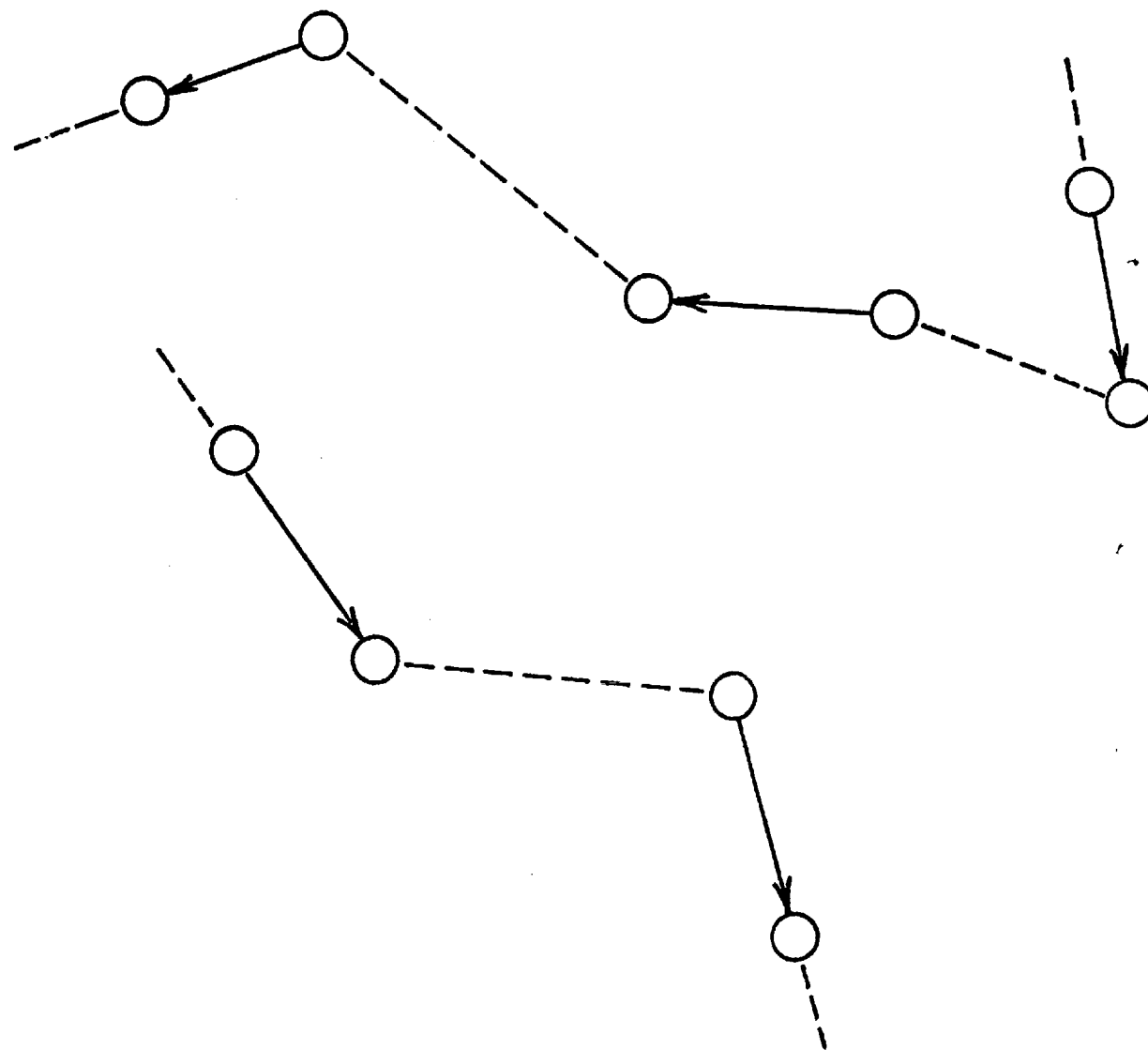


Figure 5. Example of Two Chains Linking the Five Clusters of Figure 4

10. CLUSTERING

In the previous section we introduced the clustering concept. In this section we shall provide more details of the concept as well as the structure and operation of various clustering models. Figure 6 depicts a typical cluster (in this case, three trips).

Clustering makes sense if the origins are reasonably close together and the destinations are also close together. One way to develop an evaluation of such circumstance is to locate the centroid of the origins, the centroid of the destinations and accumulate the resulting distances from the original trips. In Figure 6 we could evaluate the distances represented by $(a+b+c) + (d+e+f)$. If this sum is small then it would make sense to cluster the trips.

By utilizing surrogate distances we lose the actual route distance evaluation; however, we gain the ability to evaluate large numbers of cluster possibilities conveniently and simultaneously. In Figure 6 we might employ Euclidean distances. In this case we could compare the sum of the row prices, $p_1 + p_2 + p_2$, generated in the covering model for clustering to the quantity $2(a+b+c) + 2(d+e+f) + g$ to determine whether clustering is appropriate. We can think of the latter quantity as a surrogate for the vehicle routing distance.

We can develop a straight forward extension of the Location - Allocation model discussed in Section 7 to identify good clusters for the dial-a-ride problem. In place of the quantity

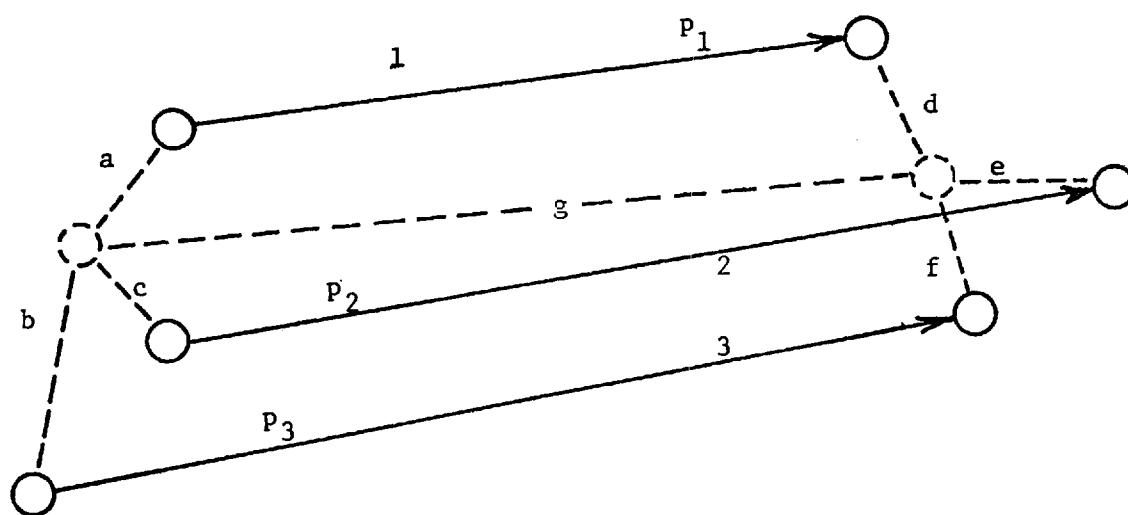


Figure 6. Surrogate Distances for a Typical Cluster

$$\sum_i \sum_j 2[(x_j - a_i)^2 + (y_j - b_i)^2]^{\frac{1}{2}} z_{ij}$$

we employ a quantity

$$\begin{aligned} & \sum_i \sum_j 2[(\bar{x}_j - \bar{a}_i)^2 + (\bar{y}_j - \bar{b}_i)^2] z_{ij} \\ & + \sum_i \sum_j 2[(\hat{x}_j - \hat{a}_i)^2 + (\hat{y}_j - \hat{b}_i)^2]^{\frac{1}{2}} z_{ij} \\ & + \sum_j [(\bar{x}_j - \hat{x}_j)^2 + (\bar{y}_j - \hat{y}_j)^2]^{\frac{1}{2}} \end{aligned}$$

where \bar{x}_j , \bar{y}_j , \bar{a}_i and \bar{b}_i correspond to origins and \hat{x}_j , \hat{y}_j , and \hat{a}_i , \hat{b}_i correspond to destinations of clusters and trips.

We can also develop a savings approach to clustering in a similar manner to that described earlier for the delivery problem. As in the delivery problem, the clusters generated by the Location - Allocation models by the savings approaches or by the human interaction can be achieved in a set partitioning model. This model can then be solved to determine a "best" set of clusters.

11. CHAINING

Upon termination of the clustering process, a number of reasonably good clusters are available. This set includes not only the "best" cluster sets as selected by the covering model for clustering, but also a number of other clusters which might be nearly as good, but which were not selected in the optimal solution to the covering model. The pricing mechanism can again be utilized to select these additional "good" clusters. Figure 7 illustrates a set of clusters which might result from the clustering process. The clusters in the figure represent only the optimal solution to the clustering process. In addition, we might have other clusters available, e.g., a cluster containing only trips 1 and 2.

The clusters obtained represent good possibilities for segments (legs) of a vehicle route. The next step in the process is to link ("chain") these clusters into complete vehicles routes. Figure 8 illustrates the chaining concept. Trips 1 and 2 form one cluster, while trips 3, 4 and 5 form another cluster (see Figure 8a). In Figure 8b, trips 1 and 2 are replaced by a single pseudo (cluster) trip, as is also the case for trips 3, 4 and 5. These cluster trips are then chained together.

The interpretation of chaining is that a single vehicle will service the first set of trips (in Figure 8b these would be trips 1 and 2) and then proceed to service the next set of trips (i.e., trips 3, 4 and 5) in the chain. Figure 9 illustrates the likely vehicle route to service the two clusters.

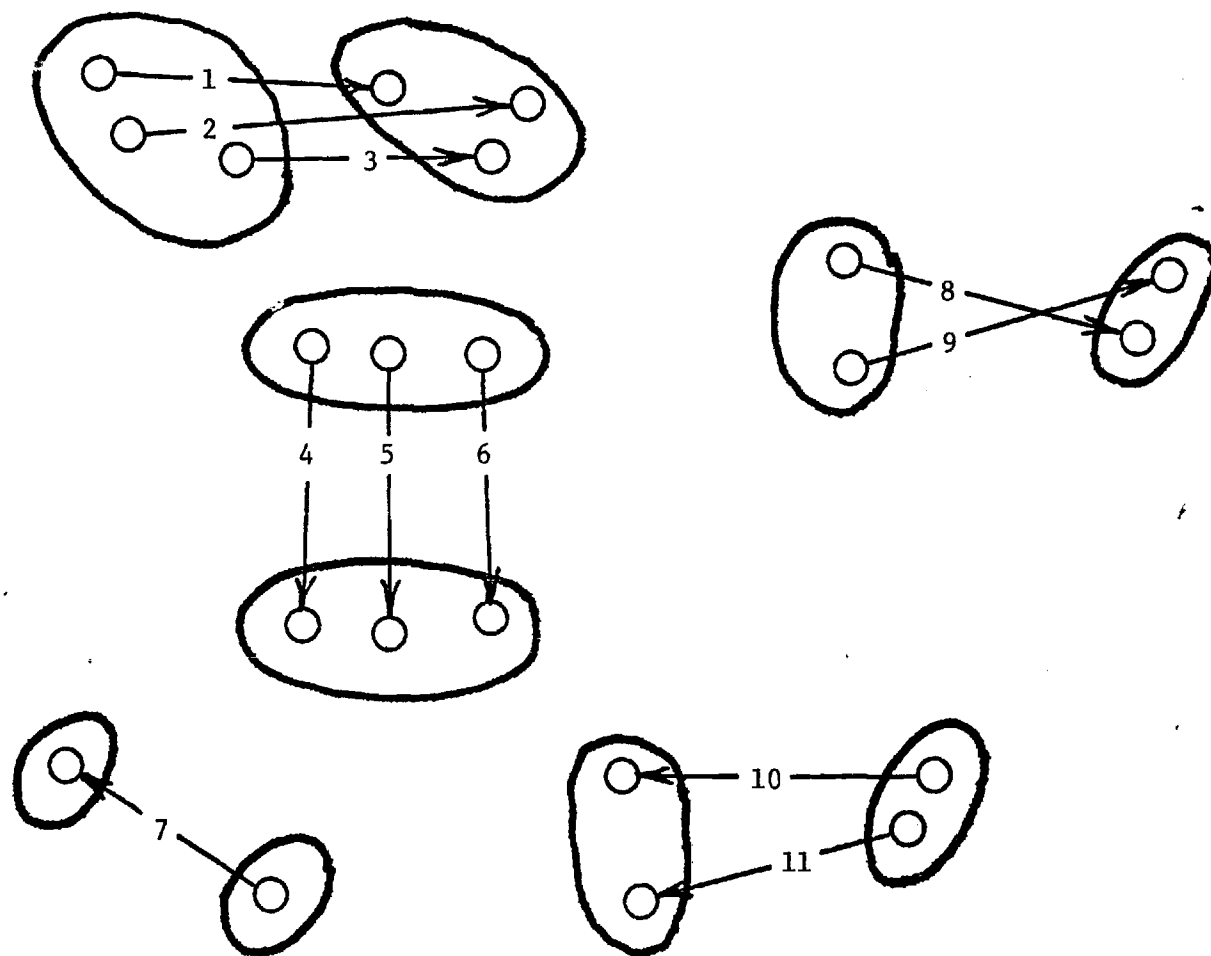
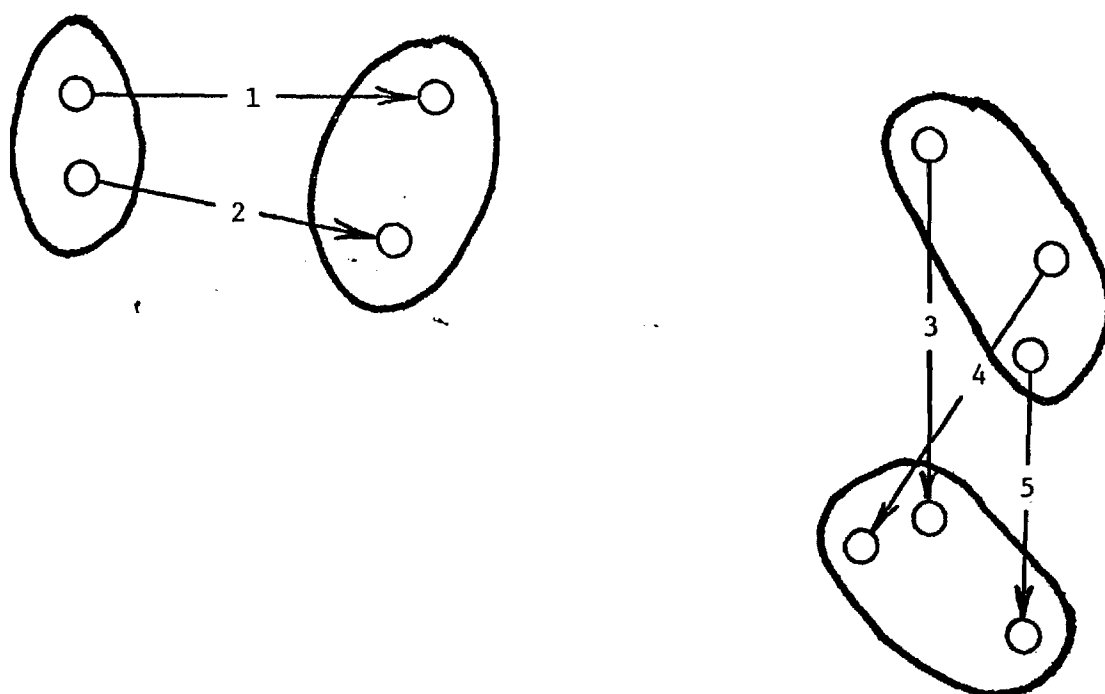
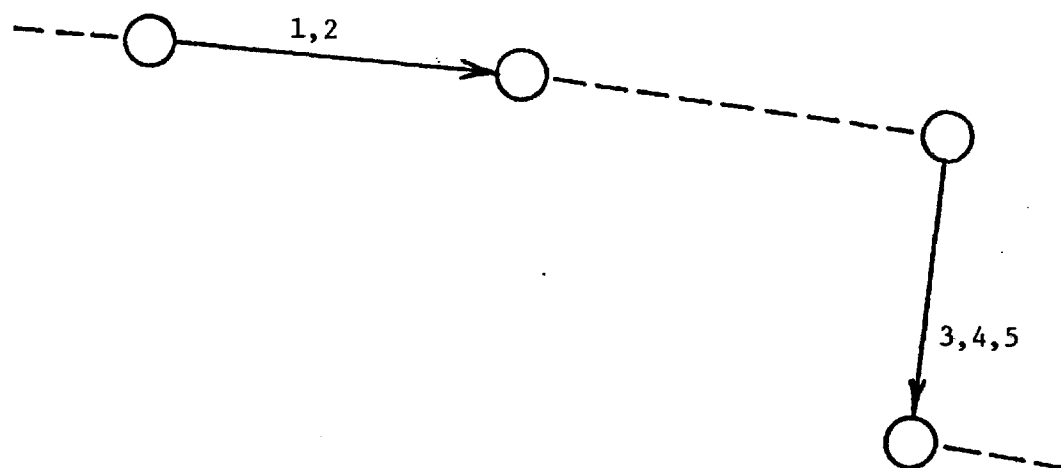


Figure 7. Example of Clusters Resulting from the Clustering Process



a. Two Typical Clusters



b. The Associated Cluster Arcs Chained Together

Figure 8. An Example of Chaining Clusters Together

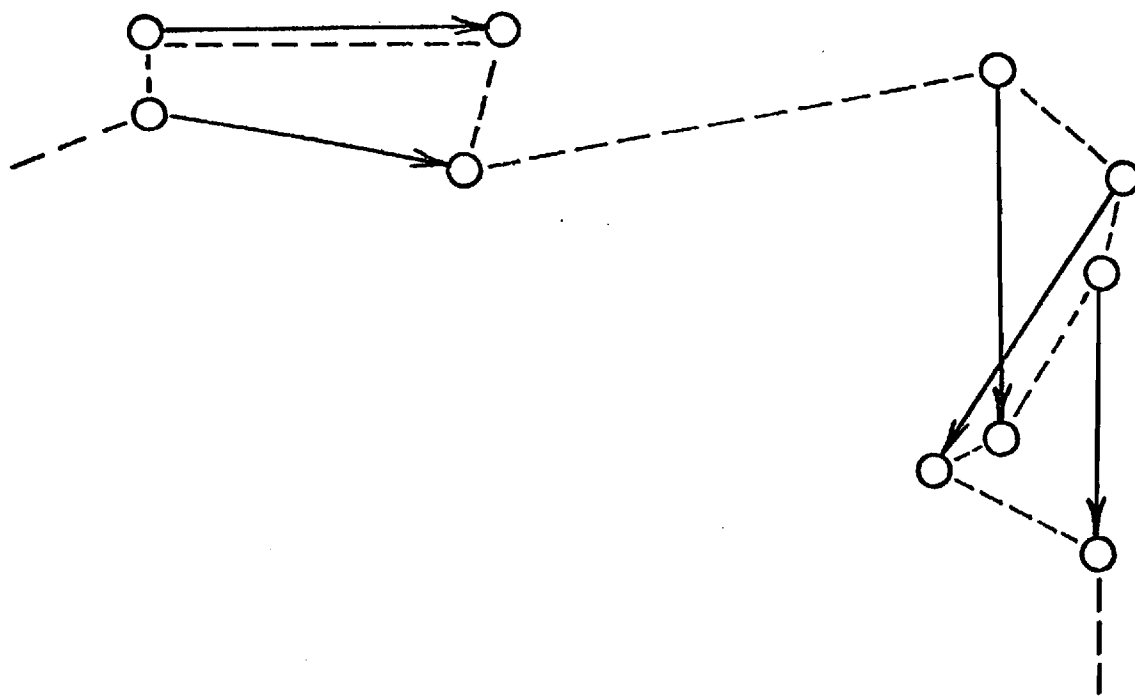


Figure 9. Probable Vehicle Route
for the Chain of Figure 8b

In the partitioning model for chaining, we associate a column of the partitioning matrix with each feasible chain (vehicle route) and a row for each trip. Column j contains 1 in row i if trip i is serviced by chain (vehicle route) j . Otherwise, it contains a 0 (zero). The zero-one variable associated with the columns provide indications of which chains were selected in the optimal partitioning solution. Table 3 illustrates a partitioning matrix for several chains in Figure 7.

The column generation process for the chaining problem is similiar to that for the delivery problem in section 5. However, there are two differences which must be addressed. The first is that in the delivery problem we were routing through "points" while in chaining, we are routing through "lines" (one for each cluster). This requires only minor changes in the savings approach; however, the Location - Allocation is no longer appropriate. The second difficulty occurs because we do not want two clusters in the same chain if they have a trip in common. This is easily avoided in the same manner as we avoid exceeding vehicle capacity in the delivery problem.

	clusters 1 & 2	clusters 1 & 4	clusters 2 & 5	clusters 1, 2 & 5	clusters 3, 4 & 5	clusters 1, 2 & 4	clusters 1, 2, 3 & 5
	1	2	3	4	5	6	7
1	1	1		1		1	1
2	1	1		1		1	1
3	1	1		1		1	1
4	1		1	1		1	1
5	1		1	1		1	1
6	1		1	1		1	1
7					1		1
8		1			1	1	
9		1			1	1	
10			1	1	1		1
11			1	1	1		1

Table 3. An Example Partitioning Model
for Certain Chains in Figure 7

12. DIAL-A-RIDE SOLUTION PROCEDURE

We may put all of the foregoing ideas together into an algorithm for the dial-a-ride problem. Figure 10 provides a flowchart for the algorithm. All of the operations ① thru ⑦, in Figure 10 have been previously discussed except operation ④.

The chaining procedure forms clusters into good vehicle routes. In order to increase the flexibility of the chaining procedure we must provide it with a number of clusters to work with. Thus, in addition to passing the optimal set of clusters to the chaining procedure we should also pass a number of other good clusters. For example, we might pass clusters which priced out near optimal in the partitioning problem for clustering. This is what is suggested in operation ④.

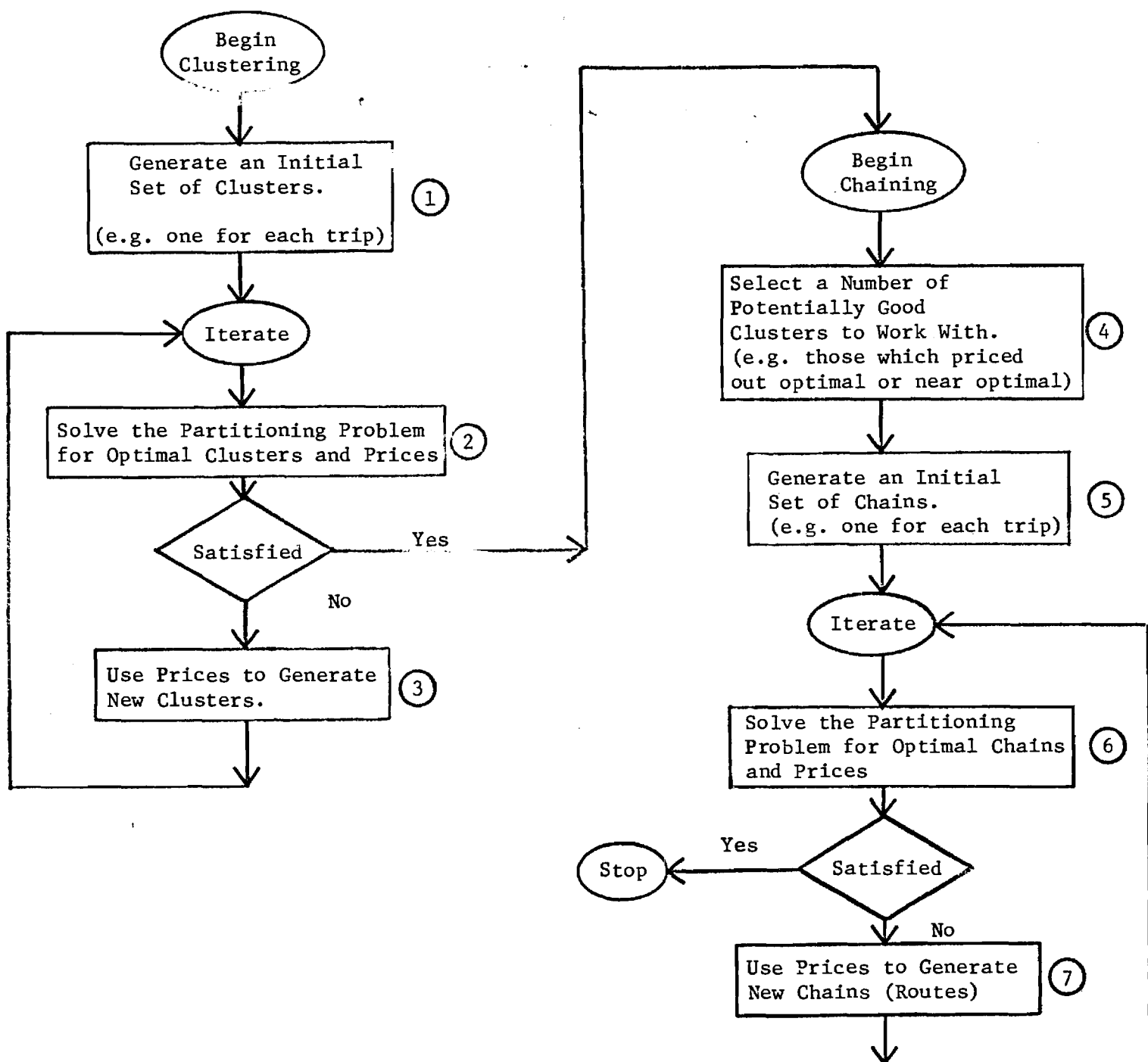


Figure 10. Flowchart of the Dial-A-Ride Solution Procedure

13. PRELIMINARY COMPUTATIONAL RESULTS

The delivery algorithm described in this paper has not yet been fully implemented. However, for evaluation purposes a version was tested which employed prices to aid the human in locating improving delivery solutions, but did not include a partitioning problem to locate a best set from the candidate routes generated. The version was tested on the 50-point, 75-point and 100-point problems of Eilon, Watson-Gandy and Christofides [6]. All of these problems (1) employ a single depot, (2) are Euclidean, and (3) have a limited vehicle capacity.

The current best known solution values for each of the three problems selected are given in Russell [8]. They are 524, 854, and 833 respectively. For each problem, one of the authors employed the interactive procedure until no improvement could be made. In every case, the best known solution value was equalled or exceeded. Table 4 presents the results of the three tests. In some cases an iteration consisted of the complete regeneration of new routes, whereas, in other cases it consisted of the exchange of demand points on a few routes.

It is very encouraging that the proposed procedure was able to generate a better solution to the 100-point problem than the current best known solution.

METHOD PROBLEM	RUSSELL	PROPOSED	
		COST	ITERATIONS
50 POINT	524	524	5
75 POINT	854	854	4
100 POINT	833	827	11

Table 4. Results of the Proposed Method
Compared With Current Best Known Solutions

14. CONCLUSIONS

An interactive delivery system and dial-a-ride system based on the concepts presented here have been implemented on a Chromatics colorgraphics terminal interfaced with a CYBER 74 mainframe computer. Preliminary tests indicate that the interactive procedure is able to compete with state-of-the-art automatic procedures for delivery problems without a great degree of human effort. Although the systems are in many ways very rudimentary, they dramatically indicate the potential for this kind of human aided optimization.

The interactive procedures should derive their greatest benefits in more complex problems containing unusual side constraints (e.g. multiple depots, time, etc.) which the human is able to perceive and control. We are in the process of making extensive modifications in the software and are testing a variety of new models and heuristics to aid in clustering and in route generation.

ACKNOWLEDGMENT

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David J. Friedman and Robert T. Lewis contributed significantly to the implementation of the interactive dial-a-ride system. The extension of the location - allocation model to the dial-a-ride problem is due to Robert T. Lewis.

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APPENDIX A-2

TECHNICAL REPORT:

CLUSTERING IN THE
DIAL-A-RIDE VEHICLE ROUTING PROBLEM

CLUSTERING IN THE
DIAL-A-RIDE VEHICLE ROUTING PROBLEM

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August 1980

ABSTRACT

Two models of clustering are developed for the dial-a-ride problem. End Point Clustering attempts to assign the trips to cluster points located in the two dimensional space of trips. Linear Clustering assigns the trips to lines in the trip space.

Each cluster method is fully developed methodologically and an algorithm is also presented for implementation of the techniques. Test examples as well as Rochester dial-a-ride data offer encouraging evidence of the usefulness of the cluster methods.

1. INTRODUCTION

Consider the following class of two-ended routing problems: For a given origin-destination trip matrix and an underlying network on which the trips are to be made, there are items (people, goods, etc.) at each origin that must be transported to their destination. The items are to be transported from origins to destinations on vehicles with a capacity of k in such a manner so as to minimize the total distance travelled. The particular routing problem which will be considered in this paper is the dial-a-ride problem in which a trip represents a demand for service by a subscriber of the transportation system. See Cullen, Jarvis, and Ratliff [1] for further discussion of this problem.

Because of the complex nature of this class of routing problems, it is extremely difficult to solve even moderately sized problems optimally. Instead, the approach that will be taken here is to first cluster the trips together into groups of size k or less and then to determine a minimum distance route through the origins and destinations of each cluster. Clearly any grouping of size k or less will satisfy the capacity requirements of the vehicles; however, if the clusters are chosen poorly, the resulting routes will not be of minimum distance. Furthermore, the routing problem is restricted in that the origin of each trip must be visited before the destination. Thus, the solution of a dial-a-ride problem will proceed in two steps, a clustering step and a routing step.

2. CLUSTERING

The purpose of clustering is to group together those trips which form minimum distance routes. In general, it is difficult to determine the exact contribution of each trip to the total route distance. Hence, clustering models use surrogate measures instead. These measures are composed of two parts: the distance between the origin (destination) of a trip and the cluster, and the distance along the cluster. (The details of these distances will be specified later.) The surrogate measure for each vehicle approximates the total distance that the vehicle must travel in routing through the trips assigned to it. For example, in one type of clustering the vehicle can always begin at an origin point for the cluster, go out and back to the origin of each trip, travel to a destination point for the cluster, and go out and back to the destination of each trip. Furthermore, the out-and-back distance for each trip can be weighted by a distance multiplier to improve the quality of the surrogate measure.

Two types of distance criteria can be used in clustering: Minimum Load Distance and Minimum Vehicle Distance. Load distance refers to the total of vehicle load times vehicle distance travelled whereas vehicle distance refers only to the total vehicle distance travelled. The appropriateness of either criteria depends upon the application. For example, if the routing problem concerns people, it may be more appropriate to use the load distance criteria. (Presumably people prefer to minimize their vehicle distance travelled). If the routing problem concerns objects, it may be more appropriate to use the vehicle distance criteria.

In some applications it may not be possible to "split" loads. This restriction requires that all of the load for a trip be carried on the same vehicle. In some applications it may be appropriate to split loads in terms of some unit of divisibility. For example, if people are being carried on the trips, then it does not make sense to divide into units smaller than one person.

The clustering problem to be solved in the dial-a-ride application can be formally stated as follows:

$$\text{Minimize: } \sum_i \sum_j e_{ij} x_{ij} + \sum_j f_j$$

$$\text{Subject to: } \sum_i x_{ij} \leq k_j \quad \forall j$$

$$\sum_j x_{ij} = \ell_i \quad \forall i$$

$$x_{ij} = 0, 1, \dots, \ell_i \quad \forall i, j$$

where: e_{ij} = the distance between the origin of trip i and cluster j plus the distance between the destination of trip i and cluster j .

f_j = the distance along the cluster line for vehicle j

k_j = the capacity of vehicle j

ℓ_i = the load of trip i

λ = the distance multiplier

This problem employs the minimum vehicle distance criteria with load splitting. The x_{ij} variables are in terms of units of load and determine

how much of trip i 's load is assigned to vehicle j . The constraint set is that of a transportation problem, and as such it can be efficiently solved.

Consider the clustering problem. So far, no mention has been made of the specific method of determining the quantities e_{ij} and f_j . Rather, e_{ij} was identified only as the distance between the origin and the destination of trip i and the cluster j , and f_j only as the distance along the cluster j . Two general methods of determining these values will be discussed.

3. ENDPOINT CLUSTERING

The first method of clustering is known as endpoint clustering and is illustrated in Figure 1. (For purposes of illustration all distances are euclidean, although it is possible to use squared euclidean and rectilinear distances as well.) In this example $e_{ij} = p_i + q_i$ or more precisely:

$$e_{ij} = ((\bar{a}_j - \bar{x}_i)^2 + (\bar{b}_j - \bar{y}_i)^2)^{\frac{1}{2}} + ((\hat{a}_j - \hat{x}_i)^2 + (\hat{b}_j - \hat{y}_i)^2)^{\frac{1}{2}}$$

Also, $f_j = r_j$ or more precisely:

$$f_j = ((\bar{a}_j - \hat{a}_j)^2 + (\bar{b}_j - \hat{b}_j)^2)^{\frac{1}{2}}$$

For this method of calculating e_{ij} and f_j , it can be shown that the objective function is not convex. Hence, it may not be possible to determine the optimal solution to this problem without resorting to some sort of enumerative procedure. Instead, a heuristic approach to solving this problem has been developed. Initial computational experience with this algorithm indicates that it converges rapidly to a locally optimal solution.

The heuristic algorithm is based on the following decomposition of the clustering problem: Suppose initial values for the cluster points \bar{a}_j , \bar{b}_j , and \hat{a}_j , \hat{b}_j are known. (Two methods of determining these values will be discussed later.) Then it is possible to compute values for e_{ij} and f_j as shown above. Furthermore, the quantities e_{ij} and f_j become constants in the objective function and the only variables are the x_{ij} s.

The problem is now a transportation problem and can be readily solved to

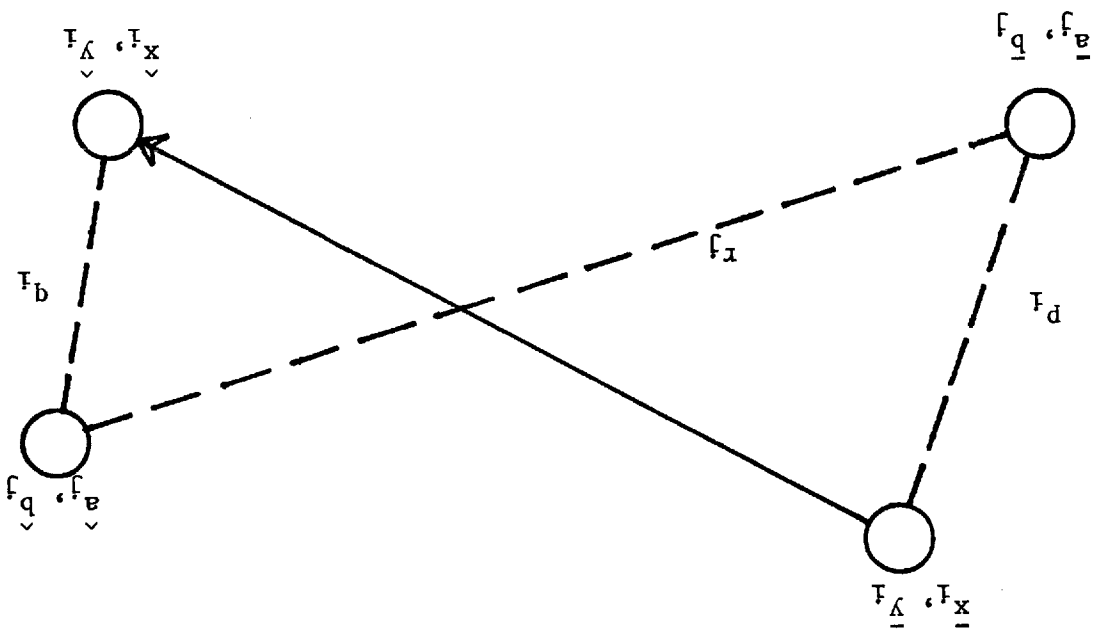


Figure 1 - Endpoint Clustering

yield locally optimal values of the x_{ij} s. With these values of the x_{ij} s as constants in the objective function, the resulting problem is now a location problem and can be readily solved using the Hyperbolic Approximation Procedure [2] to yield locally optimal values of \bar{a}_j , \bar{b}_j and \hat{a}_j , \hat{b}_j . This decomposition is illustrated in Figure 2.

The algorithm alternates back and forth between solving a transportation problem and a location problem until no further improvement in the objective function can be obtained. Since the resulting solution is only locally optimal, the quality of the final solution is a function of the initial values of the cluster points. Two methods of determining the initial cluster points have been tested. In the first method, the origin and destination points for the clusters are set equal to the origin and destination points for selected trips. These trips are chosen so as to give a fair representation of the dispersion of trips throughout the space. In the second method, the initial cluster points are selected by an operator using a color graphics terminal on which the trips are displayed. This method attempts to exploit the ability of a human operator to recognize spatial relationships.

Location/Allocation Problem (Euclidean Distance)

$$\begin{aligned} \text{Minimize: } & \sum_i \sum_j [\lambda x_{ij} ((\bar{a}_j - \bar{x}_i)^2 + (\bar{b}_j - \bar{y}_i)^2)^{\frac{1}{2}} + \\ & \lambda x_{ij} ((\hat{a}_j - \hat{x}_i)^2 + (\hat{b}_j - \hat{y}_i)^2)^{\frac{1}{2}}] + \\ & \sum_i \sum_j x_{ij} ((\bar{a}_j - \hat{a}_j)^2 + (\bar{b}_j - \hat{b}_j)^2)^{\frac{1}{2}} \end{aligned}$$

$$\begin{aligned} \text{Subject to: } & \sum_i x_{ij} \leq k_j \quad \forall j \\ & \sum_j x_{ij} = \ell_i \quad \forall i \\ & x_{ij} = 0, 1, \dots, \ell_i \quad \forall ij \end{aligned}$$

Transportation Problem (Euclidean Distance)

$$\text{Minimize: } \sum_i \sum_j x_{ij} d_{ij}$$

Subject to: As above

$$\begin{aligned} \text{Where: } d_{ij} = & \lambda ((\bar{a}_j - \bar{x}_i)^2 + (\bar{b}_j - \bar{y}_i)^2)^{\frac{1}{2}} + \\ & \lambda ((\hat{a}_j - \hat{x}_i)^2 + (\hat{b}_j - \hat{y}_i)^2)^{\frac{1}{2}} + \\ & ((\bar{a}_j - \hat{a}_j)^2 + (\bar{b}_j - \hat{b}_j)^2)^{\frac{1}{2}} \end{aligned}$$

Location Problem (Euclidean Distance)

$$\begin{aligned} \text{Minimize: } & \sum_i \sum_j [\lambda x_{ij} ((\bar{a}_j - \bar{x}_i)^2 + (\bar{b}_j - \bar{y}_i)^2)^{\frac{1}{2}} + \\ & \lambda x_{ij} ((\hat{a}_j - \hat{x}_i)^2 + (\hat{b}_j - \hat{y}_i)^2)^{\frac{1}{2}} + \\ & x_{ij} ((\bar{a}_j - \hat{a}_j)^2 + (\bar{b}_j - \hat{b}_j)^2)^{\frac{1}{2}}] \end{aligned}$$

Figure 2 - Decomposition Procedure for Endpoint Clustering

4. LINEAR CLUSTERING

The second method of clustering is known as linear clustering and is depicted in Figure 3. (For purposes of illustration all distances are euclidean.) The line connecting \bar{a}_j, \bar{b}_j with \hat{a}_j, \hat{b}_j is known as the cluster line. The point $\bar{c}_{ij}, \bar{d}_{ij}$ represents the point on the cluster line that is closest to the origin point for trip i . Likewise, the point $\hat{c}_{ij}, \hat{d}_{ij}$ represents the point on the cluster line that is closest to the destination point for trip i . (As noted in the figure $\bar{c}_{ij}, \bar{d}_{ij}$ can be represented as a convex combination of \bar{a}_j, \bar{b}_j and \hat{a}_j, \hat{b}_j . Likewise, for $\hat{c}_{ij}, \hat{d}_{ij}$. This representation will be useful later.) In this example, $e_{ij} = p_i + q_i$ or more precisely:

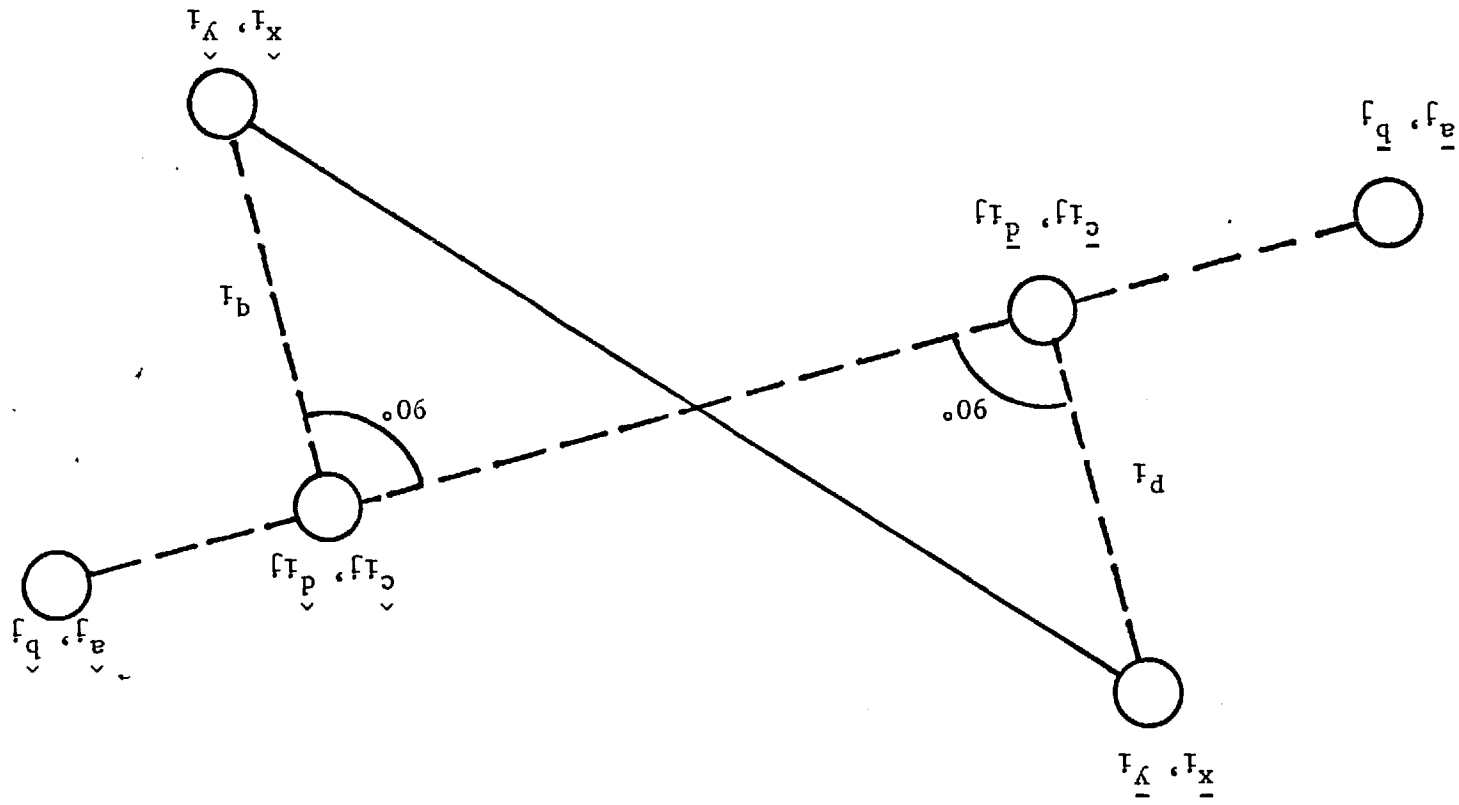
$$e_{ij} = ((\bar{c}_{ij} - \bar{x}_i)^2 + (\bar{d}_{ij} - \bar{y}_i)^2)^{\frac{1}{2}} + ((\hat{c}_{ij} - \hat{x}_i)^2 + (\hat{d}_{ij} - \hat{y}_i)^2)^{\frac{1}{2}}$$

The calculation of f_j is somewhat more complicated; in terms of the notation it is as follows:

$$f_j = ((\bar{c}_{kj} - \hat{c}_{lj})^2 + (\bar{d}_{kj} - \hat{d}_{lj})^2)^{\frac{1}{2}}$$

where: $\bar{c}_{kj}, \bar{d}_{kj}$ is that point for which $\lambda_k = \max_i (\lambda_i)$
 $\hat{c}_{lj}, \hat{d}_{lj}$ is that point for which $\pi_l = \max_i (\pi_i)$

Thus, f_j represents the distance between the most extreme point $\bar{c}_{ij}, \bar{d}_{ij}$ in the direction of the origin and the most extreme point $\hat{c}_{ij}, \hat{d}_{ij}$ in the direction of the destination. This is illustrated for an example involving two trips in Figure 4.



$$\begin{aligned} \bar{c}_{1j} &= \lambda_{1j} \bar{a}_j + (1 - \lambda_{1j}) \bar{a}_j \\ \bar{d}_{1j} &= \lambda_{1j} \bar{b}_j + (1 - \lambda_{1j}) \bar{b}_j \\ \hat{c}_{1j} &= \pi_{1j} \hat{a}_j + (1 - \pi_{1j}) \hat{a}_j \\ \hat{d}_{1j} &= \pi_{1j} \hat{b}_j + (1 - \pi_{1j}) \hat{b}_j \end{aligned}$$

Figure 3 - Linear Clustering

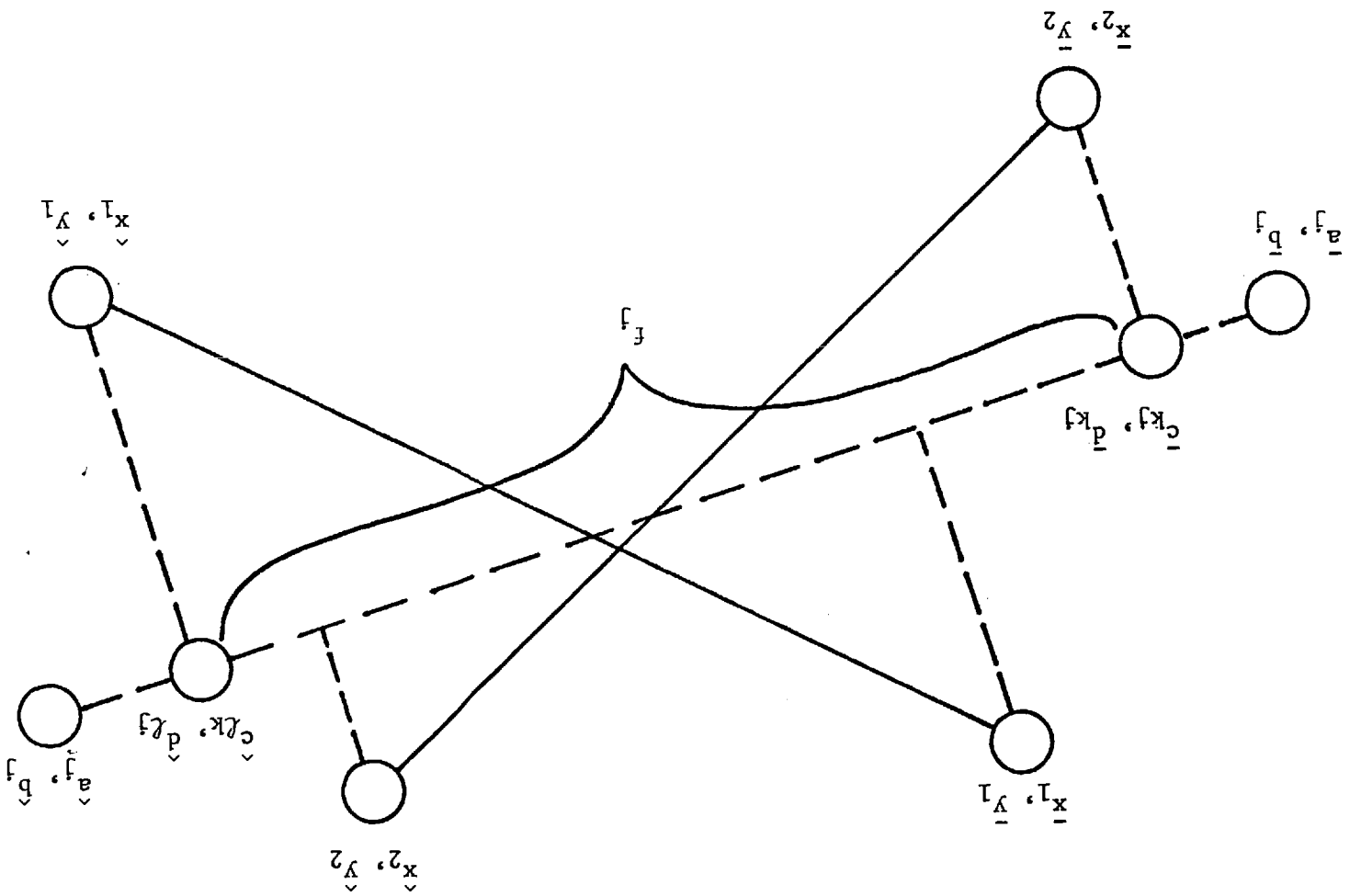


Figure 4 - Linear Clustering

Thus far it has been assumed that \bar{c}_{ij} , \bar{d}_{ij} and \hat{c}_{ij} , \hat{d}_{ij} exist, but no method of calculating them has been presented. Fortunately, it is possible to calculate these points (or rather their λ_i and π_i values) in closed form, thus avoiding the expense of an iterative procedure. For euclidean and squared euclidean distances, it can be shown that

$$\lambda_i = ((\bar{x}_i - \hat{a}_j)(\bar{a}_j - \hat{a}_j) + (\bar{y}_i - \hat{b}_j)(\bar{b}_j - \hat{b}_j)) / ((\bar{a}_j - \hat{a}_j)^2 + (\bar{b}_j - \hat{b}_j)^2)$$

and

$$\pi_i = ((\hat{x}_i - \bar{a}_j)(\hat{a}_j - \bar{a}_j) + (\hat{y}_i - \bar{b}_j)(\hat{b}_j - \bar{b}_j)) / ((\hat{a}_j - \bar{a}_j)^2 + (\hat{b}_j - \bar{b}_j)^2)$$

For rectilinear distances, it can be shown that

$$\begin{aligned} \lambda_i &= (\bar{x}_i - \hat{a}_j) / (\bar{a}_j - \hat{a}_j) \text{ if } |\bar{a}_j - \hat{a}_j| / |\bar{b}_j - \hat{b}_j| \geq 1 \\ &= (\bar{y}_i - \hat{b}_j) / (\bar{b}_j - \hat{b}_j) \text{ if } |\bar{a}_j - \hat{a}_j| / |\bar{b}_j - \hat{b}_j| < 1 \end{aligned}$$

and

$$\begin{aligned} \pi_i &= (\hat{x}_i - \bar{a}_j) / (\hat{a}_j - \bar{a}_j) \text{ if } |\hat{a}_j - \bar{a}_j| / |\hat{b}_j - \bar{b}_j| \geq 1 \\ &= (\hat{y}_i - \bar{b}_j) / (\hat{b}_j - \bar{b}_j) \text{ if } |\hat{a}_j - \bar{a}_j| / |\hat{b}_j - \bar{b}_j| < 1 \end{aligned}$$

A proof of these results is contained in Appendix A.

As with endpoint clustering, the linear clustering problem is also not convex in its objective. Hence, a similar heuristic approach to solving the problem is taken. Given a set of cluster points \bar{a}_j , \bar{b}_j and \hat{a}_j , \hat{b}_j , a transportation problem is solved to yield locally optimal values of the x_{ij} 's.

Given a set of x_{ij} 's, a location problem is solved to yield values of \bar{a}_j , \bar{b}_j and \hat{a}_j , \hat{b}_j . While the transportation problem for linear clustering is identical to that for endpoint clustering, the location problem in linear clustering is more difficult and cannot be solved by use of the Hyperbolic Approximation Procedure. To illustrate this point, consider the formulation of the location problem in linear clustering for euclidean distance shown in Figure 5. This problem has a nonlinear objective function and nonlinear constraints. While one would probably not attempt to solve this problem in this form (since the constraints are all equations, they can be substituted into the objective function), it does illustrate the difficulty in solving this problem: the cross-product terms involving $\alpha_j \bar{c}_{ij}$, $\beta_j \bar{d}_{ij}$, $\alpha_j \hat{c}_{ij}$, and $\beta_j \hat{d}_{ij}$ and

$$\max_{i,k} \{((c_{ij} - c_{kj})^2 + (d_{ij} - d_{kj})^2)^{1/2}\}.$$

Because of the difficulties in solving the location problem in linear clustering, it does not seem possible to solve the problem efficiently. However, suppose that the problem is simplified by eliminating the distance along the cluster line from the objective function for each cluster. The resulting problem is that of minimizing the sum of the distances to the cluster line for all trips in a cluster for each cluster. Morris and Norback [3] have shown that in an optimal solution to this problem, the cluster line must pass through at least two of the trip points (origins or destinations). Thus, the procedure which they suggest for solving this problem is to enumerate all pairs of points as possible locations for the cluster line, and to select that pair for which the sum of the distances to the cluster line is minimal.

Location Problem (Euclidean Distance)

$$\begin{aligned} \text{Minimize: } & \sum_i \sum_j \left[\lambda_{x_{ij}} ((\bar{c}_{ij} - \bar{x}_i)^2 + (\bar{d}_{ij} - \bar{y}_i)^2)^{\frac{1}{2}} + \right. \\ & \left. \lambda_{x_{ij}} ((\hat{c}_{ij} - \hat{x}_i)^2 + (\hat{d}_{ij} - \hat{y}_i)^2)^{\frac{1}{2}} \right] + \\ & \sum_j \max_{i,k} ((\hat{c}_{ij} - \bar{c}_{kj})^2 + (\hat{d}_{ij} - \bar{d}_{kj})^2)^{\frac{1}{2}} \end{aligned}$$

$$\text{Subject to: } \alpha_j \hat{c}_{ij} + \beta_j \hat{d}_{ij} = \gamma_j \quad \forall ij$$

$$\alpha_j \bar{c}_{ij} + \beta_j \bar{d}_{ij} = \gamma_j \quad \forall ij$$

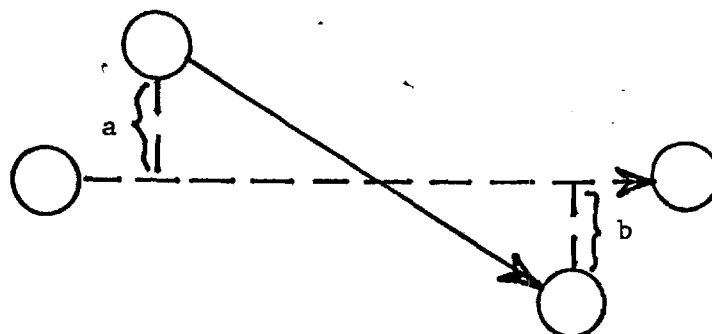
Where: α_j , β_j , and γ_j are the coefficients in linear form
(i.e. $\alpha_j x + \beta_j y - \gamma = 0$) of the cluster line

Figure 5 - Location Problem in Linear Clustering

If one assumes for the location problem in linear clustering that the cluster line must also pass through two trip points, then the problem can be solved by evaluating the objective function for each location of the cluster line and selecting that location with the minimum value. This assumption can be partially justified by noting that the distance along the cluster line is mostly a function of the minimum and maximum x and y coordinates for the trips in the cluster. Thus, it is approximately a constant. If the enumerative solution approach is adopted, then it is possible to consider more realistic values for the e_{ij} terms. Recall that the term e_{ij} represents the contribution of trip i to the total route distance for cluster j. While letting e_{ij} be simply the distance between the origin of trip i and cluster line j plus the distance between the destination of trip i and cluster line j is not a bad approximation, it can be improved upon in many cases. The various combinations of a trip i and a cluster line j which give rise to different ways of evaluating e_{ij} are shown in Figure 6. The trip is indicated by two points connected by a solid line, and the cluster line j is indicated by two points connected by a dashed line.

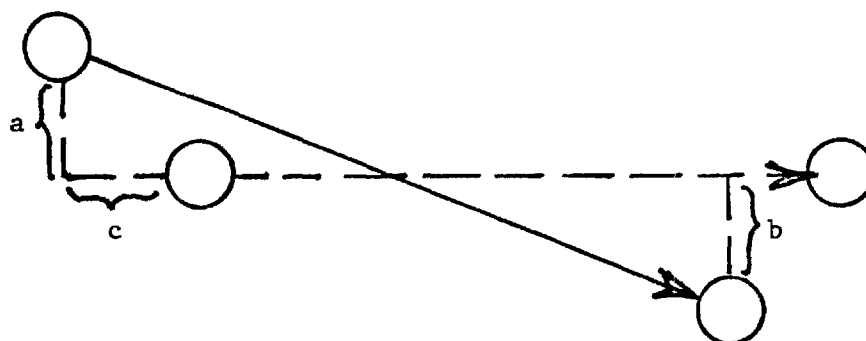
To illustrate the rationale for the method of evaluating e_{ij} in Figure 6, consider Case 2. Vehicle j must travel out and back to the origin and destination for trip i from the cluster line. Hence, e_{ij} includes distances a and b. Furthermore, because the line which connects the origin for trip i with cluster line j intersects the cluster line to the left of the origin for cluster j, vehicle j must travel the additional distance c in order to pickup trip i. Hence e_{ij} includes the distance c.

Case 1



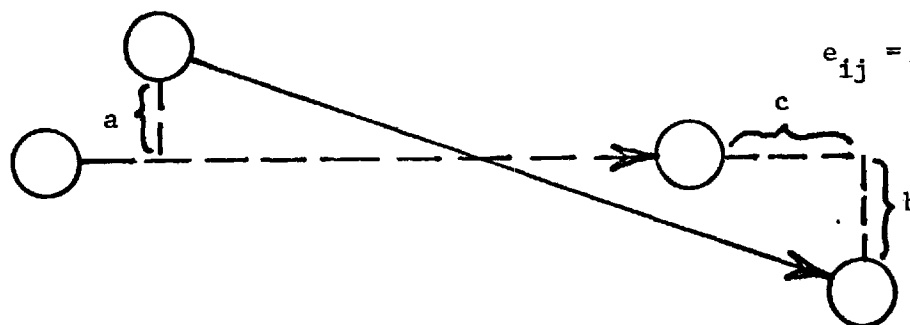
$$e_{ij} = a + b$$

Case 2



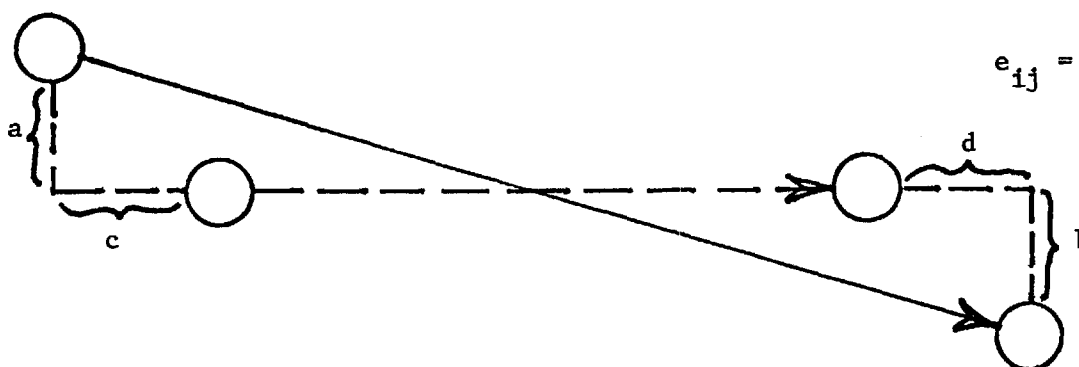
$$e_{ij} = a + b + c$$

Case 3



$$e_{ij} = a + b + c$$

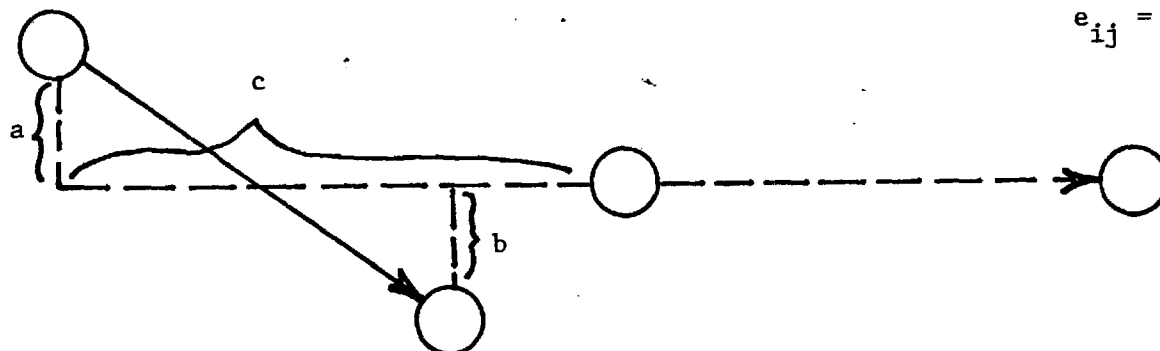
Case 4



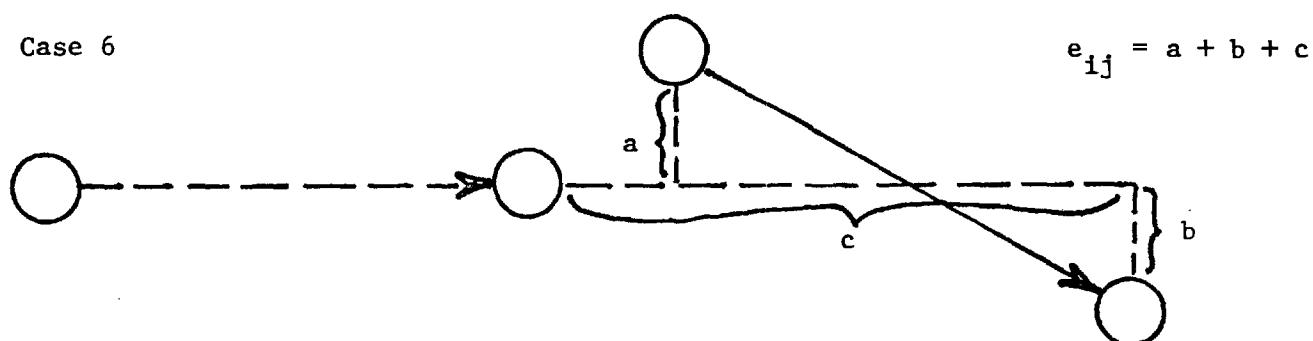
$$e_{ij} = a + b + c + d$$

Figure 6 - Evaluation of e_{ij} in Linear Clustering

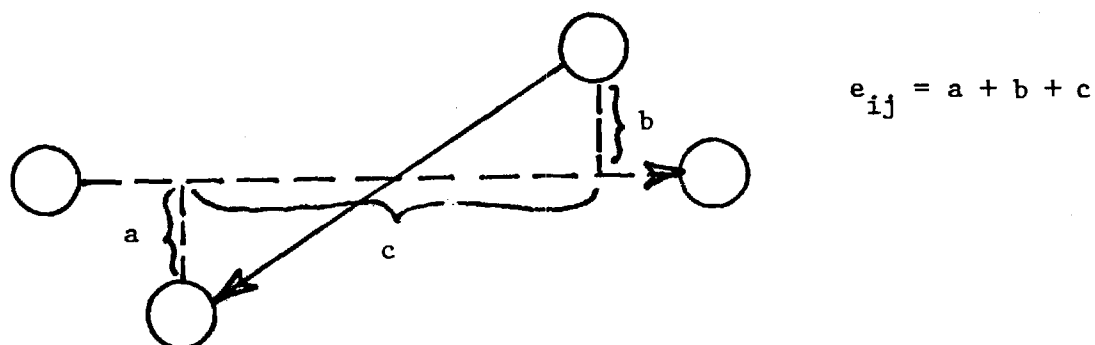
Case 5



Case 6



Case 7



Case 8

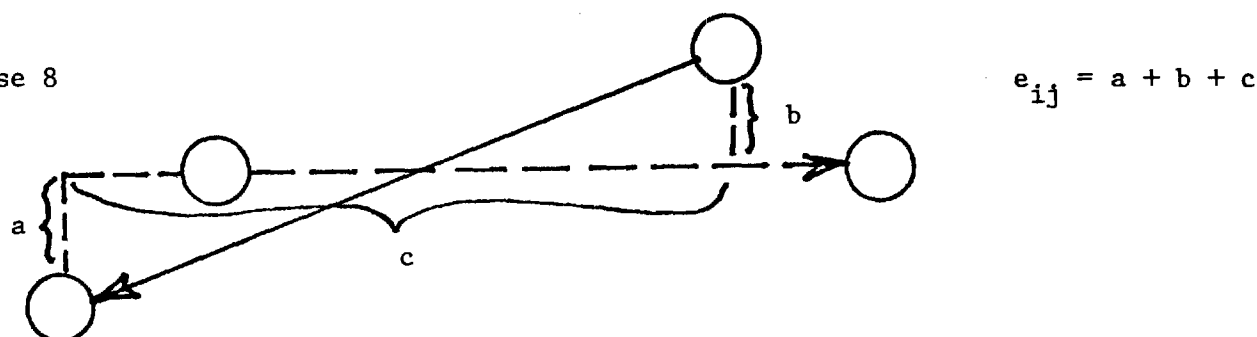
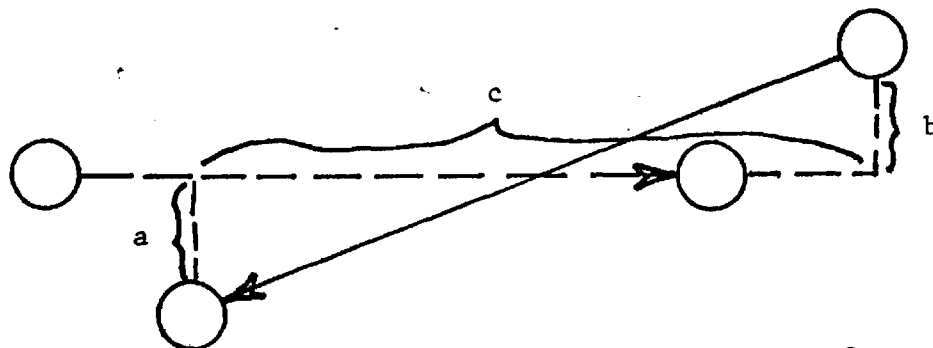


Figure 6 - Continued

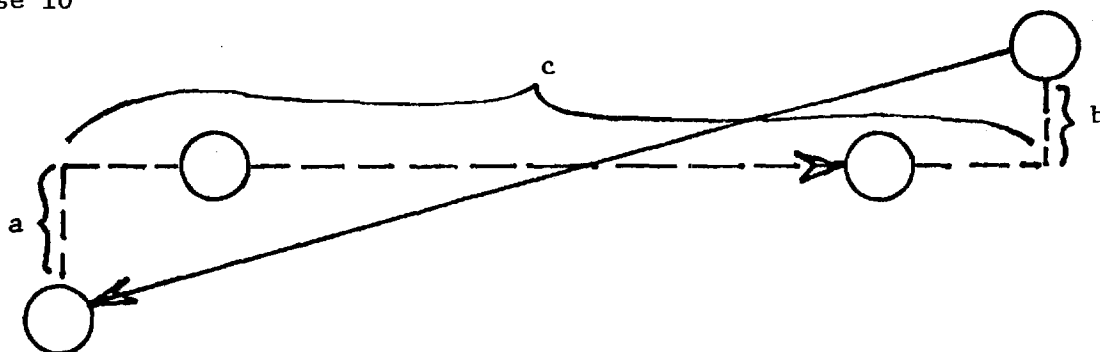
Case 9

$$e_{ij} = a + b + c$$



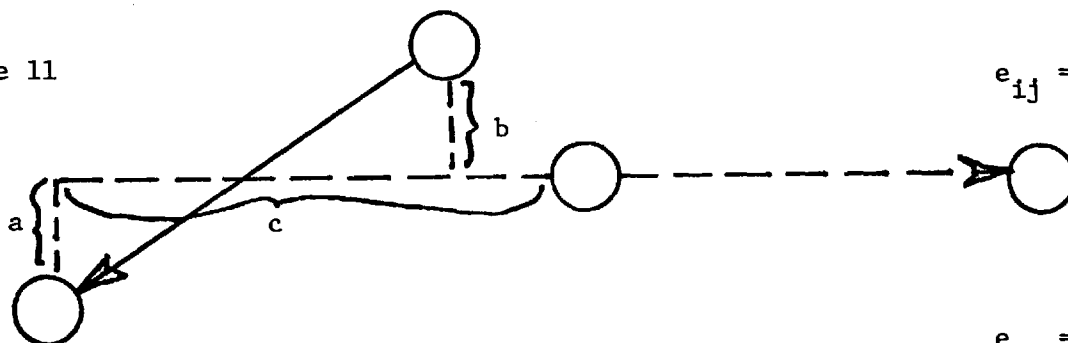
Case 10

$$e_{ij} = a + b + c$$



Case 11

$$e_{ij} = a + b + c$$



Case 12

$$e_{ij} = a + b + c$$

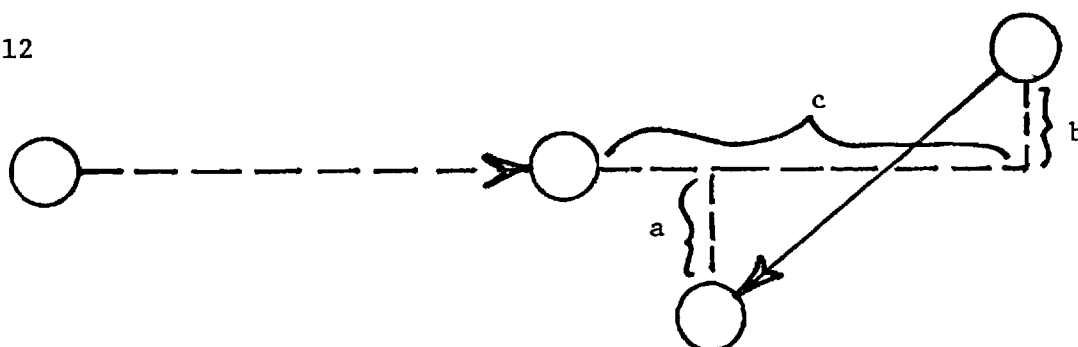


Figure 6 - Continued

5. EXAMPLES OF CLUSTERING

The clustering techniques described above have been implemented on a color graphics terminal. Endpoint and linear clustering models were applied to a sample set of Rochester, New York dial-a-ride data. The results appear quite favorable and are encouraging for future efforts clustering model development.

6. REFERENCES

1. Cullen, F. H., J. J. Jarvis, and H. D. Ratliff, "Set Partitioning Based Heuristics for Interactive Routing and Scheduling," School of Industrial and Systems Engineering Report Series #J-80-1 Georgia Institute of Technology, (1980).
2. Francis, R. and J. White, Facility Layout and Location, Prentice Hall, Englewood Cliffs, New Jersey, 1974.
3. Morris, J. and J. Norback, "A Simple Approach to Linear Facility Location," *Transportation Science*, Vol. 14, pp. 1-8, 1980.

Appendix A

Verification of Closed Form Expressions for π and λ in Linear Clustering

First consider euclidean and squared euclidean distances. The problem of finding the point on the cluster line that minimizes the distance between the line and an origin (or destination) point is identical for euclidean and squared euclidean distances. This is true because the minimum of the square root of a function occurs at the same point as that for the minimum of the function.

Let D represent the squared euclidean distance from an origin point to the cluster line. (For simplicity of notation the subscripts are dropped.) Then,

$$\begin{aligned}
 D &= (\lambda \bar{a} + (1 - \lambda) \hat{a} - \bar{x})^2 + (\lambda \bar{b} + (1 - \lambda) \hat{b} - \bar{y})^2 \\
 \partial D / \partial \lambda &= 2(\lambda \bar{a} + (1 - \lambda) \hat{a} - \bar{x})(\hat{a} - \bar{a}) + \\
 &\quad 2(\lambda \bar{b} + (1 - \lambda) \hat{b} - \bar{y})(\hat{b} - \bar{b}) \\
 &= (\lambda(\bar{a} - \hat{a}) + \hat{a} - \bar{x})(\bar{a} - \hat{a}) + (\lambda(\bar{b} - \hat{b}) + \hat{b} - \bar{y})(\bar{b} - \hat{b}) \\
 &= \lambda(\bar{a} - \hat{a})^2 + (\hat{a} - \bar{x})(\bar{a} - \hat{a}) + \lambda(\bar{b} - \hat{b})^2 + (\hat{b} - \bar{y})(\bar{b} - \hat{b}) \\
 &= \lambda((\bar{a} - \hat{a})^2 + (\bar{b} - \hat{b})^2) - ((\bar{x} - \hat{a})(\bar{a} - \hat{a}) + (\bar{y} - \hat{b})(\bar{b} - \hat{b})) = 0 \\
 \lambda &= ((\bar{x} - \hat{a})(\bar{a} - \hat{a}) + (\bar{y} - \hat{b})(\bar{b} - \hat{b})) / ((\bar{a} - \hat{a})^2 + (\bar{b} - \hat{b})^2)
 \end{aligned}$$

The argument is similar for π . Hence,

$$\pi = ((\hat{x} - \bar{a})(\hat{a} - \bar{a}) + (\hat{y} - \bar{b})(\hat{b} - \bar{b})) / ((\hat{a} - \bar{a})^2 + (\hat{b} - \bar{b})^2)$$

Consider rectilinear distance next. Let D represent the rectilinear distance from an origin point to the cluster line. Then

$$\begin{aligned}
D &= |\lambda \bar{a} + (1 - \lambda) \hat{a} - \bar{x}| + |\lambda \bar{b} + (1 - \lambda) \hat{b} - \bar{y}| \\
&= |\lambda(\bar{a} - \hat{a}) - (\bar{x} - \hat{a})| + |\lambda(\bar{b} - \hat{b}) - (\bar{y} - \hat{b})|
\end{aligned}$$

This can be rewritten as the following linear programming problem.

$$\begin{aligned}
\text{Minimize:} \quad & D = A + B \\
\text{Subject to:} \quad & (\bar{a} - \hat{a})\lambda + A = (\bar{x} - \hat{a}) \\
& (\bar{b} - \hat{b})\lambda + B = (\bar{y} - \hat{b}) \\
& \lambda, A, B \text{ unrestricted}
\end{aligned}$$

Excluding for the moment the case where $\lambda^* = 0$, we know from the theory of linear programming that if $\lambda^* \neq 0$, then either $A^* = 0$ or $B^* = 0$. If $\lambda^* = 0$, then either $\bar{x} = \hat{a}$ and $A^* = 0$ or $\bar{y} = \hat{b}$ and $B^* = 0$. Hence, when D is minimized either 1)

$$|\lambda(\bar{a} - \hat{a}) - (\bar{x} - \hat{a})| = 0 \Rightarrow \lambda = (\bar{x} - \hat{a})/(\bar{a} - \hat{a})$$

or 2)

$$|\lambda(\bar{b} - \hat{b}) - (\bar{y} - \hat{b})| = 0 \Rightarrow \lambda = (\bar{y} - \hat{b})/(\bar{b} - \hat{b})$$

Thus, at optimality λ can take on only two values; denote them by λ_1 and λ_2 .

For case 1) to occur then

$$D(\lambda_1) \leq D(\lambda_2)$$

$$\begin{aligned}
& |((\bar{b} - \hat{b})(\bar{x} - \hat{a}) - (\bar{a} - \hat{a})(\bar{y} - \hat{b})) / (\bar{a} - \hat{a})| \leq \\
& |((\bar{y} - \hat{b})(\bar{a} - \hat{a}) - (\bar{b} - \hat{b})(\bar{x} - \hat{a})) / (\bar{b} - \hat{b})|
\end{aligned}$$

which implies

$$|\bar{a} - \hat{a}| \geq |\bar{b} - \hat{b}|$$

For case 2) to occur then

$$|\bar{a} - \hat{a}| \leq |\bar{b} - \hat{b}|$$

In summary,

$$\begin{aligned} \lambda &= (\bar{x} - \hat{a}) / (\bar{a} - \hat{a}) \quad \text{if } |\bar{a} - \hat{a}| / |\bar{b} - \hat{b}| \geq 1 \\ &= (\bar{y} - \hat{b}) / (\bar{b} - \hat{b}) \quad \text{if } |\bar{a} - \hat{a}| / |\bar{b} - \hat{b}| < 1 \end{aligned}$$

The argument for π is similar.

$$\begin{aligned} \pi &= (\hat{x} - \bar{a}) / (\hat{a} - \bar{a}) \quad \text{if } |\hat{a} - \bar{a}| / |\hat{b} - \bar{b}| \geq 1 \\ &= (\hat{y} - \bar{b}) / (\hat{b} - \bar{b}) \quad \text{if } |\hat{a} - \bar{a}| / |\hat{b} - \bar{b}| < 1 \end{aligned}$$

APPENDIX A-3

TECHNICAL REPORT:

CHAINING IN THE DIAL-A-RIDE
VEHICLE ROUTING PROBLEM

CHAINING IN THE DIAL-A-RIDE
VEHICLE ROUTING PROBLEM

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August 1980

ABSTRACT

A network flow model of chaining in the Dial-A-Ride transportation problem is developed. Since the network flow model employs side constraints, viz certain subsets of arcs may only have one unit of flow between them, it cannot be solved by ordinary network flow techniques.

A Lagrangian relaxation method is developed to handle the side constraints of the network flow problem for chaining. The method appears to work well on small test problems; however, further testing will be required before definite answers about its usefulness can be obtained.

1. INTRODUCTION

Elsewhere [1] a framework for modeling and analysis of demand responsive (dial-a-ride) transportation systems has been discussed. Figure 1 illustrates a dial-a-ride problem in which 11 trips (people) must be accommodated[†]. Each arc represents an association of origin and destination for the particular trip. The problem is to route the available vehicles through the community so as to satisfy all trip requirements with minimum distance.

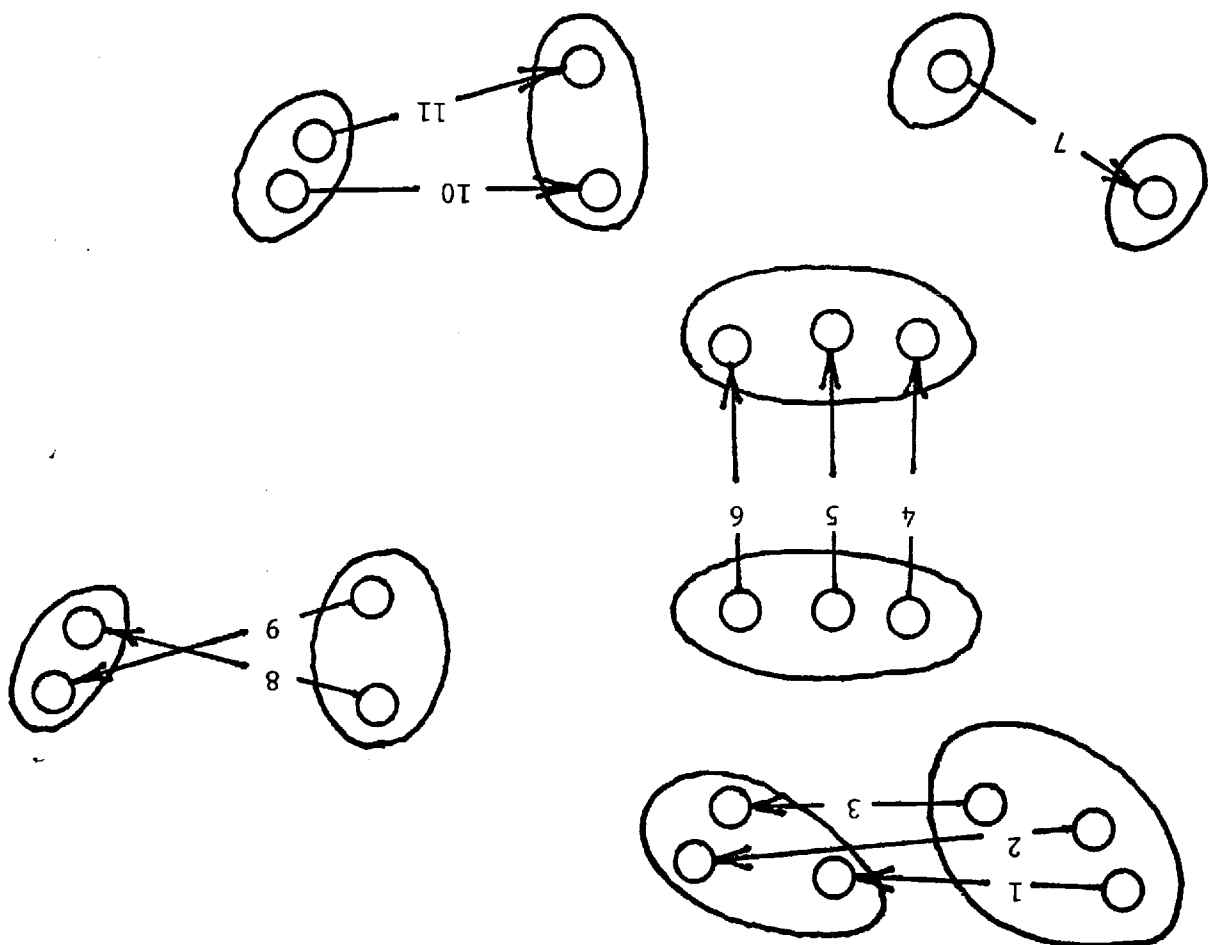
In [1] a two stage procedure was developed for analyzing a dial-a-ride system. The trips were first "clustered". The object of clustering is to identify subgroups of trips which will be serviced by the same vehicle by first visiting their origins and then visiting their destinations. Figure 2 depicts five such clusters. By employing different clustering techniques (see [2]) it is possible to generate a number of different clusters, all containing the same trip.

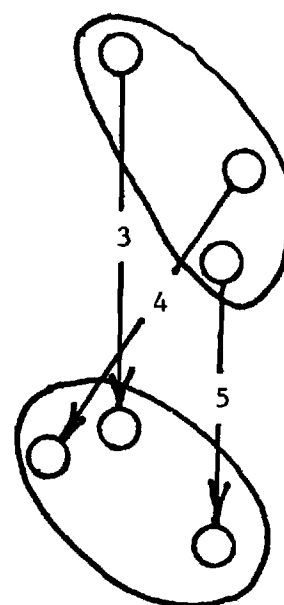
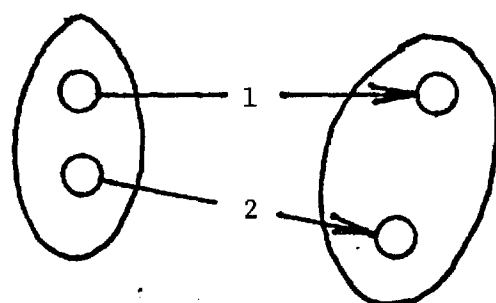
The clusters obtained represent good possibilities for segments (legs) of a vehicle route. The next step in the process is to link ("chain") these clusters into complete vehicles routes. Figure 2 illustrates the chaining concept. Trips 1 and 2 form one cluster, while trips 3, 4 and 5 form another cluster (see Figure 2). In Figure 2, trips 1 and 2 are replaced by a single pseudo (cluster) trip, as is also the case for trips 3, 4 and 5. These cluster trips are then chained together.

The interpretation of chaining is that a single vehicle will service the first set of trips (in Figure 2 these would be trips 1 and 2) and then proceed to service the next set of trips (i.e., trips 3, 4 and 5) in the chain.

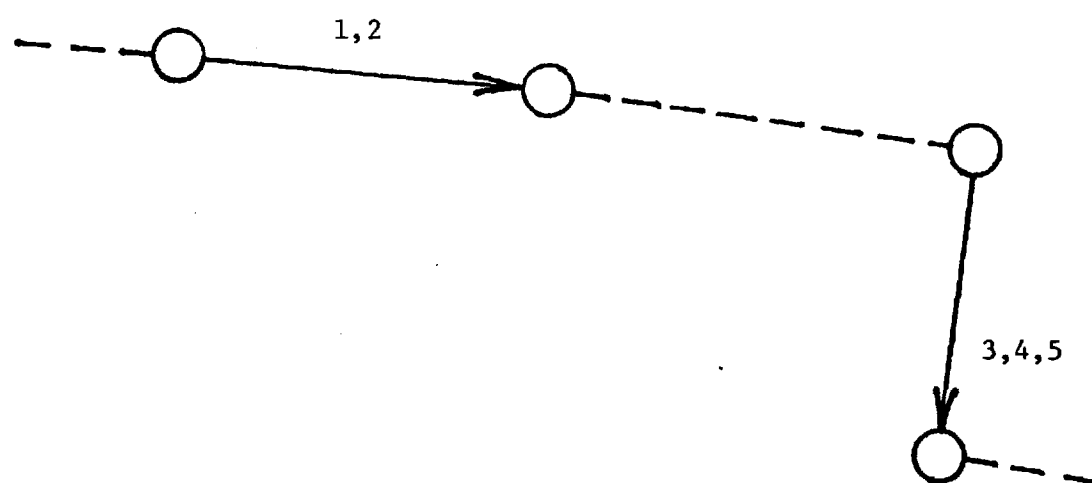
[†] Several figures in this report are repeated from the earlier report [1] so that the current report can be read as a self-contained document.

Figure 1. Example of Clusters Resulting from the Clustering Process





a. Two Typical Clusters



b. The Associated Cluster Arcs Chained Together

Figure 2. An Example of Chaining Clusters Together

Figure 3 illustrates the likely vehicle route to service the two clusters.

We shall demonstrate how mathematical models can be developed to aid the human in developing good chains (vehicle routes).

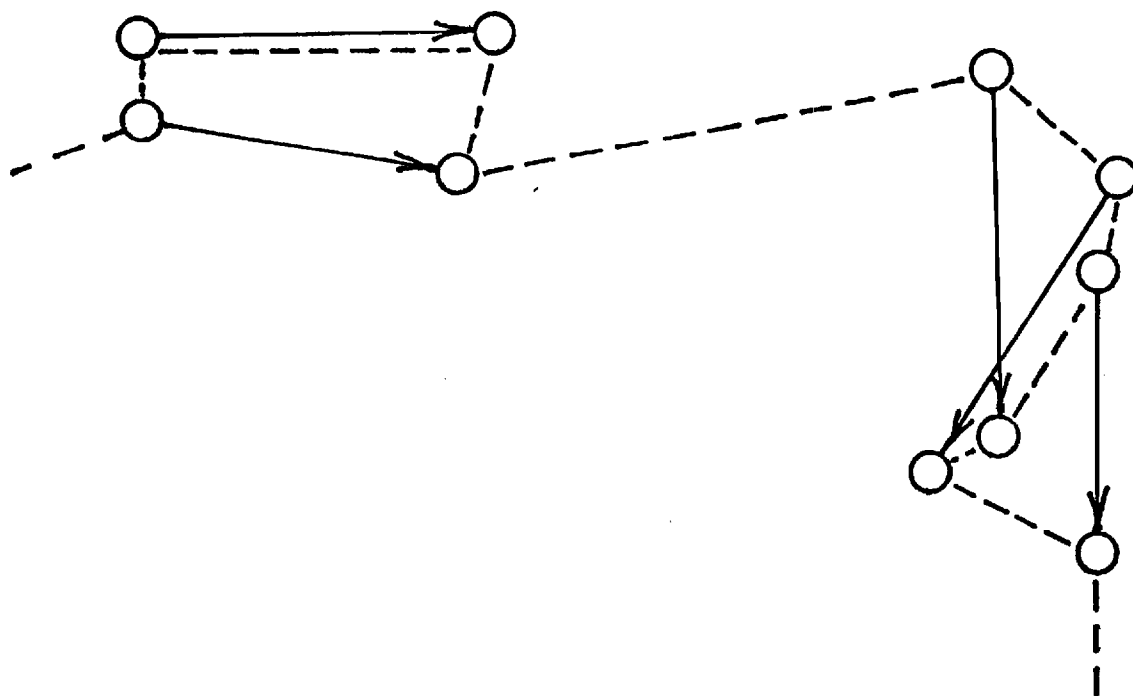


Figure 3. Probable Vehicle Route
for the Chain of Figure 2b

2. NETWORK FLOW/PARTITIONING MODEL FOR CHAINING

The most fundamental model of chaining is based on network flows.

In a network we represent each cluster trip by two nodes (an origin and a destination node) and an arc. We then add additional arcs to the network which link the destination node of one cluster arc to the origin node of another cluster arc on the basis of proximity considerations. In Figure 4, we indicate one network flow model for the clusters of Figure 1.

To establish the flow variables for the network flow problem consider the case where each trip appears in exactly one cluster. We assign every arc an upper capacity of 1, the dashed arcs a lower capacity of 0 (zero) and the solid cluster arcs a lower capacity of 1 indicating that these trips must be serviced. Arc flow costs for the network flow problem are the associated vehicle travel distances. If the "starting node" and the "ending node" represents the vehicle storage depot, then we may also assign additional costs to the arcs originating at the starting node to reflect the fixed cost of using each vehicle (provided they are all the same).

If the network flow problem for chaining contains no circuits and if the same trip does not appear in two different clusters in the network, then the resulting chains (vehicles routes) will be valid ones. If either of these two conditions are explicitly included in the model, then the underlying network flow problem becomes considerably more complicated.

We can circumvent some of the problems associated with the difficult problems of chaining by utilizing a partitioning model of chaining. (Actually we substitute one difficulty for another.) In a partitioning model of chaining, we associate a column of the partitioning matrix for each feasible chain (vehicle route) and a row for each trip. Column j contains a 1 in row i if trip i is serviced by chain (vehicle route) j . Otherwise, it contains a 0 (zero). The zero-one variable associated with the columns provide indications

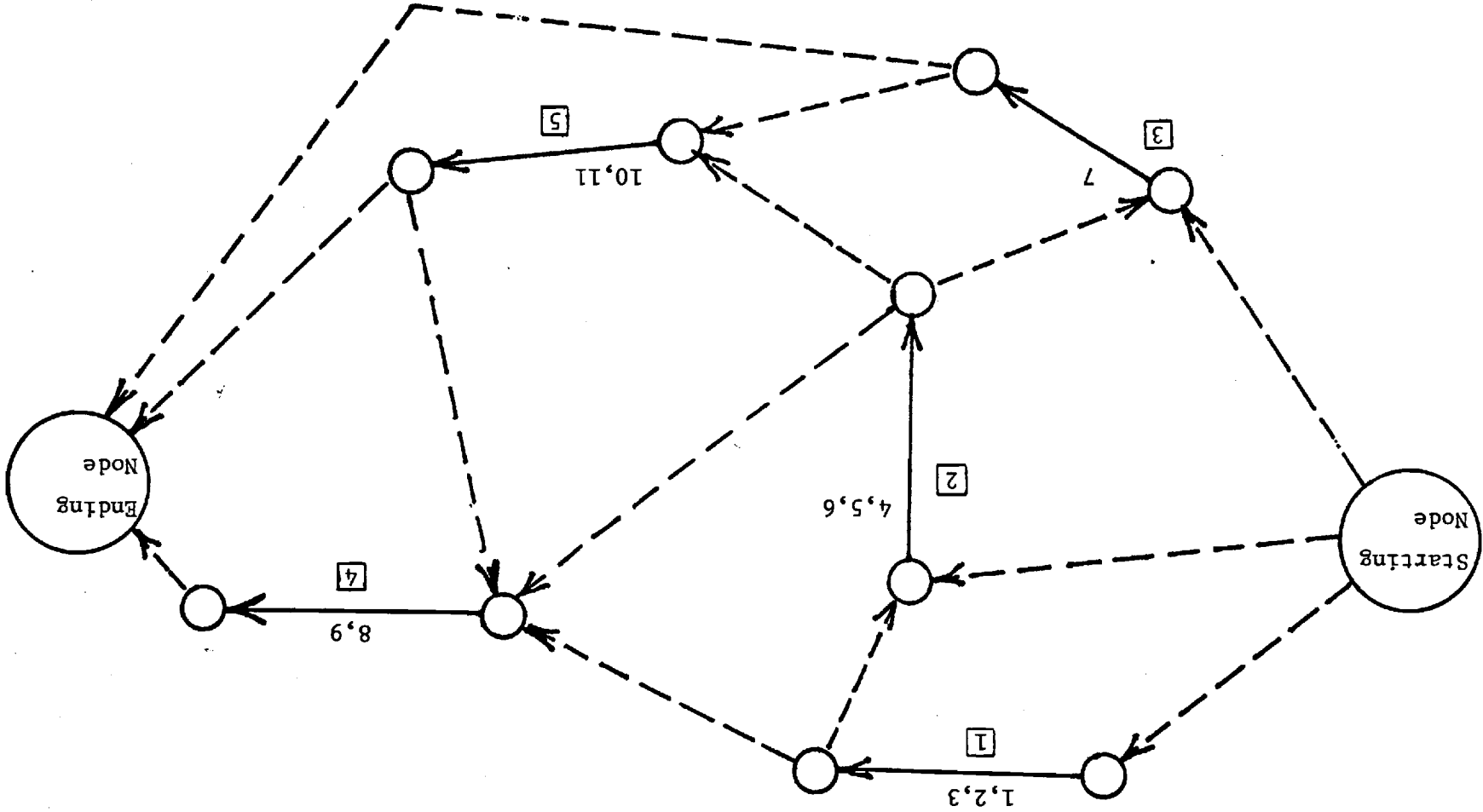


Figure 4. The Network Flow Problem for Chaining of the Clusters in Figure 1

of which chains were selected in the optimal partitioning solution. Table 1 illustrates a partitioning matrix for several chains in Figure 4.

Besides solving the partitioning model optimally (which we would not likely do), the obvious difficulty with such a model is in generating the candidate chains (columns). To aide in this column generation process, we could employ (1) the human (which would certainly be part of any interactive process), (2) a savings approach to combine clusters into chains, (3) a network flow model or (4) some other method. The first two of these column generation approaches should be reasonably intuitive to develop. We shall briefly describe the third one. Suppose we have identified some candidate columns (chains) for the primary concern partitioning problem (e.g. the individual clusters from the clustering process). Then, the partitioning model will yield (1) an optimal solution and (2) a set of row prices. As before, a column j not in the solution appears favorable if

$$\sum_i p_i a_{ij} - c_j > 0.$$

where p_i is the price for row i in the partitioning problem (see [1]).

Now, c_j is the cost (distance) of servicing the chain. Also, $\sum_i p_i a_{ij}$ is the cost of servicing the given trips in the current partitioning solution. Consider how these two terms might be represented in the network of Figure 4.

Suppose we associate with each dashed arc the negative of whatever costs that are incurred in traversing the arc (this is the same as before with a sign change). Associated with each clustering arc the quantity $\sum p - c$, where the term $\sum p$ represents the sum of row prices for trips in the cluster and c represents the cost of the cluster. With these costs defined on the network, we seek a path (or paths) in the network, from the starting to the ending node, which has positive total cost. It should be clear that such a

	clusters 1 & 2	clusters 1 & 4	clusters 2 & 5	clusters 1, 2 & 5	clusters 3, 4 & 5	clusters 1, 2 & 4	clusters 1, 2, 3 & 5
	1	2	3	4	5	6	7
1	1	1		1		1	1
2	1	1		1		1	1
3	1	1		1		1	1
4	1		1	1		1	1
5	1		1	1		1	1
6	1		1	1		1	1
7					1		1
8		1			1	1	
9		1			1	1	
10			1	1	1		1
11			1	1	1		1

Table 1 An Example Partitioning Model for Certain Chains in Figure 4

path satisfies the condition for a potentially improving chain, and can be added to the partitioning problem.

Again, with this network flow model (a shortest path model for a single chain) we have the difficulties associated with circuits and with the same trip serviced several times by a single chain. The phenomenon of a trip being serviced several times seems to occur infrequently since in seeking a least cost solution, the model tends to avoid such an instance. When it does occur, an attractive heuristic is to simply delete one of the conflicting clusters from the column being generated. We are currently utilizing the human interactor to handle the case where the flow problem contains circuits. The human breaks the circuits and patches the paths back together. If we restrict the procedure to locating a single improving path each time, the resulting shortest path model lends itself more intuitively to the development of good heuristic procedures for solving both of the major difficulties associated with the flow mode. In particular it is much easier for the human to break the circuits in a single path than in multipaths.

3. THE LAGRANGIAN APPROACH

A possible approach to solving the problem of multiple trips in chaining involves the use of Lagrangian multipliers. When dealing with a general primal problem $P(x)$ of the form:

$$\begin{aligned} P(x): \quad & \min \quad cx \\ & \text{s.t.} \quad Ax \geq b \\ & \quad \quad x \in X \end{aligned}$$

the Lagrangian relaxation, $P_\mu(x)$, is defined as

$$\begin{aligned} P_\mu(x): \quad & \min \quad cx + \lambda(b - Ax) \\ & \text{s.t.} \quad x \in X \end{aligned}$$

where λ is a nonnegative vector with one component for each row of A . This relaxation removes constraints from the constraint set and adds them, as a form of penalty, to the objective function. It can be proven that for all $\lambda \geq 0$, $v(P_\mu(x)) \leq v(P(x))$, where $v(\cdot)$ denotes optimal objective value. Thus $P_\mu(x)$ is a valid relaxation of the primal problem. This relaxation will become helpful when considering a network flow problem consisting of chaining clusters together with the added constraints prohibiting multiple trips. Since these added multiple trip constraints rob the problem of its network form, steps should be taken to somehow eliminate these "bad" constraints. It will be attempted in the following manner. First, separate the primal constraint matrix into two submatrices as follows:

$$A = \begin{bmatrix} A' \\ A'' \end{bmatrix}$$

where A' represents the set of all network constraints and A'' represents the set of all multiple trip prohibition constraints. Then, relax the primal to $P_\mu(x)$, where

$$P_\mu(x): \min \quad cx + (b'' - A''x)$$

$$\text{s.t. } x \in X$$

$$\text{where } X = \{x: A'x \geq b'\}$$

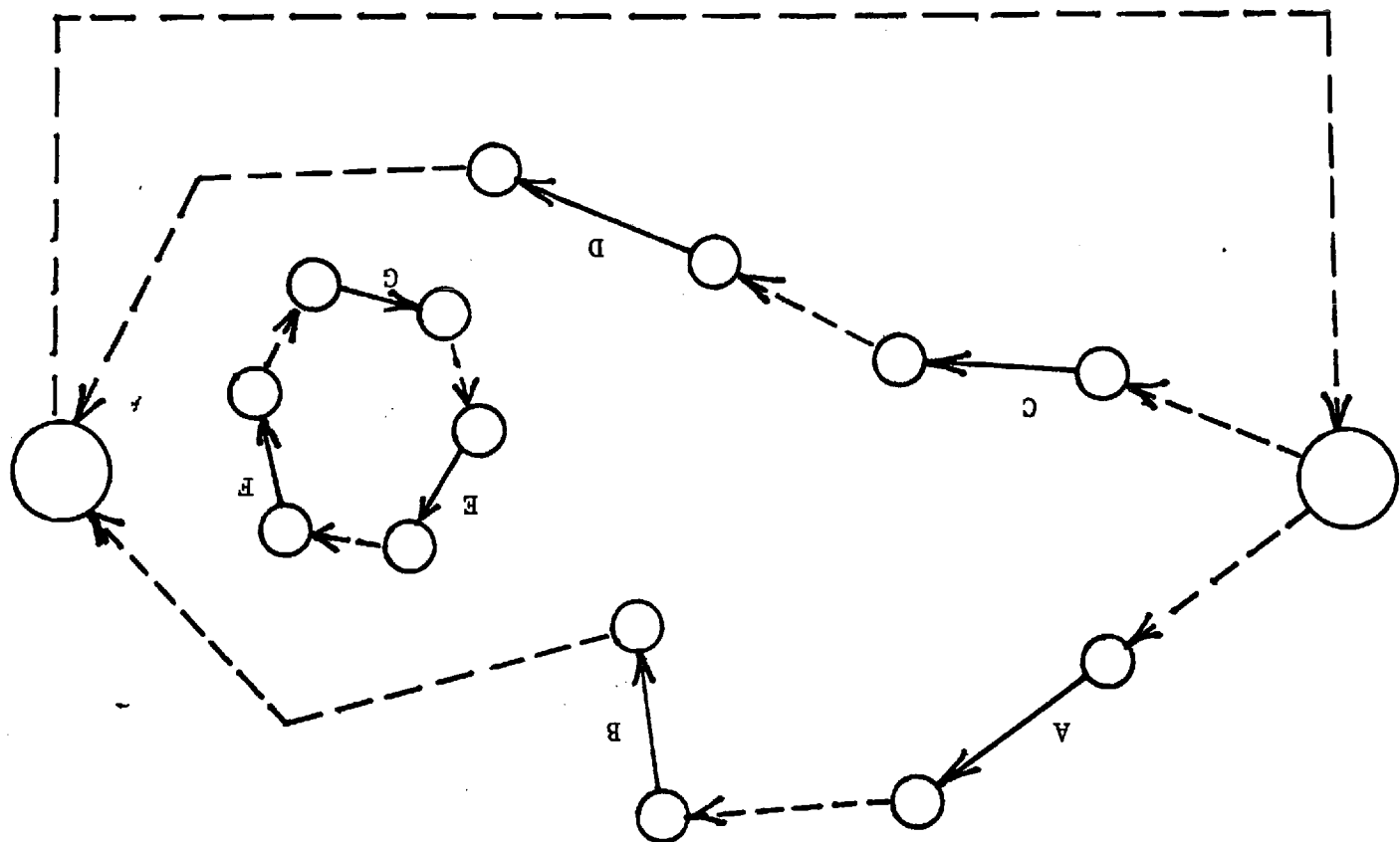
It will be noted that b' is a $l \times k'$ matrix where $k' =$ twice the number of clusters and b'' is a $l \times k''$ matrix where $k'' =$ the number of trips.

The dimension of k'' is intuitive since each trip will have its own constraint prohibiting duplication. It is therefore possible to view λ_i as the penalty for chaining more than one cluster containing the i th trip.

Once the modified problem $P_\mu(x)$ has been constructed, the next step is to solve it using a network flow algorithm, for example the out-of-kilter algorithm. By defining a supersource node, a supersink node and a return arc connecting the sink to the source, a lower bound on the number of chains generated can be established. For instance, if the lower bound on the return arc is 2, at least two chains would be generated (the validity of these chains is yet to be established however). See Figure 5 for an example.

Although the return arc has been forced to 2, three chains are formed ($A \rightarrow B$, $C \rightarrow D$, and $E \rightarrow F \rightarrow G$). Since the final chain is actually a negative flow circuit, the chain was established by simply deleting the largest arc connecting the clusters. The chaining algorithm thus proposed will iteratively solve an out-of-kilter problem and at each iteration store all valid

Figure 5. Example of A Solution Generated in the Chaining Network



chains as columns for the set covering model. By increasing the λ_i for the violated trips on invalid chains, new solutions to the algorithm will be generated during the next iteration. The idea behind increasing the λ_i , of course, is to make clusters violating the one trip constraint less desirable. The λ_i will be increased until all clusters contained trip i (except possibly one) are driven from the chain.

Consider an example of this method. Figure 6 represents twelve clusters that are available upon termination of the clustering routine. The trips within each cluster are shown in Table 2 and the costs of traveling from one cluster to another (along with the benefits of servicing each cluster) is shown in Table 3.

Initially, the problem was solved using $\lambda_i = 0$ for every i and a return arc of 1, with the result shown in Figure 7. As can be seen, a chain of $x_{12} \rightarrow x_8 \rightarrow x_6 \rightarrow x_2 \rightarrow x_1$ was formed. This is not, however, a valid chain since trip 6 is contained in both cluster 6 and cluster 2. If a return arc constraint of two is used (Figure 8) two paths are generated, neither of which constitutes a valid chain. It will be noted, however, that the raising of the lower bound decreased the value of the objective function, thus increasing the benefits. If this were not the case, it would indicate that the chains being added (or augmented) were not particularly good ones. Taking the simpler case of only one conflict (with the return arc constraint of 1), we increase the value of λ_6 to 5 (since 6 is the violated trip) and resolve the conflict. Figure 9 indicates that two chains are formed, with one a negative flow circuit. Since neither path contains any conflicts, two valid chains have been generated. Their corresponding set cover columns are: $[0,0,0,0,0,0,0,1,0,0,1,1,0,1,0,1]^t$ for the negative flow circuit of $x_8 \rightarrow x_9 \rightarrow x_{12}$ and $[1,1,1,1,0,1,1,0,0,0,0,0,0,0,0,0]^t$ for $x_2 \rightarrow x_1$. Computing

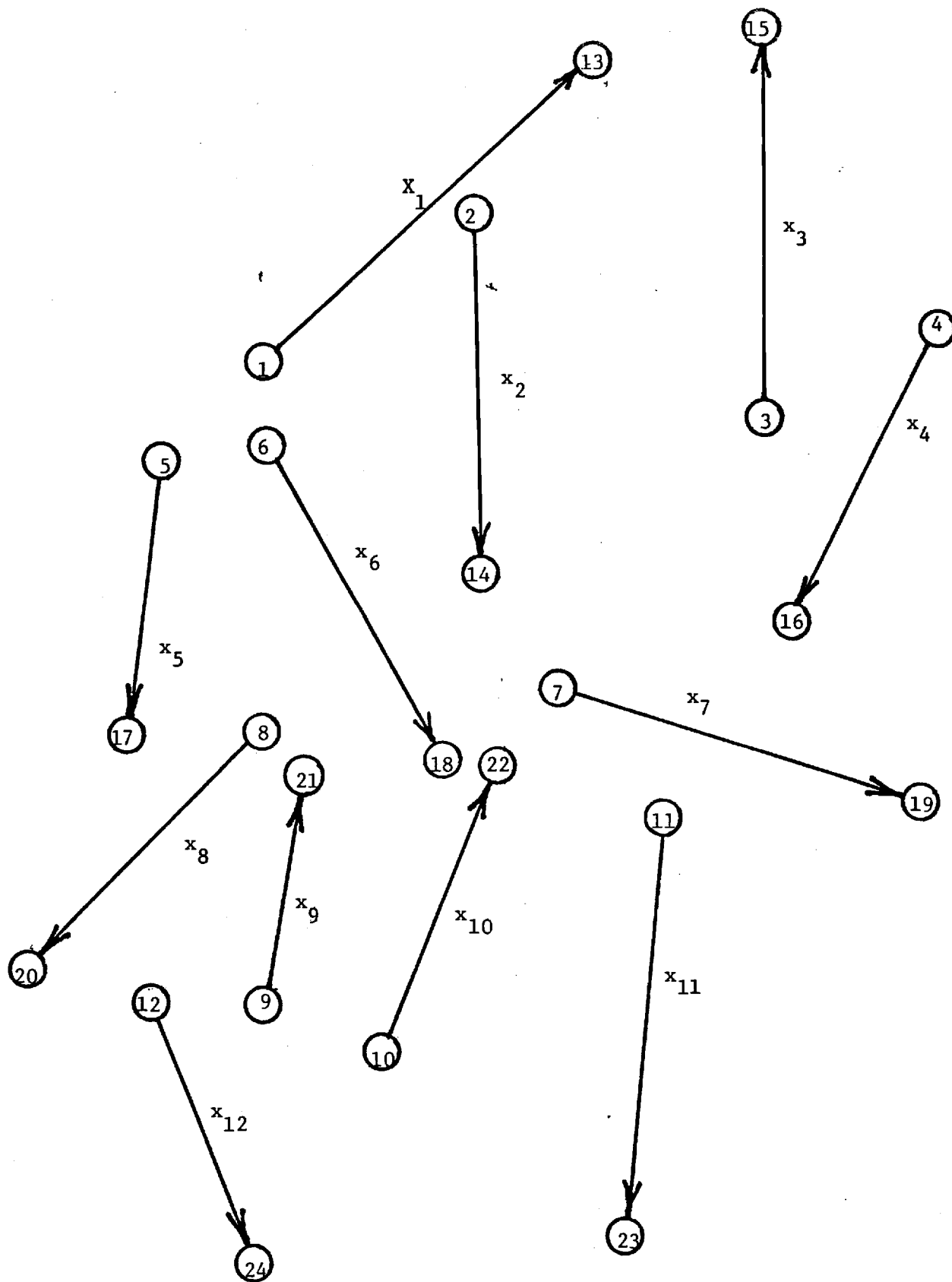


Figure 6. Twelve Clusters Available for Chaining

TRIP	CLUSTER
1	1
2	2
3	1,3
4	1,3
5	4
6	2,5,6
7	2,4
8	5,8
9	6,7
10	7,11
11	8
12	9,10
13	10
14	12
15	11
16	12

CLUSTER	TRIP
1	1,3,4
2	2,6,7
3	3,4
4	5,7
5	6,8
6	6,9
7	9,10
8	8,11
9	12
10	12,13
11	10,15
12	14,16

Table 2 Correspondence Between Trips and Clusters

BEGIN NODE	END NODE	COST
1	13	-13
14	1	7
15	1	12
18	1	17
2	14	-16
13	2	10
15	2	11
18	2	7
3	15	-9
14	3	11
18	3	21
19	3	23
4	16	-7
15	4	7
19	4	8
23	4	9
5	17	-9
20	5	4
18	5	10
21	5	10
6	18	-8
19	6	5
20	6	6
23	6	8
7	19	-5
15	7	15
16	7	15
23	7	8
8	20	-9
21	8	8
22	8	11
24	8	5
9	21	-2
20	9	3
22	9	9
24	9	9
10	22	-7
19	10	4
21	10	10
23	10	7
11	23	-6
21	11	14
22	11	10
24	11	17
12	24	-7
20	12	18
21	12	9
23	12	9

Table 3 Travel Cost Between Clusters

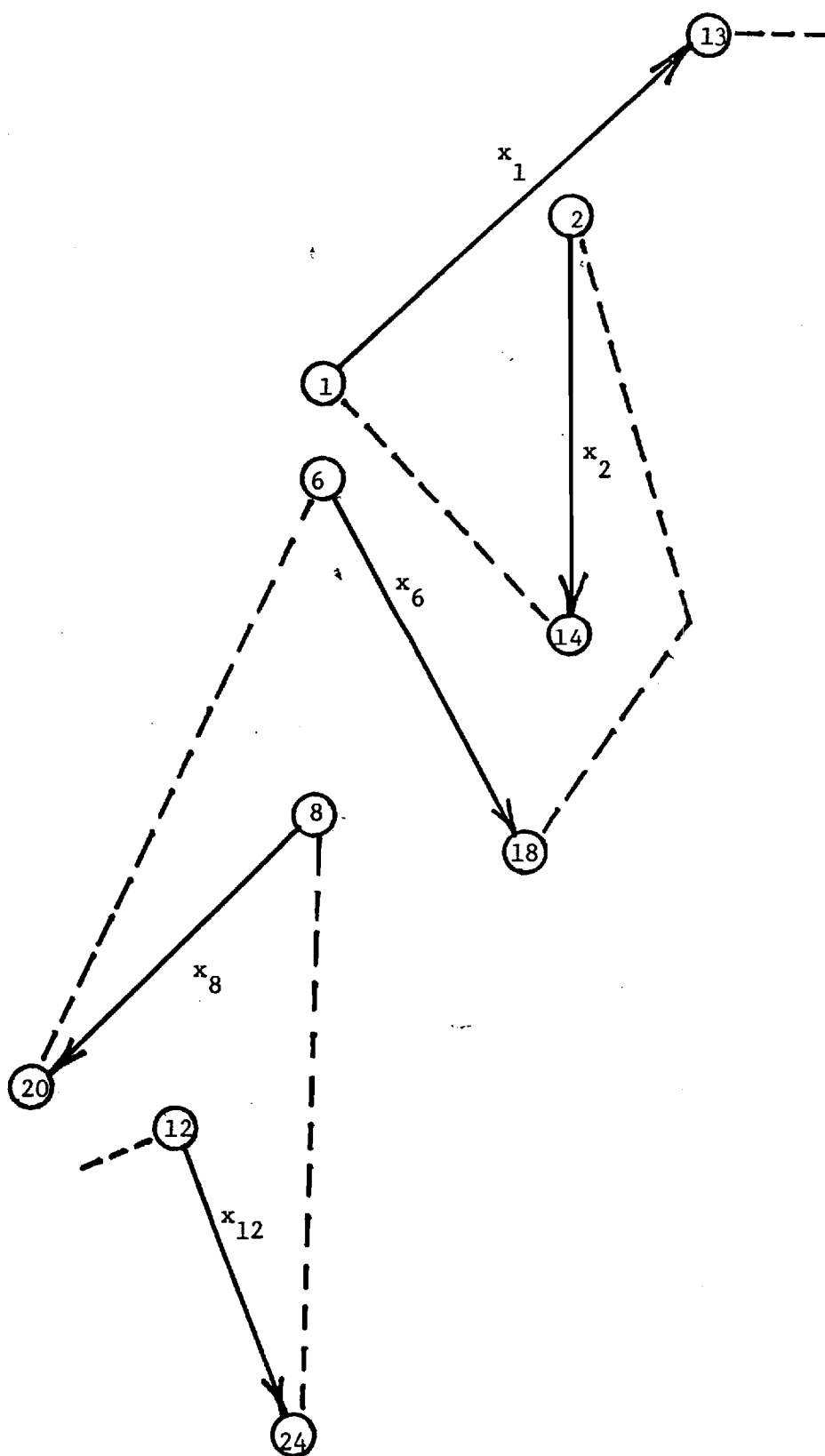


Figure 7. Example of a Chain Through the Clusters

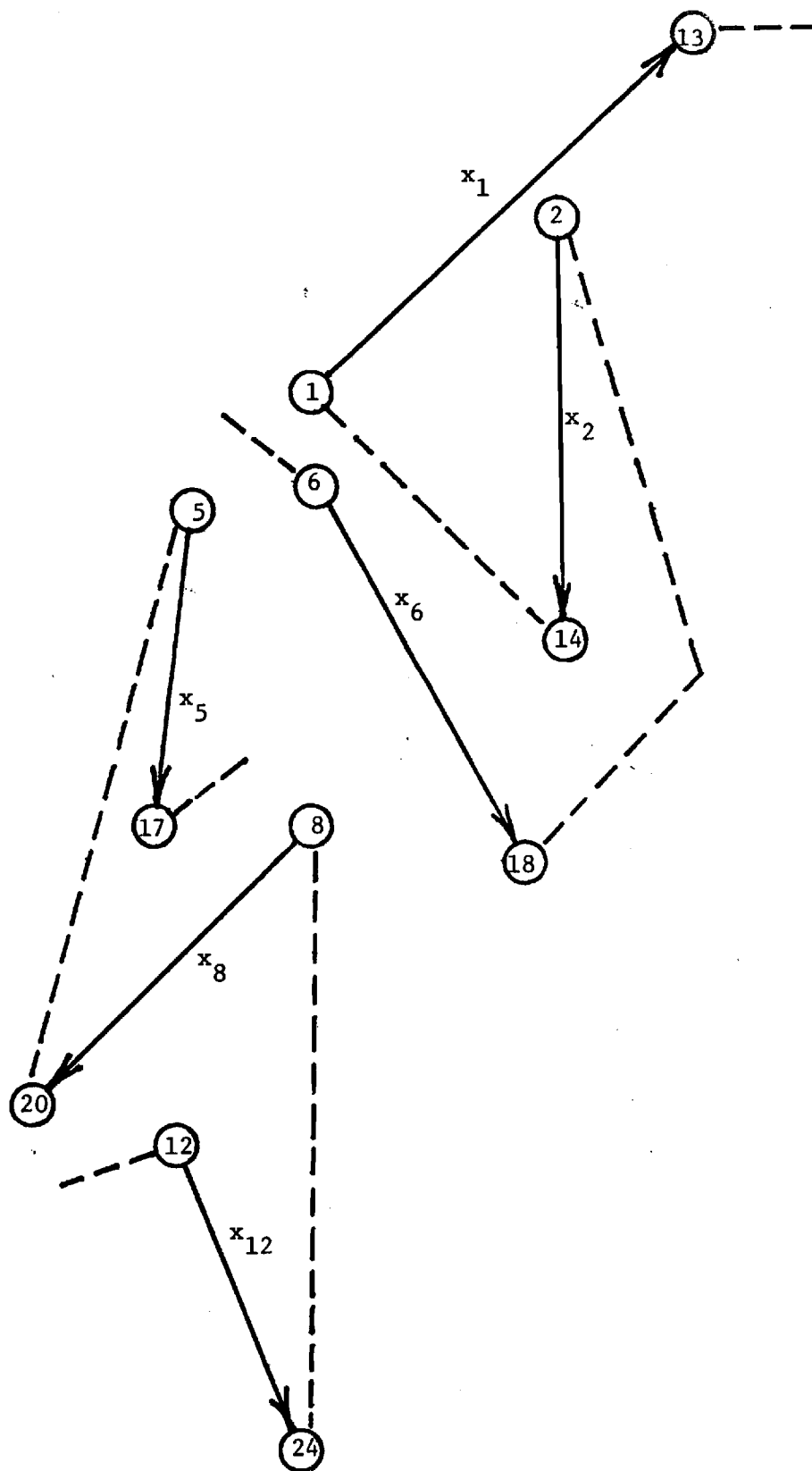
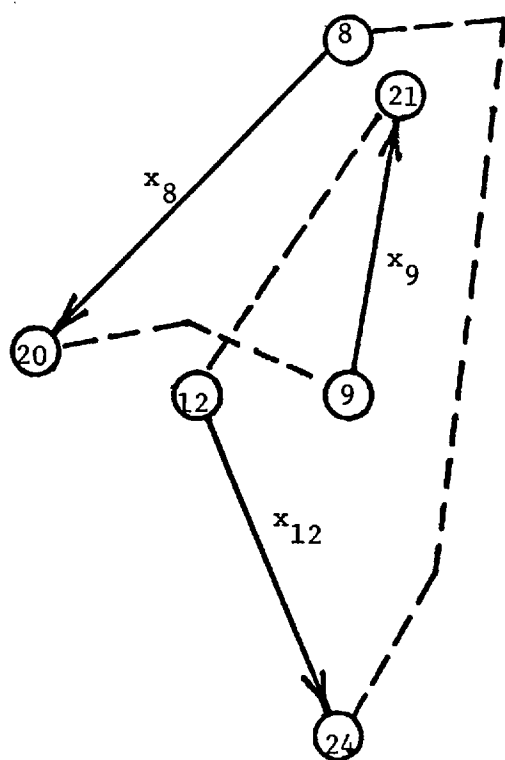
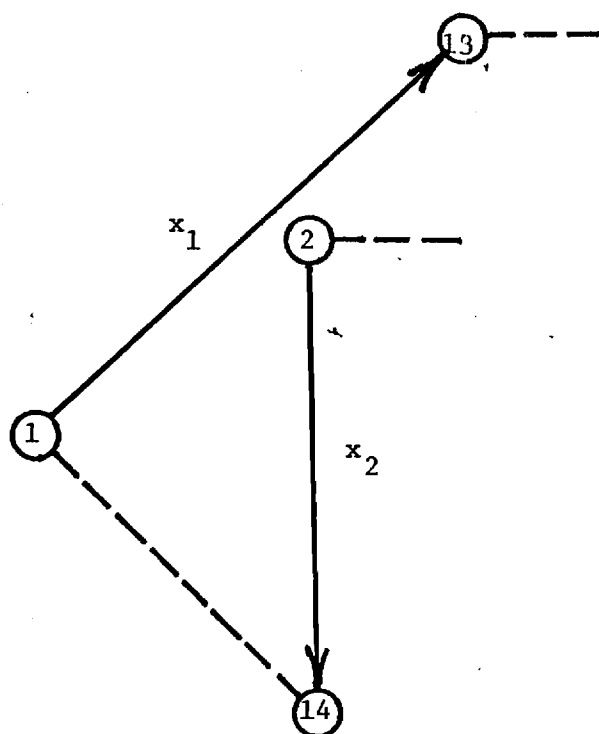


Figure 8. The Network Flow Solution for a Two Chain Requirement

Figure 9. The Network Flow Solution for $\lambda_c = 5$

the reduced costs for $x_2 \rightarrow x_1$ the path is source \rightarrow node 2 \rightarrow node 14 \rightarrow node 1 \rightarrow node 13 \rightarrow sink and its reduced cost is $0 + (-16) + 7 + (-13) + 0 = -22$. Similarly, for $x_8 \rightarrow x_9 \rightarrow x_{12}$ the reduced cost is $(-9) + 3 + (-2) + 9 + (-7) + 5 = -1$. Now the most expensive arc of cost 9 is deleted (eliminating the circuit). Thus, the true reduced cost is $-1 - 9 = -10$.

An alternate way to approach this problem is to increase only those costs corresponding to clusters containing violated trips. Thus, in Figure 7, where clusters 6 and 2 both contained trip 6, only those two clusters would be increased by 5 (in the Lagrangean relaxation approach all clusters containing trip 5 would be penalized, whether they are in the basis or not). The difference will be noted in Figure 10. Now there is a conflict in path 2 which contains clusters 12, 8 and 5. If the costs for cluster 5 had been penalized for having trip 6 (as was done in Figure 8), the cluster would not have entered into the basis, thus avoiding the conflict. More generally, penalizing only the violated clusters goes against the very spirit of the method developed, since it only addresses selected members of the A'' matrix.

Finally, the lower bound is raised from 1 to 2 in the final model (with $\lambda_6 = 5$). This breaks up the negative flow circuit (Figure 11) and generates a new column $x_{12} \rightarrow x_8$ which is a proper subset of the column generated by the negative flow circuit. Since its reduced cost is $(-7) + 5 + (-9) = -11$ and it is not dominated by the negative flow cycle column, it is a valid column.

Summarizing the example, there were three valid columns added to the partitioning model for the clusters presented. By varying other parameters (such as lower bounds of each cluster, which could be made 1 to force inclusion in the basis), a number of other possibly valid columns could be generated.

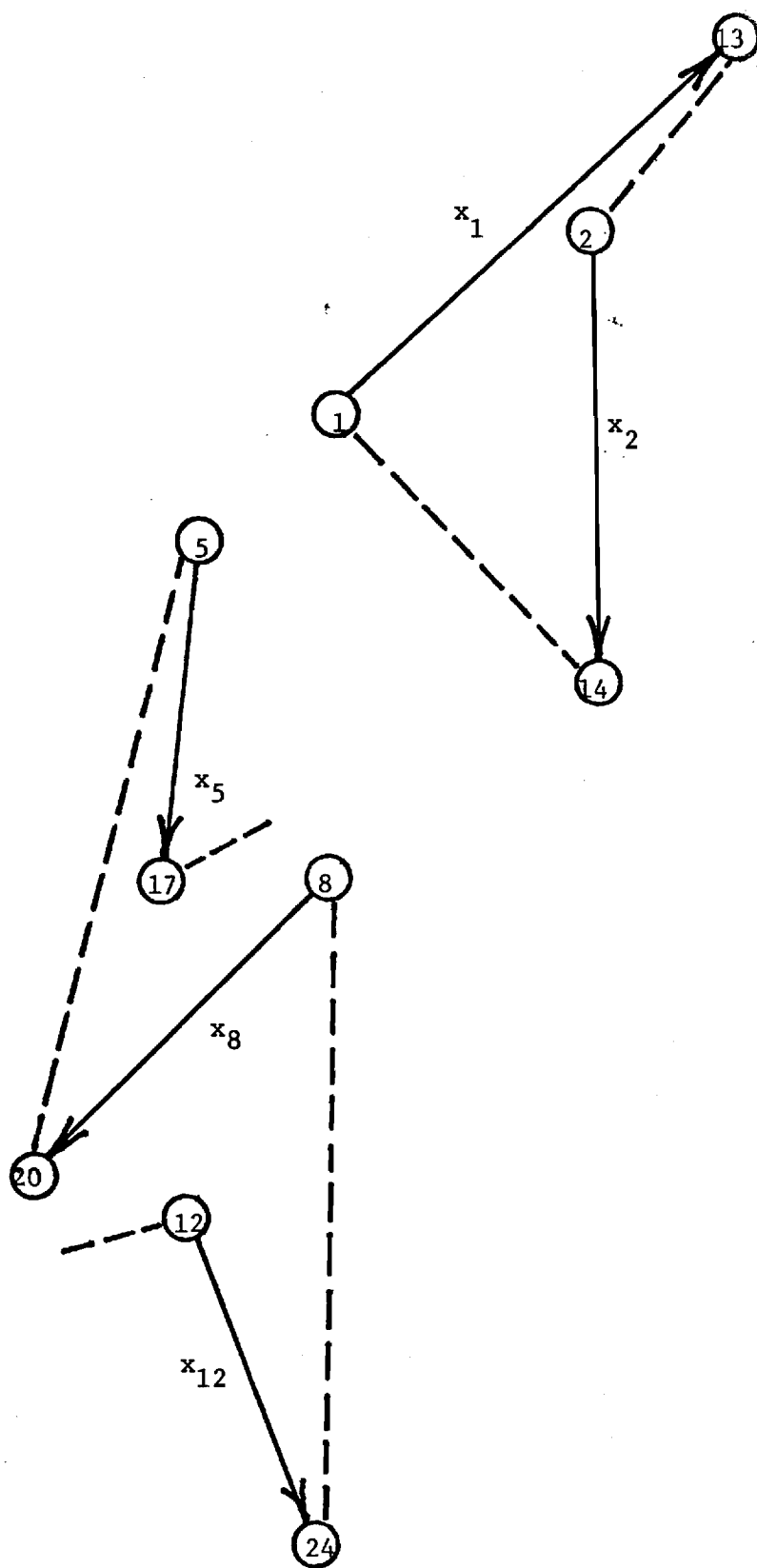


Figure 10. The Network Flow Solution When Only Certain Clusters Containing Trip 6 Are Penalized by 5.

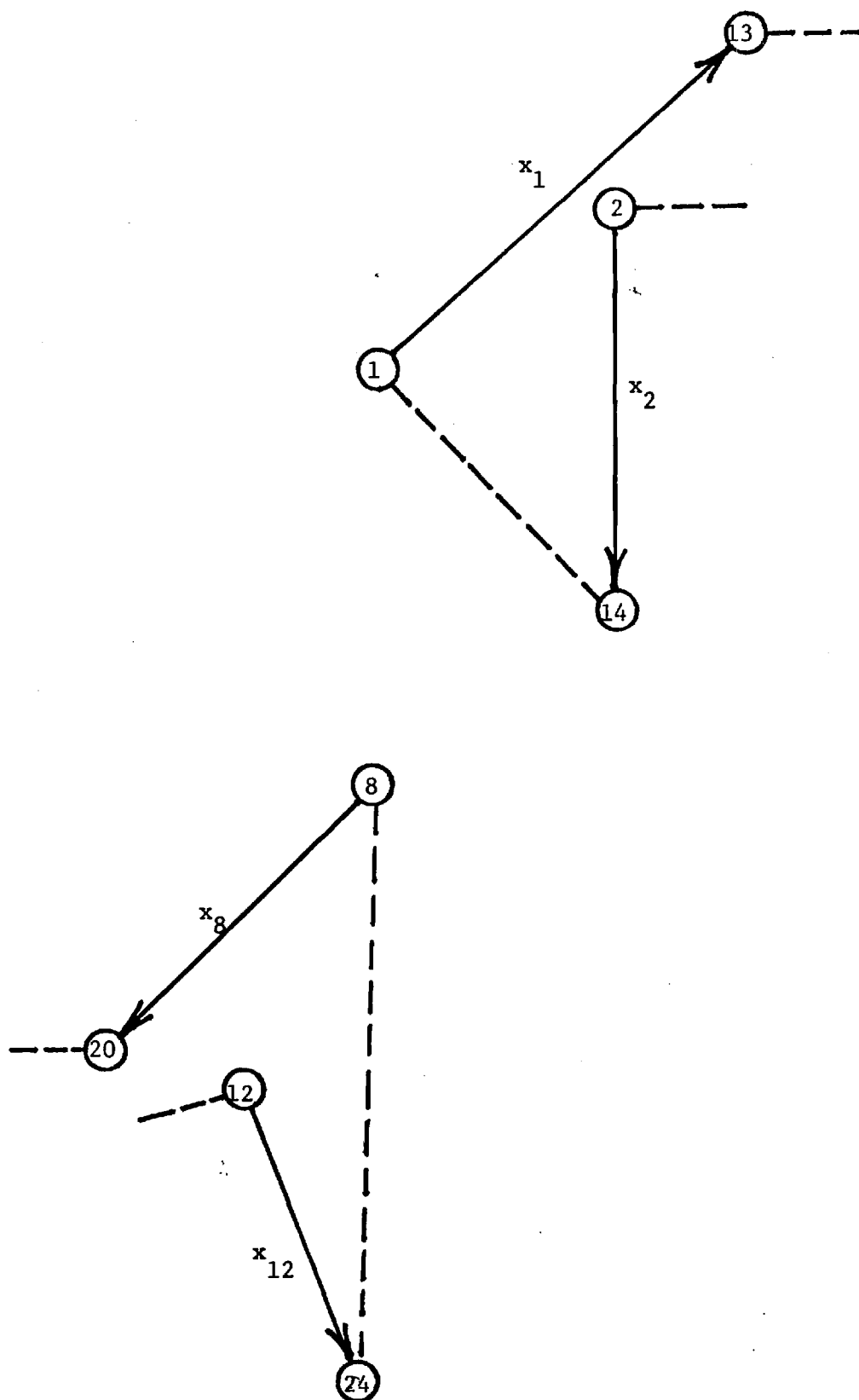


Figure 11. The Network Flow Solution
for A Two Chain Requirement With $\lambda_6 = 5$

It will be noted that it was not explained by how much λ_1 should be incremented so as to drive the violated clusters out of the basis. This problem will be addressed later on in the extensions section. For the time being, let it just be noted that for some nonnegative value of λ a "better" solution may be determined.

4. OTHER MODELS FOR CHAINING

It has also been suggested that a shortest path algorithm might be used to address the problem of chaining. The mathematical formulation of the shortest path problem is

$$\begin{aligned}
 &\min \quad cx \\
 &\text{s.t.} \quad \sum_{j=1}^m x_{ij} - \sum_{k=1}^m x_{ki} = \begin{cases} 1 & \text{if } i = 1 \\ 0 & \text{if } i \neq 1 \text{ or } m \\ -1 & \text{if } i = m \end{cases} \\
 &\quad \quad \quad x_{ij} = 0, 1 \quad i, j = 1, 2, \dots, m
 \end{aligned}$$

As can be seen, this is a special case of the out-of-kilter algorithm, with the return arc restricted to one. Since the general case is the more useful one here, the intuitive approach of using the shortest path algorithm will not be considered further.

5. EXTENSIONS

The first extension which will be discussed is calculation of "good" values for the Lagrangian multipliers. A good value, in this context, constitutes a value which will drive at least one violated cluster from the basis. To do this, the dual variables arrived at in the termination of the out-of-kilter algorithm were examined. Considering the example previously analyzed, after the first iteration (with all $\lambda_i = 0$) there was one conflict, which arose because clusters 2 and 6, both elements of the basis, both contain trip 6. The dual variables are shown in Table 4. The reduced cost for each cluster appears in Table 5 for six values of λ_6 . It will be noticed that if the reduced cost is less than zero, the arc is at its lower bound; similarly, if the reduced cost is greater than zero, the arc is at its upper bound. If the reduced cost is zero, however, the out-of-kilter algorithm states that an arc could be at its lower bound or upper bound thus (as evidence by the data in Table 5) there is no obvious way to find the minimum λ needed to change the basis. There is, however, a strong chance that further research in this area will yield a method for calculating the Lagrangian multipliers which is superior to the haphazard method previously employed.

Another possible extension of the Lagrangian multiplier method outlined is investigation into the possibility that a certain circumstance or set of circumstances might cause the upper bound on the return arc to be varied. Since this upper bound constraint does effect the chains produced (as shown in the previous example), it is possible that a certain upper bound or sequence of upper bounds, should be used to generate chains.

A second, more general, extension that should be pursued is the incorporation of time constraints into the model. This would most likely be done through the use of time slices on, for example, an hour-by-hour basis. The

<u>NODE</u>	<u>PI</u>
1	11
13	0
14	4
15	1
18	3
2	10
3	11
19	6
4	8
16	1
23	3
5	9
17	0
20	5
21	3
6	11
7	11
8	11
22	1
24	6
9	8
10	10
11	11
12	11
25	11
26	0

Table 4 Dual Variables for the OOK Solution

		λ_6					
		<u>0</u>	<u>1</u>	<u>2</u>	<u>3</u>	<u>4</u>	<u>5</u>
	1	(2)	(3)	(3)	(4)	(4)	(3)
	2	(10)	(8)	(7)	(6)	(5)	(4)
	3	-1	-1	-1	0	0	-1
C	4	0	0	0	0	0	0
L	5	0	0	0	(0)	(0)	0
U	6	(0)	(0)	(0)	-1	-1	0
S	7	0	0	0	0	0	0
T	8	(3)	(3)	(2)	(2)	(1)	(0)
E	9	-3	-3	-2	-2	-1	0
R	10	-2	-2	-2	-1	-1	-2
	11	-2	-2	-2	-2	-2	-2
	12	(2)	(2)	(2)	(2)	(2)	(1)

Smallest value of λ_6 which eliminates multiple trip within one cluster. \therefore

$$\lambda_6^* = 3$$

○ indicates elements of basis, i.e. flow is one.

Table 5. Reduced Costs for Various Values of λ_6

clustering would then be done on an hour-by-hour basis so the chaining would be forced to take into account these time precedent relationships. While this has not been addressed in the chaining study thus far, it remains a worthwhile topic for future study.

Another possibility for chaining is to utilize a savings approach similar to that described in [1]. The development of such an approach would follow directly from the method described there.

6. CONCLUSIONS

Futher development and testing of several methods will be required before definitive conclusions can be drawn about chaining, in both theory and practice.

7. REFERENCES

1. Cullen, F. H., J. J. Jarvis, and H. D. Ratliff, "Set Partitioning Based Heuristics for Interactive Routing," School of Industrial and Systems Engineering Report Series #J-80-1, Georgia Institute of Technology (1980).
2. Jarvis, J. J., H. D. Ratliff, and R. T. Lewis, "Clustering in the Dial-A-Ride Vehicle Routing Problem," School of Industrial and Systems Engineering Report Series #J-80-15, Georgia Institute of Technology (1980).

APPENDIX B

COMPUTER PROGRAMS

B-1

Chromatics (BASIC)
Data Generating Program for
Dial-A-Ride

```

100 NM="MENU2"
105 PRINT CHR$(12):
110 GOSUB 2000
120 GOSUB 2300
130 DIM PMENU(PX,5)
140 FOR I=1 TO MX
150 FOR J=1 TO 5
160 PMENU(I,J)=MENU(I,J)
170 NEXT J
180 NEXT I
185 PX=MX
190 ERASE MENU,M0,HDMENU
200 NM="MENU1"
210 GOSUB 2000
220 GOSUB 2300
230 PRINT "-G-C7+0,0,511511":
240 PRINT "-C,400511400350400350511":
250 DIM NH(50,5)
260 OUT&H90,0
270 ON ERROR#2 GOTO 1000
280 GOTO 910
1000 REM *** LIGHT PEN INTERRUPT ROUTINE
1010 X=CURSX(4)
1020 Y=CURSY(4)
1030 IF Y < 400 THEN GOTO 5000
1040 IF X > 350 THEN GOTO 3000
1050 GOSUB 2700
1070 OUT&H90,0
1080 RESUME
2000 REM *** COLOR MENU READ-IN ROUTINE
2010 DOS"CFER 5 R "+NM
2020 INPUT #5: MX,SMX
2030 DIM MENU(PX,5),MH(SMX),HDMENU(SMX,3)
2040 FOR I=1 TO MX
2050 INPUT #5: MENU(I,1),MENU(I,2),MENU(I,3),MENU(I,4),MENU(I,5)
2060 NEXT I
2061 IF SMX = 0 THEN GOTO 2070
2062 FOR I = 1 TO SMX
2064 INPUT #5: HDMENU(I,1),HDMENU(I,2),HDMENU(I,3),MH(I)
2066 NEXT I
2070 DOS"CLOSE 5"
2080 RETURN
2300 REM *** MENU DRAW ROUTINE
2310 PRINT "-G-K":
2320 FOR I=1 TO MX
2330 PRINT "-F-C":
2340 PRINT USING "#":MENU(I,5);
2350 PRINT "+":
2360 PLOT MENU(I,1),MENU(I,2),MENU(I,3),MENU(I,4)
2362 PRINT "-C7-L+":
2364 PLOT MENU(I,1),MENU(I,2),MENU(I,3),MENU(I,4)
2370 NEXT I
2380 PRINT CHR$(21):
2395 IF SMX=0 THEN RETURN
2400 FOR I = 1 TO SMX
2410 PRINT "-G-U":
2420 PLOT HDMENU(I,1),HDMENU(I,2)
2430 PRINT "-C":
2440 PRINT USING "#": HDMENU(I,3):
2450 PRINT CHR$(21):MH(I):
2460 NEXT I
2470 RETURN
2500 REM *** MENU LOCATE ROUTINE
2502 PRINT CHR$(27):"OA1": "-W351401510510":8":CHR$(12):"-F":CHR$(27):"OA0":

```



```

7030 FLOW
7040 PRINT CHR$(7)
7050 GOTO 1070
7100 MN=MN+1
7110 IF MN
7120 PRINT CHR$(7)
7150 NW(I,1)=E1: NW(I,2)=E1: NW(I,3)=X: NW(I,4)=Y: NW(I,5)=0
7160 GOSUB 4000
7170 B1=0
7180 GOTO 1070
8000 REM *** SAVE ROUTINE
8010 DOS"OPEN 6 N+.DOS"
8012 MT=0
8014 FOR I=1 TO MN
8016 IF NW(I,5) <> 0 THEN MT=MT+1
8018 NEXT I
8020 PRINT #6: USING "##": MT
8030 IF MN=0 THEN GOTO 8120
8040 FOR I=1 TO MN
8050 IF NW(I,5)=0 THEN GOTO 8110
8060 FOR J = 1 TO 4
8070 PRINT #6: USING "###": NW(I,J):
8080 PRINT #6: ", "
8090 NEXT J
8100 PRINT #6: USING "#": NW(I,5)
8110 NEXT I
8115 PRINT #6: CHR$(30)
8120 DOS "CLOSE 6 NETSAVE"
8125 PRINT CHR$(27):"OA1~W1,401349510~:6":CHR$(12):CHR$(27):"OA0~:F":
8130 RETURN
9000 REM *** REDRAW ROUTINE
9010 PRINT CHR$(27):"OA1~W1,1,510399":CHR$(12):CHR$(27):"OA0~:
9020 DOS"OPEN 6 R NETSAVE"
9030 INPUT #6: MN
9040 IF MN=0 THEN GOTO 9090
9050 FOR I = 1 TO MN
9060 INPUT #6: NW(I,1),NW(I,2),NW(I,3),NW(I,4),NW(I,5)
9070 GOSUB 4000
9080 NEXT I
9090 DOS "CLOSE 6"
9095 PRINT CHR$(27):"OA1~W1,401349510~:6":CHR$(12):CHR$(27):"OA0~:F":
9100 RETURN
9500 REM *** CLEAR ROUTINE
9510 MN=0
9520 PRINT CHR$(27):"OA1~W1,1,510399":CHR$(12):CHR$(27):"OA0~:
9525 PRINT CHR$(27):"OA1~W1,401349510~:6":CHR$(12):CHR$(27):"OA0~:F":
9530 RETURN

```

6,7, NETWORK GENERATION PRIMARY MENU

9,430,45,480,7

59,430,95,480,7

109,430,145,480,7

159,430,195,480,7

209,430,245,480,7

259,430,295,480,7

16,425,2,"ADD"

57,425,4,"DELETE"

112,425,6,"SAVE"

156,425,3,"REDRAW"

200,425,5,"CHANGE"

262,425,1,"CLEAR"

70,502,7,"DIAL-A-RIDE NETWORK GENERATION"

604NETWORK GENERATION PRIMARY MENU 02

B-2

Chromatics (BASIC)
Display and Data Manipulation
Programs and Menu Data Sets for
Dial-A-Ride

```

90 GOTO 400
92 RP=0
94 PRINT CHR$(27) ; "OIA" ; CHR$(27) ; "IA4" ; CHR$(27) ; "FO-" ;
95 CH=0
100 PRINT "F1" ; CHR$(12) ; "16707+0.0511511" ; "110113412740408398511" ;
110 F1="HEADOFF" : GOSUB 4300
115 M=1 : F1=0 : F2=0 : GOSUB 4400
120 M=F1 : F1=0 : F2=0
130 GOSUB 4500
135 OUTP=0
140 ON ERROR GOTO 500
150 OUTP=0
160 GOTO 150
500 REM *** PAIN ISRU ROUTINE
505 X=CURSX(4) : Y=CURSY(4)
510 GOSUB 4000
520 IF M=0 THEN RESUME 150
530 F1=M
540 F2=0
550 PRINT "M1,401349510" ; CHR$(12) ;
560 M=0
564 IF F1<>4 THEN GOSUB 4500
570 M=F1+1
575 IF F1=4 THEN M=M+1
580 GOSUB 4500
590 IF F1=1 THEN GOTO 5920
592 IF F1=2 THEN GOTO 6900
593 IF F1=3 THEN GOTO 7900
594 IF F1=4 THEN GOTO 9000
595 OUTP=0
600 RESUME
1000 REM *** MID-RUN RESTART
1005 CLEAR 400
1010 RP=1
1020 GOTO 94
2000 REM *** TRANSMISSION ROUTINES
2100 REM *** XMIT/INIT
2110 ON ERROR GOTO 0
2199 RETURN
2200 REM *** XMIT/COMPLETE
2210 PRINT CHR$(27) ; "CAF" ; CHR$(27) ; "IA4" ;
2215 Z=0 : "THIS IS A DUMMY STATEMENT"
2220 PRINT CHR$(27) ; "OAO" ; CHR$(27) ; "IA0" ;
2230 RETURN
2300 REM *** RECEIVE/INIT
2310 ON ERROR GOTO 0
2320 PRINT CHR$(27) ; "CAF" ; CHR$(27) ; "IA4" ;
2330 Z=0 : "THIS IS A DUMMY STATEMENT"
2340 PRINT CHR$(27) ; "IA0" ;
2350 RETURN
2400 REM *** RECEIVE/COMPLETE
2410 PRINT CHR$(27) ; "IA4" ;
2420 PRINT CHR$(27) ; "IA0" ; CHR$(27) ; "OAO" ;
2430 RETURN
2500 REM *** TALLY ACTIVE TRIPS
2510 TY=0
2520 FOR L=1 TO NT
2530 IF TAIL(L)=1 THEN TY=TY+1
2540 NEXT L
2550 RETURN
2600 REM *** XMIT ACTIVE TRIP NUMBERS
2610 FOR L=1 TO NT
2620 IF TAIL(L)=0 THEN 2650
2630 PRINT #4 ; " " ;

```

```

2660 PRINT "CLUSTERING " & NT & "L";
2665 NEXT L
2670 RETURN
2670 REM *** TALLY ACTIVE CLUSTER TRIPS
2675 TV=0
2680 FOR L=1 TO NT
2685 IF YACL=L AND TC(L,2)=CN THEN TV=TV+1
2690 NEXT L
2695 RETURN
2700 REM *** XMIT ACTIVE CLUSTER TRIP ALONGS
2705 FOR L=1 TO NT
2710 IF YACL=L OR TC(L,2)<>CN THEN 2725
2715 PRINT #4: ", "
2720 PRINT #4: USING "##":L
2725 NEXT L
2727 PRINT CHR$(12):"C6ACTIVE CLUSTER XMITTED"
2730 RETURN
2800 REM *** XMIT NETWORK ON INITIATE
2802 PRINT "W391401510510":CHR$(12):CHR$(12):"C6SGIN XMIT ":NT:" TRIPS"
2805 GOSUB 2100
2810 PRINT #4:1
2812 PRINT "7005":
2815 GOSUB 2200
2820 ON ERROR#3 GOTO 2830
2825 GOTO 2825
2830 RESUME 2835
2835 GOSUB 2100
2840 PRINT #4: 1: ", ":NT: ", ":
2845 FOR I=1 TO NT
2850 FOR J=1 TO 4
2852 PRINT #4: USING "##": TP(I,J):
2854 XX=I MOD 5:IF J=4 AND (XX=0 OR I=NT) THEN 2856
2855 PRINT #4: ", ":GOTO 2857
2856 PRINT #4: " "
2857 NEXT J
2862 IF XX<>0 AND I<>NT THEN NEXT I
2867 PRINT "7005":
2865 GOSUB 2200
2870 ON ERROR#3 GOTO 2880
2875 GOTO 2875
2880 RESUME 2885
2885 ON ERROR#3 GOTO 0
2887 PRINT "C6TRIP ":I:" XMITTED"
2890 NEXT I
2895 PRINT "C4XMIT COMPLETE7010":CHR$(12):"G";
2897 ON ERROR#0 GOTO 0
2900 RETURN
3000 REM *** INITIALIZE
3010 DOS"OPEN 5 R NETSAVE"
3020 INPUT #5: NT
3030 DIM TP(NT,4),TC(NT,2),TA(NT),CK(20)
3040 FOR I=1 TO NT
3050 INPUT #5:TP(I,1),TP(I,2),TP(I,3),TP(I,4),TC(I,1)
3060 TC(I,2)=TC(I,1)
3070 NEXT I
3080 DOS"CLOSE 5"
3085 IF RR=0 THEN GOSUB 2200
3087 PRINT "G":
3090 PRINT "WC,0,511511~:8":CHR$(12):"AF":
3095 GOSUB 5100
3100 RETURN
3200 REM *** MACRO - LOCATE TRIP
3210 TR=0:NT=0
3220 FOR J=1 TO NT

```



```

3250 IF ABS(X-TP(I,1))>5 AND ABS(Y-TP(I,2))>5 THEN 3260
3260 IF ABS(X-TP(I,3))>5 OR ABS(Y-TP(I,4))>5 THEN 3260
3270 RETURN
3280 PRINT CHR$(7);RETURN
3290 NEXT I
3300 RETURN
3310 REM *** MACRO - DRAW X YIP (TYPE I, COLOR C)
3320 PRINT "X";
3330 PRINT USING "X":
3340 PRINT "Y";
3350 PLOT TP(I,1)-5,TP(I,2)-5,TP(I,3)+5,TP(I,4)+5
3360 PRINT "L";
3370 PLOT TP(I,3)-5,TP(I,4)-5,TP(I,3)+5,TP(I,4)+5
3380 PRINT "X";
3390 PLOT TP(I,1),TP(I,2),TP(I,3),TP(I,4)
3400 RETURN
3410 REM *** MACRO - DRAW CLUSTER (CLUSTER CN, COLOR C)
3420 AT=0
3430 PRINT "C";
3440 PRINT USING "X":C:
3450 FOR I=1 TO NT
3460 IF TC(I,2)<>CN THEN 3470
3480 IF C=0 THEN TA(I)=-1
3490 IF TA(I)<>0 THEN GOSUB 3490:AT=AT+1
3500 IF TA(I)=-1 THEN TA(I)=0
3510 NEXT I
3520 RETURN
3530 REM *** MACRO - LOCATE CLUSTER
3540 CN=0
3550 IF Y>400 THEN GOTO 3560
3570 GOSUB 3200
3580 IF TN=0 THEN RETURN
3590 CN=TC(TN,2)
3600 C=TC(TN,1)
3610 RETURN
3620 REM LOCATE CLUSTER FROM COLOR
3630 K=K+1
3640 IF K>NT THEN K=0:MJ=0:RETURN
3650 IF TC(K,1)<>C OR TA(K)=0 THEN 3660
3670 IF MJ=0 THEN 3680
3690 FOR J=1 TO MJ
3700 IF TC(K,2)=CK(J) THEN GOTO 3710
3720 NEXT J
3730 MJ=MJ+1:CK(MJ)=TC(K,2)
3740 CN=TC(K,2)
3750 C=TC(K,1)
3760 RETURN
3770 REM *** MACRO - LOCATE ITEM CN MENU (MENU M)
3780 MI=0
3790 FOR I=1 TO MX(M)
3800 IF X<MENU(M,I,1) OR X>MENU(M,I,3) THEN 3810
3820 IF Y<MENU(M,I,2) OR Y>MENU(M,I,4) THEN 3810
3830 GOTO 3840
3840 NEXT I
3850 RETURN
3860 MI=1:PRINT CHR$(7)
3870 IF M<>0 THEN 3880
3890 PRINT "X";CHR$(12);"Y":
3900 GOTO 3910
3910 PRINT "X";CHR$(12);"Y":
3920 PRINT "L";
3930 PLOT MENU(M,I,1),MENU(M,I,2),MENU(M,I,3),MENU(M,I,4)
3940 PRINT "X";
3950 RETURN

```

```

4390 REM *** COLOR MENU READ-IN ROUTINE
4392 PRINT CHR$(21)
4394 HOLDOPEN 5 R "F"
4396 INPUT #5: M
4398 DIM MVAL (M, 1, 4), M2 (M, 12), MVAL2 (M, 12, 3), MX (M), SMX (M)
4400 FOR K=0 TO M
4402 INPUT #5: MX(K), SMX(K)
4404 M2=MX(K)
4406 FOR I=1 TO XX
4408 INPUT #5: MENU(K, I, 1), MENU(K, I, 2), MENU(K, I, 3), MVAL(K, I, 4), MENU(K, I, 5)
4410 NEXT I
4412 XX=SMX(K)
4414 IF XX = 0 THEN 4460
4416 FOR I = 1 TO XX
4418 INPUT #5: HDMENU(K, I, 1), HDMENU(K, I, 2), HDMENU(K, I, 3), M2(K, I)
4420 NEXT I
4422 NEXT K
4424 DO$="CLOSE 5"
4426 RETURN
4428 REM *** MENU DRAW ROUTINE
4430 PRINT "GK":
4432 FOR I=1 TO MX(M)
4434 PRINT "FC":
4436 PRINT USING "M:MENU(M, I, 5)":
4438 PRINT "M":
4440 PLOT MENU(M, I, 1), MENU(M, I, 2), MENU(M, I, 3), MENU(M, I, 4)
4442 PRINT "C7L4":
4444 PLOT MENU(M, I, 1), MENU(M, I, 2), MENU(M, I, 3), MENU(M, I, 4)
4446 NEXT I
4448 PRINT CHR$(21):
4450 IF SMX(M)=0 THEN RETURN
4452 FOR I = 1 TO SMX(M)
4454 PRINT "GU":
4456 PLOT HDMENU(M, I, 1), HDMENU(M, I, 2)
4458 PRINT "C":
4460 PRINT USING "M: HDMENU(M, I, 3)":
4462 PRINT CHR$(21):M2(M, I):
4464 NEXT I
4466 PRINT "G":
4468 RETURN
4470 REM **** EDIT FUNCTIONS
4472 IF Y<400 THEN 5060
4474 IF X<350 THEN K=0:HJ=0:PRINT "78W350400511511":CHR$(12):"F":
4476 IF X<350 THEN M=2:GOSUB 4000:F2=M
4478 IF X>350 THEN M=0:GOSUB 4000:C=M+1
4480 ON F2 GOTO 5100, 5400, 5200, 5600
4482 IF F2=0 THEN 5900
4484 PRINT "W1,401510510":CHR$(12):"C7 350400350511":
4486 PRINT "W1,1,510400F":CHR$(12):"F":
4488 F2=0:F1=0:OUT$="20.0":RESUME 120
4490 REM *** EDIT ~ RESTORE
4492 PRINT "W1,1,510399F":CHR$(12):
4494 FOR I=1 TO NT
4496 TA(I)=1
4498 C=TC(I,1)
4500 GOSUB 3400
4502 NEXT I
4504 PRINT "W1,1,511511F":CHR$(12):"F":
4506 F2=0
4508 IF F1=0 THEN RETURN
4510 GOTO 5900
4512 REM *** EDIT ~ SUBROUTINE
4514 IF Y<400 THEN 5230
4516 PRINT "78W1,1,511400":CHR$(12):"F":

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5270 GOTO 5900
5280 PRINT "7:4TW1,1,511400";CHR$(12);"";F":
5290 GOSUB 3200
5300 IF TA=0 THEN 5900
5310 TA(TA)=0
5320 C=0:TA=TA
5330 GOSUB 3400
5340 GOTO 5900
5350 REM *** EDIT - SQUARE CLUSTER
5360 IF Y<400 OR X>350 THEN 5500
5370 K=0
5380 PRINT "7:8TW1,1,511400";CHR$(12);"";F":
5390 GOTO 5900
5400 GOSUB 3200
5410 IF CA=0 THEN 5900
5420 C=0
5430 GOSUB 3500
5440 GOTO 5900
5450 REM *** EDIT - HIGHLIGHT CLUSTER
5460 IF Y<400 OR X>350 THEN 5700
5470 K=0
5480 PRINT "7:8TW1,1,511400";CHR$(12);"";F":
5490 MJ=0
5500 GOTO 5900
5510 GOSUB 3200
5520 IF CA=0 THEN 5900
5530 PRINT "7:8TW1,1,511400";CHR$(12);"";F~1":
5540 GOSUB 3600
5550 PRINT "2":
5560 GOTO 5900
5570 REM *** EDIT - RESET LIGHT PEN AND RESUME EDIT
5580 OUTAH=0,0
5590 RESUME 5920
5600 ON ERROR GOTO 5950
5610 OUTAH=0,0
5620 GOTO 5940
5630 X=CURSX(4):Y=CURSY(4)
5640 GOTO 5900
5650 REM *** CLUSTER FUNCTIONS
5660 IF Y<400 THEN 6050
5670 IF X<350 THEN K=0:MJ=0:PRINT "7:8TW350400511511";CHR$(12);"";F":
5680 IF X<350 THEN M=3:GOSUB 4000:F2=PI
5690 IF X>350 THEN M=0:GOSUB 4000:C=MI-1
5700 ON F2 GOTO 6200,6300,6400,6500,6600,6700
5710 IF F2=0 THEN 6900
5720 PRINT "TW1,401510510";CHR$(12);"";C7:350400350511":
5730 PRINT "TW1,1,510400";CHR$(12);"";F":
5740 F2=0:F1=0:OUTAH=1,C:RESUME 120
5750 REM *** CLUSTER - SELECT CLUSTER
5760 IF Y < 400 OR X>350 THEN 6250
5770 K=0:MJ=0:CC=0:CA=0
5780 PRINT "7:8TW1,1,511400";CHR$(12);"";TW350400511511";CHR$(12);"";F":
5790 GOTO 6900
5800 GOSUB 3200
5810 IF CA=0 THEN 6900
5820 CA=CA:CC=C
5830 PRINT "7:8TW1,1,511400";CHR$(12);"";F~1":
5840 GOSUB 3600
5850 PRINT "2":
5860 GOTO 6900
5870 REM *** CLUSTER - CREATE CLUSTER
5880 IF Y<400 THEN 6900
5890 IF X>350 THEN 6350
5900 GOTO 6900

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6390 PRINT "W1,1,510400":CHR$(12):"F"
6395 GO=0:CA=0:CN=1:OM=0
6370 GOTO 6380
6400 REM *** CLUSTER - ADD TO CLUSTER
6410 IF OC=0 THEN PRINT "W1,400300011":CHR$(12):"F":F2=0:GOTO 6390
6417 IF Y=400 THEN CN=0
6418 PRINT "W1,4003000511511":CHR$(12):"F"
6420 GOTO 6430
6430 GOSUB 3200
6440 IF TA=0 THEN 6900
6450 TC(TA,1)=0:TC(TA,2)=0A
6460 I=TA:OC=0:CN=0A
6465 PRINT "1":
6470 GOSUB 3400
6475 PRINT "2":
6480 GOTO 6900
6500 REM *** CLUSTER - DELETE FROM CLUSTER
6510 IF OC=0 THEN PRINT "W1,400300011":CHR$(12):"F":F2=0:GOTO 6900
6520 IF Y=400 THEN 6540
6525 PRINT "W1,4003000511511":CHR$(12):"F"
6530 GOTO 6900
6540 GOSUB 3200
6550 IF TA=0 THEN 6900
6555 IF TC(TA,2)<>0A THEN 6900
6560 TC(TA,1)=7:TC(TA,2)=99999:TA=7
6570 GOSUB 3400
6580 GOTO 6900
6600 REM *** REQUEST CLUSTER INFO
6602 PRINT "W1,1,510400":CHR$(12):"F"
6605 PRINT "W351401510510":CHR$(12):CHR$(21):"CABLE IN CLUSTER REQUEST"
6608 OUT$=90,0:RESUME 6610
6610 GOSUB 2100:PRINT #4:2
6611 PRINT "7005":GOSUB 2200
6612 ON ERROR#3 GOTO 6614
6613 GOTO 6613
6614 RESUME 6615
6615 GOSUB 2100
6617 INPUT "DESIRED NO OF CLSTERS":DC
6620 INPUT "VEHICLE CAPACITY":VC
6625 YC=0 "DUMMY CAPACITY = 0"
6626 GOSUB 2500
6627 IF DC*VC < TY THEN PRINT "C7 INSUFF CAP. FOR":TY:"TRIPS":GOTO 6617
6630 PRINT#4:3:,"":DC:,"":TY:,"":VC:,"":YC:GOSUB 2600
6635 PRINT #4: " ":PRINT "TRIP INFORMATION EXITED"
6640 DIM S$(TY),T$(TY)
6645 FOR J=1 TO TY
6649 GOSUB 2200:GOSUB 2200
6650 INPUT #4: S$(J),T$(J):I=T$(J):TC(I,1)=S$(J) MOD 9:TC(I,2)=S$(J)+OM
6652 IF TC(I,1)=0 THEN TC(I,1)=9
6653 PRINT "C3CLUS=":TC(I,2):"CLF=":TC(I,1):"TRP=":I
6655 NEXT J
6660 PRINT "C4CLUSTER INFO RETURNED":W1,1,510399"
6665 FOR J=1 TO TY
6670 I=T$(J):C=TC(I,1):GOSUB 3400
6675 NEXT J
6680 OM=OM+DC:GOSUB 2200:ERASE S$,T$
6685 PRINT "W351401510510":CHR$(12):"F":GOSUB 4500
6687 PRINT "G":
6688 PRINT "W1,1,510510":CHR$(12):"F"
6689 CN=0
6690 OUT$=90,0:GOTO 6930
6700 REM *** TRANSFER CLUSTER INFO
6705 PRINT "W351401510510":CHR$(12):CHR$(21):"CABLE IN CLUSTER EXIT"
6707 IF CN=0 THEN 6731

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7419 OUT&H90,0:RESUME 7420
7420 GOSUB 2100:PRINT#4:PRINT "??005":GOTO 7430
7430 ON ERROR#2 GOTO 7435
7435 GOTO 7430
7435 RESUME 7440
7440 GOSUB 2100:GOSUB 2200
7445 PRINT#4:PRINT#4,"0,0,1":GOSUB 2700:PRINT#4 " "
7455 FOR I = 1 TO 2:Y
7457 PRINT#4:"?001":GOSUB 2200:GOSUB 2200
7460 INPUT#4:RT(I)
7465 IF RT(I)>0 THEN PRINT "C3 PICKUP "RT(I)
7466 IF RT(I)<0 THEN PRINT "C3 DELIVER ":-RT(I)
7470 NEXT I
7475 TD=0:PRINT#4:"C5-G":
7480 FOR I=1 TO 2:Y
7485 Z=RT(I)
7490 IF Z<0 THEN X2=TP(-Z,3):Y2=TP(-Z,4)
7495 IF Z>0 THEN X2=TP(Z,1):Y2=TP(Z,2)
7500 IF I=1 THEN 7515
7505 TD=TD+SCR((X2-X1)^2+(Y2-Y1)^2)
7510 PRINT#4:"":PLOT X1,Y1,X2,Y2
7515 PRINT#4:"F+":PLOT X2,Y2:PRINT "005-L"
7517 X1=X2:Y1=Y2
7520 NEXT I
7525 PRINT#4:"F-1+":PLOT X2,Y2:PRINT "005-2-L-1-F":
7530 LA=2*TY:OUT&H90,0:GOTO 7532
7531 OUT&H90,0:RESUME 7532
7532 PRINT "W351401510110~F":CHR$(12):IN#5:GOSUB 4500
7535 GOSUB 7800:GOSUB 2200
7540 GOTO 8120
7600 REM *** ROUTE/ROUTE XMIT INFO
7605 PRINT "W351401510510~F":CHR$(12):CHR$(21):"C4BEGIN ROUTE XMIT"
7610 GOSUB 2670:IF ON#0 OR TY=0 THEN PRINT#4:"C4NO CLUSTER SELECTED?006":GOTO 753
7615 IF LA<2*TY THEN PRINT "C4INCOMPLETE ROUTE?008":GOTO 7531
7620 OUT&H90,0:RESUME 7625
7625 GOSUB 2100:PRINT#4:PRINT "??005":GOSUB 2200
7630 ON ERROR#3 GOTO 7640
7635 GOTO 7635
7640 RESUME 7645
7645 GOSUB 2200:GOSUB 2100:PRINT#4:"1,":PRINT#4: USING "####":TD;
7647 PRINT#4:",";TY:GOSUB 2700:PRINT#4:"~":PRINT "??005":
7650 ON ERROR#3 GOTO 7660
7655 GOTO 7655
7660 RESUME 7662
7662 GOSUB 2200
7665 GOSUB 2200:PRINT "C6XMIT ACKNOWLEDGED?030"
7666 GOSUB 2200
7670 GOTO 7532
7800 REM *** ROUTE/ROUTE POST PARTIAL TOUR DISTANCE
7805 PRINT "W350485510510~F":CHR$(12):
7810 PRINT "C7U360497":CHR$(21):"TOTAL DISTANCE =":PRINT USING "####":TD;
7820 PRINT "G":
7830 RETURN
7900 REM *** ROUTE - RESET LIGHT FEN AND RESUME EDIT
7910 OUT&H90,0
7920 RESUME 7930
7930 ON ERROR#2 GOTO 7960
7940 OUT&H90,0
7950 GOTO 7090
7960 X=CURSX(4):Y=CURSY(4)
7970 GOTO 7800
8000 REM *** ROUTE - ROUTE PACED
8010 IF ON#0 THEN 7900
8020 PRINT "W111510399":CHR$(12):

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8080 GOSUB 3000
8090 PRINT "X3510 1510510" : CHR(12) : "X4510 4500
8100 REM ***
8110 GOTO 8145
8120 LA=0:PRINT "X3510 1510510" : CHR(12) : "X4510 4500
8130 LA=0
8140 REM ***
8150 REM ROUTE/ROUTE RESET LIGHT PEN
8160 CHRS(12)
8170 REM ***
8180 ON LAPOW2 GOTO 8145
8190 GOTO 8140
8200 X=CURSY(4):Y=CURSY(4)
8210 IF Y<500 THEN 8500
8220 IF X<350 THEN 8100
8230 N=5:GOSUB 4000:IF N=1
8240 ON F3 GOTO 8280,8300,8700,7400,7600
8250 GOTO 8100
8260 REM ROUTE/ROUTE START
8270 IF RB=-1 THEN PRINT "X3510 1510510" : CHR(12) : "X4510 4500
8280 RB=-1:TC=0
8290 LA=0:PRINT "X3510 1510510" : CHR(12) : "X4510 4500
8300 GOTO 8100
8310 REM ROUTE/ROUTE BACK-UP
8320 PRINT "X3510 1510510" : CHR(12) : "X4510 4500
8330 IF LA<2 THEN 8100
8340 A1=ABS(RT(LA)):H1=A1/RT(LA)
8350 A2=ABS(RT(LA-1)):H2=A2/RT(LA-1)
8360 IF H1>0 THEN X1=TP(A1,1):Y1=TP(A1,2)
8370 IF H1<0 THEN X1=TP(A1,3):Y1=TP(A1,4)
8380 IF H2>0 THEN X2=TP(A2,1):Y2=TP(A2,2)
8390 IF H2<0 THEN X2=TP(A2,3):Y2=TP(A2,4)
8400 PRINT "X3510 1510510" : CHR(12) : "X4510 4500
8410 TO=TO-SCR((X1-X2)^2+(Y1-Y2)^2)
8420 GOSUB 7000
8430 LA=LA-1:GOTO 8055
8440 REM *** ROUTE/ROUTE STARTING POINT GIVEN
8450 LA=0
8460 GOSUB 3200
8470 IF TN=0 THEN 8100
8480 IF TC(TN,2)<>CN OR TA(TN)=0 THEN 8100
8490 IF HT<0 THEN 8100
8500 LA=1:RT(1)=TN:RB=0
8510 PRINT "X3510 1510510" : CHR(12) : "X4510 4500
8520 PRINT "X3510 1510510" : CHR(12) : "X4510 4500
8530 TO=0
8540 X2=TP(TN,1):Y2=TP(TN,2):GOTO 8655
8550 REM *** ROUTE/ROUTE NEXT POINT
8560 IF RB=-1 THEN 8400
8570 IF LA=0 THEN 8100
8580 GOSUB 3200
8590 IF TN=0 THEN 8100
8600 IF TC(TN,2)<>CN OR TA(TN)=0 THEN 8100
8610 PRINT "X3510 1510510" : CHR(12) : "X4510 4500
8620 FG=0
8630 FOR J=1 TO LA
8640 IF RT(J)=TN*HT THEN 8100
8650 IF RT(J)=-TN*HT THEN FG=1
8660 NEXT J
8670 IF FG=0 AND HT<0 THEN 8100
8680 LA=LA+1
8690 RT(LA)=TN*HT
8700 A1=ABS(RT(LA-1)):H1=A1/RT(LA-1)
8710 IF H1>0 THEN X1=TP(A1,1):Y1=TP(A1,2)

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8675 IF M1<0 THEN Y1=TP(11,3):Y2=TP(11,4)
8680 IF M1>0 THEN Y2=TP(11,3):Y1=TP(11,2)
8685 IF M1<0 THEN X2=TP(11,3):Y2=TP(11,4)
8687 Y2=TP(11,3):X2=TP(11,3):Y1=TP(11,2)
8690 PRINT "TTCOC":PLOT X1,Y1,X2,Y2
8695 PRINT "TTCOC":PLOT X2,Y2:PRINT "TTCOC":PLOT X1,Y1,X2,Y2
8698 GOSUB 7500
8699 GOTO 6100
8700 REM ***** STOP
8705 PRINT "TTCOC":CHR$(12):"TTCOC":
8720 PRINT "TTCOC":CHR$(12):"TTCOC":GOSUB 4500
8722 PRINT "TTCOC":
8725 ERASE RT
8727 GOSUB 7700
8730 GOTO 7900
9000 REM ***** COVER SUBFUNCTION
9010 OUT$F90,0
9020 RESUME 1040
9030 PRINT CHR$(12):"OA1":
9040 PRINT "M1:1,510399":CHR$(12):"M351401510510":CHR$(12):
9050 PRINT CHR$(21):"TTC4BEGIN COVER REQUEST"
9060 GOSUB 2100:PRINT#4:7
9070 PRINT "TTCOC":GOSUB 2200
9080 ON ERROR#3 GOTO 9100
9090 GOTO 9350
9100 RESUME 9110
9110 GOSUB 2100
9115 PRINT#4:1:PRINT "TTCOC":GOSUB 2200
9120 PRINT CHR$(12):"OA1":"M351401510510":"TTC4COVER REQUEST XMITTED":GOSUB 2200
9130 GOSUB 2200
9135 PRINT CHR$(12):"OA1TTCOC":
9140 INPUT#4:NC
9150 PRINT NC:"CLUSTERS RETURNED"
9160 FOR K = 1 TO NC
9164 CHK MOD 6:IF C=0 THEN C=6
9170 GOSUB 2200
9180 INPUT#4:RT
9185 PRINT CHR$(12):"OA1":CHR$(21):
9190 PRINT RT:"TRIPS IN CLUSTER":K
9195 PRINT CHR$(12):"OAG":
9200 FOR J=1 TO RT
9210 GOSUB 2200
9220 INPUT#4:I
9230 TC(1,1)=C:TC(I,2)=K:PRINT "TTCOC":GOSUB 3400:TA(I)=1
9240 NEXT J
9245 PRINT CHR$(12):CHR$(27):"OA1":
9250 NEXT K
9260 PRINT CHR$(12):"OA1TTC4COVER REQUEST COMPLETE":GOSUB 2200
9280 ON=NC+1
9290 PRINT CHR$(12):CHR$(27):"OA1TTCOC":
9300 REM ***** COVER MENU SERVICE ROUTINE
9310 OUT$F90,0
9320 ON ERROR#2 GOTO 9340
9330 GOTO 9330
9340 X=CURSX(4):Y=CURSY(4)
9350 GOSUB 4000
9355 OUT$F90,0
9360 IF M1<0 THEN RESUME 9300
9365 IF M1=1 THEN RESUME 10000
9370 IF M1=2 THEN 9000
9380 RESUME 9350
9400 REM ***** COVER/EXIT
9410 PRINT "M1:1,510510":CHR$(12):"M351401510510":
9420 F1=0:F2=0:RESUME 120

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10790 RETURN
10810 REM *** MAKE - DRAW CLUSTERED AND (AND K, COLOR C)
10815 PRINT "C700":
10820 PRINT USING "A4:01":
10830 PRINT "Y4:01":
10840 PLOT CT(K,1)-7,CT(K,2)-7,CT(K,1)+7,CT(K,3)+7
10850 PRINT "L4:01":
10860 PLOT CT(K,3)-7,CT(K,4)-7,CT(K,3)+7,CT(K,4)+7
10870 PRINT "Y4:01":
10880 PLOT CT(K,1),CT(K,2),CT(K,3),CT(K,4)
10890 TL=CONV(CT(K,1)-CT(K,3))-(CT(K,2)-CT(K,4))-(2)
10900 IF C=7 THEN CT(K,6)=0
10910 IF C=0 THEN TA(K)=0
10920 RETURN
11000 REM *** CHAINING FUNCTIONS
11010 IF Y<400 THEN 11050
11020 IF X<350 THEN L=0:YJ=0:PRINT "W350400511011":CHR$(12):"F":
11030 IF X<550 THEN M=2:GOSUB 4000:F2=M1
11040 IF X<350 THEN M=3:GOSUB 4000:OPMT=1
11050 ON F2 GOTO 11200,11400,11600,12000,12500
11060 OUTA90,0
11070 RESUME 10090
11200 REM *** CHAINING - SELECT CHAIN
11210 IF Y<400 OR X>350 THEN 11250
11220 L=3:MJ=0:OC=0:OA=0
11230 PRINT "W1,1,511399":CHR$(12):"W351400510510":CHR$(12):"F":
11240 OUTA90,0:RESUME 10090
11250 GOSUB 13000
11260 IF CM=0 THEN OUTA90,0:RESUME 10090
11270 OA=CM:OC=C
11280 PRINT "W1,1,511400":CHR$(12):"F":
11290 I=CM:GOSUB 13600
11300 PRINT "2":
11310 OUTA90,0:RESUME 10090
11400 REM *** CHAINING - EDIT SELECTION
11410 PRINT "W1,401349510":CHR$(12):M=3:GOSUB 4500
11415 F2=0
11420 OUTA90,0
11430 RESUME 14000
11600 REM *** CHAINING - REQUEST CHAINS
11605 PRINT "W1,1,5101":CHR$(12):"F":
11610 PRINT "W351401510510":CHR$(12):CHR$(21):"C40001 CHAIN REQUEST"
11615 OUTA90,0:RESUME 11620
11620 GOSUB 2100:PRINT#4:5:PRINT"?005":GOSUB 2200
11625 ON ERROR#3 GOTO 11635
11630 GOTO 11630
11635 RESUME 11640
11640 GOSUB 2100
11645 INPLY "MAXIMUM NO OF CHAINS":DC
11650 PRINT #4:DC:
11652 TY=0
11653 FOR I=1 TO AC
11654 IF TA(I)=1 THEN TY=TY+1
11655 NEXT I
11656 PRINT#4:"":TY:
11657 FOR I=1 TO AC
11658 IF TA(I)=1 THEN PRINT#4:"":PRINT#4:USING "A4:01":I:
11659 NEXT I
11667 PRINT#4:" "
11670 PRINT CHR$(27):"0A1":CHR$(21):"W351401510510:0000:CLUSTERS OMITTED?":
11675 GOSUB 2200:GOSUB 10000
11680 PRINT CHR$(27):"0A1":CHR$(21):
11685 INPLY#4:IN
11690 PRINT LN:"CHAINS RETURNED"

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11695 FOR I=1 TO 25
11700 ON POE P:IF C=0 THEN C=1
11705 GOSUB 2200
11710 INPUT#4:IT
11715 PRINT CHR$(27);"0A1";CHR$(12);
11720 PRINT RT;" CLUTTER IS IN CHAIN "24
11725 PRINT CHR$(27);"0A0";
11730 ON=C+1
11735 FOR J=1 TO 6
11740 CH(CH,J)=0
11745 NEXT J
11750 FOR J=1 TO RT
11755 GOSUB 2200
11760 INPUT#4:G
11765 CI(G,5)=CI(G,6)=CH:TA(G)=1
11770 IF J<7 THEN CH(CH,J)=G
11772 PRINT CHR$(27);"0A1" CHAIN TO ":G
11780 NEXT J
11785 LC=LC+1:CL(LC)=CH
11790 PRINT CHR$(27);"0A076";
11795 I=ON:GOSUB 13000
11800 PRINT CHR$(21);CHR$(27);"CA1";
11805 NEXT R
11810 PRINT CHR$(27);"0A1704CHAIN RECLIST COMPLETE77130"
11815 PRINT CHR$(12);CHR$(27);"0A076";
11817 PRINT "77187W1,1,510510";CHR$(12);"7717";
11820 FI--1:GOTO 10085
12000 REM *** CHAIN - XMIT CHAIN
12005 PRINT "77351401510510";CHR$(12);CHR$(21);"7704BEGIN CHAIN XMIT"
12010 IF CA=0 THEN PRINT "NO CHAIN SELECTED77020";OUT#90,0:RESUME 12155
12015 TY=0
12020 FOR J=1 TO 6
12025 IF CH(CH,J)=0 THEN 12032
12030 H=CH(CH,J)
12035 FOR G=1 TO NT
12040 IF TC(G,2)=H THEN TY=TY+1
12045 NEXT G
12050 NEXT J
12052 LC=LC+1:CL(LC)=CH
12055 PRINT TY;" TRIPS IN CHAIN"
12060 OUT#90,0:RESUME 12065
12065 GOSUB 2100:PRINT#4:5:PRINT"77005";:GOSUB 2200
12070 ON ERROR#3 GOTO 12080
12075 GOTO 12075
12080 RESUME 12082
12082 GOSUB 2200
12085 GOSUB 2100:PRINT#4:"1,";:PRINT#4:LSIAG"####";:CC(CH):
12090 PRINT#4:",";:TY:
12095 FOR J=1 TO 6
12100 IF CH(CH,J)=0 THEN 12130
12105 H=CH(CH,J)
12110 FOR G=1 TO NT
12115 IF TC(G,2)=H THEN PRINT#4:",";:G:
12120 NEXT G
12125 NEXT J
12130 PRINT#4:" "1PRINT"77005";:GOSUB 2200
12135 ON ERROR#3 GOTO 12145
12140 GOTO 12140
12145 RESUME 12147
12147 GOSUB 2200
12150 GOSUB 2200:PRINT "7706XMIT ACKNOWLEDGE07077730"
12155 PRINT"773514015105107717";CHR$(12);:CH=0:GOSUB 2200
12167 PRINT "77187W1,1,510510";CHR$(12);"7717";
12180 OUT#90,0:GOTO 10090

```



```

13300 G=CT(I,5)
13310 RETURN
13400 REM *** CHAINING MACRO - LOCATE CLUSTERED LINK
13410 Y=0:PTL=0
13420 FOR I=1 TO 40
13430 IF ABS(X-CT(I,1))<10 AND ABS(Y-CT(I,2))<10 THEN Y=1:GOTO 13460
13440 IF ABS(X-CT(I,3))>9 OR ABS(Y-CT(I,4))>9 THEN 13470
13450 Y=Y+1
13460 TH=1:CH=CT(I,1):IC=CT(I,5):PRINT "CH="TH":IC="IC:RETURN
13470 NEXT I
13480 RETURN
13490 REM *** MACRO - DRAW CHAIN P, COLOR C
13500 CC(I)=0:PTL=0
13510 IF I=0 THEN RETURN
13520 L=1:PRINT "C":PRINT USING "A":0:
13530 K=CH(I,L):GOSUB 13600
13540 OX=CT(K,3):OY=CT(K,4)
13550 L=L+1
13560 IF L<7 THEN K=CH(I,L)
13570 IF L>6 OR K=0 THEN RETURN
13580 GOSUB 13600:CC(I)=CC(I)+1
13590 NX=CT(K,1):NY=CT(K,2)
13600 T1=CT(K,3):T2=CT(K,4)
13610 IF C=7 THEN PRINT "C":PRINT USING "A":0:
13620 GOSUB 13600
13630 IF C=7 THEN PRINT "C":PRINT USING "A":7:
13640 OX=T1:OY=T2
13650 GOTO 13600
13660 REM *** DRAW DASHED LINE FROM (OX,OY) TO (NX,NY)
13670 TL=SGR((OX-NX)^2+(OY-NY)^2)
13680 CC(I)=CC(I)+1
13690 DN=TL/6
13700 XD=NX-OX:XQ=XO/DN
13710 YD=NY-OY:YQ=YD/DN
13720 FOR K=1 TO DN/2
13730 PRINT "C":
13740 PLOT OX,CY,OX+XQ,CY+YQ
13750 OX=OX+2*XQ
13760 OY=OY+2*YQ
13770 NEXT K
13780 RETURN
14000 REM *** CHAINING - EDIT SUBFUNCTION
14010 OUTP90,0
14020 ON ERROR#2 GOTO 14040
14030 GOTO 14030
14040 X=CURSY(4):Y=CURSY(4)
14050 IF Y<400 THEN 14090
14060 IF X<350 THEN L=0:MJ=0:PRINT "1:5TW350400511511":CHR(12):"1:F"
14070 IF X<350 THEN M=3:GOSUB 4000:F2=MJ
14080 IF X>350 THEN M=0:GOSUB 4000:CMY=1
14090 ON F2 GOTO 14200,14400,14500,14600,15000,15200
14100 IF F2=0 THEN OUTP90,0:RESUME 14000
14110 PRINT "1:5TW1,1,511511":CHR(12):"1:F"
14120 F1=-1:M=2:GOSUB 4000:PRINT "C":
14130 OUTP90,0:RESUME 10085
14200 REM *** CHAIN/EDIT - SELECT CHAIN
14210 IF Y<400 OR X>350 THEN 14250
14220 L=0:MJ=0:CC=0:OA=0
14230 PRINT "1:5TW1,1,5115399":CHR(12):"1:551400511511":CHR(12):"1:F"
14240 OUTP90,0:RESUME 14000
14250 GOSUB 13000
14260 IF CM=0 THEN OUTP90,0:RESUME 14000
14270 OA=CM:CC=C
14280 PRINT "1:5TW1,1,511450":CHR(12):"1:F"

```

```

14210 Y=CM:GOSUB 13600
14220 PRINT "2":
14310 OUT$H90,0:RESUME 14000
14410 REM *** CHAIN/EDIT - DISCARD CHAIN
14420 IF Y<400 OR X>350 THEN 14450
14430 L=0:KJ=0:OC=0:OA=0
14440 PRINT "18TW1,1,510400":CHR$(12):"1F":
14450 OUT$H90,0:RESUME 14010
14460 GOSUB 13600
14470 IF CN=0 THEN OUT$H90,0:RESUME 14000
14470 C=7:TN=0:GOSUB 13600
14470 OUT$H90,0:RESUME 14000
14500 REM *** CHAIN/EDIT - CREATE CHAIN
14510 IF Y<400 AND X>350 THEN OC=0
14520 IF Y<400 OR X>350 THEN OUT$H90,0:RESUME 14000
14530 PRINT "18TW1,1,510400":CHR$(12):"1F":
14540 OC=CA:OA=CM+1:OC:OA=0
14540 FOR J=1 TO 6
14550 CH(CA,J)=0
14560 NEXT J
14570 OUT$H90,0:RESUME 14000
14600 REM *** CHAIN/EDIT - IGNORE CHAIN
14610 IF Y<400 OR X>350 THEN 14650
14620 L=0:KJ=0:OC=0:OA=0
14630 PRINT "18TW1,1,510390":CHR$(12):"18TW31400010010":CHR$(12):"1F":
14640 OUT$H90,0:RESUME 14000
14650 GOSUB 13600
14660 IF CN=0 THEN OUT$H90,0:RESUME 14000
14670 I=CN:CN=0
14680 PRINT "18TW1,1,511400":CHR$(12):"1F":
14690 GOSUB 13600
14900 OUT$H90,0
14910 RESUME 14000
15000 REM *** CHAIN/EDIT - ADD TO CHAIN
15010 IF OC=0 OR OA=0 THEN PRINT "18TW1,400350510":F":F2=0:OUT$H90,0:RESUME 140
15020 IF Y<400 THEN 15050
15030 PRINT "18TW350400511511":CHR$(12):"1F":
15032 CM=CM+1
15033 FOR J=1 TO 6
15034 CH(CM,J)=CH(OA,J):IF CH(CA,J)<>0 THEN CT(CH(CA,J),6)=CM
15035 NEXT J
15036 OA=CM
15040 OUT$H90,0:RESUME 14000
15050 GOSUB 13400
15060 IF TN=0 OR CT(TN,6)<>0 THEN OUT$H90,0:RESUME 14000
15070 CT(TN,5)=OC:CT(TN,6)=OA
15080 FOR J=1 TO 6
15090 IF CH(CA,J)=0 THEN 15120
15100 NEXT J
15110 GOTO 15130
15120 CH(CA,J)=TN
15130 T=OA:OA=OC
15140 PRINT "1":GOSUB 13600:PRINT "2":
15150 OUT$H90,0:RESUME 14000
15200 REM *** CHAIN/EDIT - RESTORE
15205 GOSUB 10300
15207 PRINT "18TW1,1,510510":CHR$(12):"1F":
15210 OUT$H90,0:RESUME 14000
31000 STOP

```

7, C3ETAL-A-RIDE PREPARY MENU FILE C2

#, 8, C400102 MENU C2

365,460,385,500,0

325,460,400,500,1

430,460,455,500,2

465,460,490,500,3

360,410,385,450,4

395,410,420,450,5

430,410,455,450,6

465,410,490,450,7

#, 5, C40CENTRAL MENU C2

5,430,45,480,7

55,430,95,480,7

105,430,145,480,7

155,430,195,480,7

14,425,2,"EDIT"

53,425,4,"CLUSTER"

110,425,6,"ROUTE"

162,425,3,"COVER"

70,502,7,"DIAL-A-RIDE PRINCIPAL SELECTION"

#, 9, C4EDIT MENU C2

5,430,45,480,7

55,430,95,480,7

105,430,145,480,7

155,430,195,480,7

205,430,245,480,7

6,425,2,"RESTORE"

58,425,4,"IGNORE"

58,414,4,"CLUSTER"

107,425,6,"IGNORE"

115,414,6,"ARC"

151,425,3,"SELECT"

151,414,3,"CLUSTER"

212,425,7,"EXIT"

70,502,7,"DIAL-A-RIDE CLT1 SUBFUNCTION"

0,12, CACULSTER MENU C2

5,430,40,430,7

50,430,85,430,7

95,430,130,430,7

140,430,175,430,7

185,430,220,430,7

230,430,265,430,7

275,430,310,430,7

5,425,5,"SELECT"

5,414,6,"CLUSTER"

50,425,3,"CREATE"

50,414,3,"CLLSTR"

95,425,2,"ADD TO"

95,414,2,"CLLSTR"

138,425,4,"DEL FRM"

142,414,4,"CLUSTYR"

190,425,5,"REQST"

236,425,6,"XPIT"

279,425,7,"EXIT"

70,502,7,"DIAL-A-RIDE CLUSTER SUBFUNCTION"

0,5, C4ROUTING MENU C2

5,430,45,430,7

55,430,95,430,7

105,430,145,430,7

5,425,3,"SELECT"

5,414,3,"CLUSTER"

50,425,2,"ROUTE"

110,425,7,"EXIT"

70,502.1,"DIAL-A-RICE ROUTING SUB-ROUTINE"

4.5, C4ROUTING SUB-MENU C2

300,420,380,480,7

330,430,410,480,7

410,430,440,480,7

440,430,470,480,7

470,430,500,480,7

300,414,2,"BCK"

300,414,6,"EFV"

410,414,4,"END"

440,414,3,"REC"

470,414,5,"XBT"

4.3, C4COVER MENU C2

5,430,45,480,7

55,430,95,480,7

10,425,2,"CHAIN"

61,425,4,"EXIT"

70,502.7,"DIAL-A-RICE COVERING SELECTION"

0, C3PTEL-A-3300 SECONDARY MENU FILE 02

#,0, C4CCELOP MENU 02

300,400,310,500,0

300,400,420,500,1

430,400,450,500,2

455,400,490,500,3

360,410,385,400,4

395,410,420,450,5

430,410,455,450,6

465,410,490,450,7

#,3, C4COVER MENU 02

5,430,45,480,7

55,430,55,480,7

10,425,2,"CHAIN"

41,425,4,"EXIT"

70,502,7,"DIAL-A-RIDE COVERING SELECTION"

#,10, C4CHAINING MENU 02

5,430,40,480,7

50,430,85,430,7

95,430,130,480,7

140,430,175,480,7

195,430,220,480,7

5,425,6,"SELECT"

9,414,6,"CHAIN"

58,425,3,"EDIT"

50,414,3,"CHAINS"

103,425,2,"REST"

95,414,2,"CHAINS"

150,425,4,"XPIT"

140,414,4,"CHAIN"

180,425,5,"FINALE"

70,502,7,"DIAL-A-RIDE CHAINING SUBFUNCTION"

8,12, C4CHAIN EDIT MENU 02

5,430,60,400,7

55,430,80,400,7

95,470,130,400,7

140,430,175,400,7

185,430,220,400,7

230,430,265,400,7

275,430,310,400,7

5,425,6,"SELECT"

9,414,5,"CHAIN"

53,425,5,"DISSCO"

95,425,4,"IGNORE"

99,414,4,"CHAIN"

140,425,3,"CREATE"

144,414,3,"CHAIN"

185,425,2,"ADD TO"

189,414,2,"CHAIN"

224,425,1,"RESTORE"

283,425,7,"EXIT"

70,502,7,"DIAL-A-RIDE CHAIN EDITING SUBFUNCTION"

B-3

Cyber (FORTRAN)
Optimization Programs for
Dial-A-Ride

```

PROGRAM CHAIN INPUT, OUTPUT
COMMON ITXOR(50),ITYOR(50),ITXOT(50),ITYOT(50),ITLOR(50),
* RTCCS(10),ICXOR(50),ICYOR(50),ICXOT(50),ICYOT(50),
* ICTIR(50),ICTRF(250),ISCOL(100,50),ISCOL(100),
* INTRP,INCLS,INCOL
INTRP=INCLS+INCOL=0
C
C INITIALIZE SET COVER COLUMNS
C
DO 100 I=1,100
DO 100 J=1,50
ISCOL(I,J)=0
100 CONTINUE
C
C ENTER FUNCTION
C
110 READ*, IFUNC
IF(IFUNC.EQ.0) STOP
IF(IFUNC.EQ.1) CALL TSTOR
IF(IFUNC.EQ.2) CALL CLUST
IF(IFUNC.EQ.3) CALL ROUTE
IF(IFUNC.EQ.4) CALL CSTOR
IF(IFUNC.EQ.5) CALL CHAIN
IF(IFUNC.EQ.6) CALL SSTOR
IF(IFUNC.EQ.7) CALL COVER
GO TO 110
END
SUBROUTINE TSTOR
COMMON ITXOR(50),ITYOR(50),ITXOT(50),ITYOT(50),ITLOR(50),
* RTCCS(10),ICXOR(50),ICYOR(50),ICXOT(50),ICYOT(50),
* ICTIR(50),ICTRF(250),ISCOL(100,50),ISCOL(100),
* INTRP,INCLS,INCOL
DATA ITDIS/1/
C
C FUNCTION 1 - TRIP STORAGE
C
C ENTER # OF TRIPS & TRIP COORDINATES
C
READ*, IREST, ITSTC
IF(IREST.EQ.1) INTRP=INCOL=0
DO 100 I=1,ITSTC
READ*, IRXOR,IRYOR,IRYOT,IRLOT
C
C STORE TRIPS
C
ITXOR(INTRP+I)=IRXOR
ITYOR(INTRP+I)=IRYOR
ITXOT(INTRP+I)=IRYOT
ITYOT(INTRP+I)=IRYOT
ITLOR(INTRP+I)=IRLOT
RTCCS(INTRP+I)=0.0
C
C STORE COLUMNS
C
ISCOL(INCOL+I,INTRP+I)=1
IF(ITDIS.EQ.1) ISCOL(INCOL+I)=
* 2*IFIX(SQRT(FLCAT((IRYOR-IRYOT)**2+(IRYOR-IRYOT)**2))+0.5)
IF(ITDIS.EQ.2) ISCOL(INCOL+I)=
* 2*((IRXOR-IRYOT)**2+(IRYOR-IRYOT)**2)
IF(ITDIS.EQ.3) ISCOL(INCOL+I)=
* 2*(IABS(IRYOR-IRYOT)+IABS(IRYOR-IRYOT))
100 CONTINUE
INTRP=INTRP+ITSTC
INCOL=INCOL+ITSTC

```

```

      RETURN
      END
      SUBROUTINE CCLSTP
      COMMON ITXOR(50),ITYOR(50),ITXDT(50),ITYDT(50),ITLDD(50),
      *      RTXOR(50),RXYOR(50),RCXDT(50),RCYDT(50),ITCOV(50),
      *      ICTRP(50),ICTRF(50),ISCOL(10),INTP,INCLS,ISCOL
      *      INTP,INCLS,ISCOL
      DIMENSION RTXOR(10),RXYOR(10),RCXDT(10),RCYDT(10),PCNGT(10)
      DATA RSTOLU/0.5/,RSTOLL/0.5/,ITDIS/1/,ACTOL/0.1/

C
C      FUNCTION 4 - CLUSTER STORAGE
C
C      STORE CLUSTERS
C
      ITPTR=INCLS+1
      DO 100 I=1,ISCOL

C
C      COMPLETE REDUCED COSTS FOR EACH COLUMN
C
      RRCCS=FLCAT(ISCOS(I))
      DO 100 J=1,INTP
      IF (ISCOL(I,J).EQ.0) GO TO 100
      RRCCS=RRCCS-RTCOS(J)
100  CONTINUE
      IF ((RRCCS.GE.RSTOLU).OR.(RRCCS.LE.RSTOLL)) GO TO 130
      INCLS=INCLS+1

C
C      STORE CLUSTER TRIPS
C
      ITCCV=0
      DO 110 J=1,INTP
      IF (ISCOL(I,J).EQ.0) GO TO 110
      ITCCV=ITCCV+1
      ICTRP(ITPTR+ITCCV)=J
      RTXCR(ITCCV)=FLCAT(ITXCR(J))
      RXYCR(ITCCV)=FLCAT(ITYCR(J))
      RTXDT(ITCCV)=FLCAT(ITXDT(J))
      RXYDT(ITCCV)=FLCAT(ITYDT(J))
      PCNGT(ITCCV)=FLCAT(ITLDD(J))
110  CONTINUE
      ITPTR=ITPTR+ITCCV
      ICTPR(INCLS)=ITPTR

C
C      GENERATE & STORE CLUSTER COORDINATES
C
      RCXCR=FLCAT(ITXCR(ICTRP(ITPTR)))
      RXYCR=FLCAT(ITYCR(ICTRF(ITPTR)))
      RCXDT=FLCAT(ITXDT(ICTRP(ITPTR)))
      RCYDT=FLCAT(ITYDT(ICTRF(ITPTR)))
120  CALL WSUM2(RCXCR,RCYCR,RCXDT,RCYDT,RTXCR,RTYCR,RTXDT,RTYDT,
      *      PCNGT,RWSOR,RWASR,RWSOR,RWSDT,RWADT,RWBDT,ITCOV,ITDIS)
      RCGRA=SQRT((RWSOR*RCXCR-RWASR)**2+(RWSOR*RCYCR-RWBSR)**2+
      *      (RWSDT*RCXDT-RWADT)**2+(RWSDT*RCYDT-RWBDT)**2)
      RCXCR=RWASR/RWSOR
      RXYCR=RWBSR/RWSOR
      RCXDT=RWADT/RWSDT
      RCYDT=RWBDT/RWSDT
      IF (RCGRA.GT.ACTOL) GO TO 120
      ICXCR(INCLS)=IFIX(RCXCR*0.5)
      ICYCR(INCLS)=IFIX(RXYCR*0.5)
      ICXDT(INCLS)=IFIX(RCXDT*0.5)
      ICYDT(INCLS)=IFIX(RCYDT*0.5)
130  CONTINUE
C

```

```

C      REINITIALIZE SET COVER COLUMNS
C
DO 140 I=1, INCLS
DO 140 J=1, ININD
ISCOL(I,J)=0
140 CONTINUE
INCOL=0

C
C      RETURN CLUSTER
C
ITPTR=0
PRINT 160, INCLS
DO 150 I=1, INCLS
PRINT 150, ICXOR(I), ICYOR(I), ICXDT(I), ICYDT(I)
150 FORMAT (4(I6,*,*))
IINCL=ICPTR(I)-ITPTR
PRINT 160, IINCL
DO 170 J=1, IINCL
PRINT 160, ICIRP(ITPTR+J)
160 FORMAT (I4,*,*)
170 CONTINUE
ITPTR=ICPTR(I)
180 CONTINUE
RETURN
END
SUBROUTINE WSON2(RCXOR,RCYOR,RCXDT,RCYDT,RTXOR,RTYOR,
*             RTXDT,RTYDT,RCWGT,RWSOR,RWACR,RWSOR,
*             RWSOT,RWADT,RWBDT,ITCOV,ITDIS)
DIMENSION RTXOR(10),RTYOR(10),RTXDT(10),RTYDT(10),RCWGT(10)
DATA REPSL/0.01/

C
C      COMPUTE SUMS
C
RWSOR=RWACR=RWSOT=RWADT=RWBDT=0.0
DO 100 I=1,ITCOV
IF (RCWGT(I).LE.0.0) GO TO 100
IF (ITDIS.EQ.1)
*   RDIST=SQRT((RCXOR-RTXOR(I))**2+(RCYOR-RTYOR(I))**2+REPSL)
IF (ITDIS.EQ.2) RDIST=1.0
IF (ITDIS.EQ.3)
*   RDIST=ABS(RCXOR-RTXOR(I))+ABS(RCYOR-RTYOR(I))+REPSL
RWSOR=RWSOR+RCWGT(I)/RDIST
RWACR=RWACR+RCWGT(I)*RTXOR(I)/RDIST
RWSOT=RWSOT+RCWGT(I)*RTYOR(I)/RDIST
IF (ITDIS.EQ.4)
*   RDIST=SQRT((RCYDT-RTYDT(I))**2+(RCYDT-RTYDT(I))**2+REPSL)
IF (ITDIS.EQ.2) RDIST=1.0
IF (ITDIS.EQ.3)
*   RDIST=ABS(RCXDT-RTXDT(I))+ABS(RCYDT-RTYDT(I))+REPSL
RWSOT=RWSOT+RCWGT(I)/RDIST
RWADT=RWADT+RCWGT(I)*RTXDT(I)/RDIST
RWBDT=RWSOT+RCWGT(I)*RTYDT(I)/RDIST
100 CONTINUE
RETURN
END
SUBROUTINE SSTOR
COMMON ITXOR(50),ITYOR(50),ITXDT(50),ITYDT(50),ITLOD(50),
*      RICOR(50),ICXOR(50),ICYOR(50),ICXDT(50),ICYDT(50),
*      ICIRP(50),ICIRP(250),ISCOL(100,50),ISCOL(100),
*      INTRP,INCLS,INCOL
C
C      FUNCTION 6 - COLUMN STORAGE
C
C      ENTER # OF COLUMNS

```

```

C      READ*, ICSYC
C      DO 110 I=1, ICSYC
C
C      ENTER COLUMN PARAMETERS & DATA NUMBERS
C
C      READ*, IRCOS, ITCOV
C
C      STORE COLUMN
C
C      DO 100 J=1, ITCOV
C      READ*, ITRUN
C      ISCOL(ITCOL+I, ITRUN)=1
100  CONTINUE
C      ISCOS(ITCOL+I)=IRCOS
110  CONTINUE
C      INCOL=INCOL+ICSTO
C      RETURN
C      END
C      SUBROUTINE CLUST
C      COMMON ITXOR(50), IYYOR(50), ITYOT(50), IYOT(50), ITLOD(50),
C      *      RTCOS(50), ICXOR(50), ICYOR(50), ICXOT(50), ICYOT(50),
C      *      ICPTX(50), ICTPY(250), ISCOL(100,50), ISCOS(100),
C      *      ITRIP, INCLS, INCOL
C      LOGICAL ZPATH
C      DIMENSION ICAPT(50), ILCAB(50), ICOST(50,50), PCOST(50),
C      *      IASST(50), IQUAL(100), IUPRT(100), ITAPT(100),
C      *      ITRPT(100), ZPATH(100), ICXOR(50), ICYOR(50),
C      *      RCYOT(50), SCYOT(50), RTYOR(50), RTYOR(50),
C      *      RYXOT(50), RYOT(50), ITRUN(50), ITRIP(7)
C      DATA ITDIS/1/, RDISH/1.0/
C
C      FUNCTION 2 - CLUSTERING
C
C      ENTER CLUSTERING PARAMETERS & CLUSTER COORDINATES
C
C      READ*, ILOCM, IROLS, ITRIP, IVCAP, IDCAP
C      IPARM(3)=IROLS
C      IF(IDCAP.GT.0) IPARM(3)=IPARM(3)+1
C      IPARM(4)=1+ITRIP+1
C      ITOTC=0
C      DO 110 I=1, IROLS
C      RCXOR(I)=RCYOR(I)=RCYOT(I)=RCYOT(I)=0.0
C      IF(ILOCM.NE.1) GO TO 100
C      READ*, RCXOR(I), RCYOR(I), RCYOT(I), RCYOT(I)
100  ICAPT(I)=IVCAP
C      ITOTC=ITOTC+ICAPT(I)
110  CONTINUE
C      ICAPT(IROLS+1)=IDCAP
C      ITOTC=ITOTC+IDCAP
C
C      ENTER TRIPS
C
C      ITOTL=0
C      DO 120 I=1, ITRIP
C      READ*, ITRUN
C      ITRUN(I)=ITRUN
C      RTXOR(I)=FLOAT(ITXOR(ITRUN))
C      RTYOR(I)=FLOAT(IYYOR(ITRUN))
C      RTXOT(I)=FLOAT(ITXOT(ITRUN))
C      RTYOT(I)=FLOAT(IYOT(ITRUN))
C      ILOAD(I)=ITLOD(ITRUN)
C      PCOST(I)=RTCOS(ITRUN)
C      ITOTL=ITOTL+ILCAB(I)

```



```

170 CONTINUE
   FLOA(170.0)=ITCOT-ITCCL
   IPARM(7)=1

C
C
C   GENERATE CLUSTERS

180 CALL DYSY(IIST,IICOST,RCXOR,RCYOR,RCXOT,RCYOT,RTXOR,PTYOR,
   *      RYXOT,RYYOT,IPARM,IICAP,ITCIS,ITCIS)
   CALL YF(100.0,100.0,IPARM,IICAP,IICAP,IICAP,IICAP,IICAP,
   *      IICAP,IICAP,IICAP,IICAP)
   IF(IICAP.EQ.1) GO TO 180
   CALL LOCATE(RCXOR,RCYOR,RCXOT,RCYOT,RTXOR,PTYOR,RYXOT,RYYOT,
   *      IICAP,IICAP,IICAP,IICAP,IICAP,IICAP,IICAP,IICAP)
   IPARM(7)=1
   IF(ISTOP.EQ.0) GO TO 180

C
C
C   RETURN CLUSTER ASSIGNMENTS

140 IF(IPCLS.EQ.1) GO TO 190
   DO 160 I=2,IPCLS
   IF(IASST(I).EQ.0) GO TO 180
   J=ICAPY(I)-IPARM(3)
   IF(J.GT.IRTRP) GO TO 180
   PRINT 170, I, ITNUM(J)

170 FORMAT (2(14,*,*))
160 CONTINUE
190 IINCL=IPARM(3)+1
   IINCL=IPARM(3)+IRTRP
   DO 200 J=IINCL,IINCU
   IF(IASST(J).EQ.0) GO TO 200
   I=ICAPT(J)
   IF(I.GT.IPCLS) GO TO 200
   PRINT 170, I, ITNUM(J-IPARM(3))
200 CONTINUE
   RETURN
   END
   SUBROUTINE DIST(IIST,IICOST,RCXOR,RCYOR,RCXOT,RCYOT,RTXOR,PTYOR,
   *      RYXOT,RYYOT,IPARM,IICAP,ITCIS,ITCIS)
   DIMENSION IIST(50,50),RCXOR(50),RCYOR(50),RCXOT(50),RCYOT(50),
   *      RTXOR(50),PTYOR(50),RYXOT(50),RYYOT(50),RCOST(50),
   *      IPARM(7)
   IRCLS=IPARM(3)
   IF(IICAP.GT.0) IRCLS=IRCLS-1
   IRTRP=IPARM(4)+1

C
C
C   COMPUTE DISTANCES

   RTRCL=FLCAT(IRTRP)/FLCAT(IRCLS)
   DO 110 I=1,IRCLS
   RDXOR=RCXOR(I)
   RYOR=RCYOR(I)
   RDXOT=RCXOT(I)
   RYOT=RCYOT(I)
   IF(RCXOR.GT.0.0.AND.RYOR.GT.0.0.AND.
   *      RCXOT.GT.0.0.AND.RYOT.GT.0.0) GO TO 100
   J=IFIX(RTRCL*FLCAT(I))
   RDXOR=RTXOR(J)
   RYOR=PTYOR(J)
   RDXOT=RTYOT(J)
   RYOT=RTYOT(J)
100 DO 105 J=1,IRTRP
   IF(ITCIS.EQ.1)
   *      DIST=SQRT((RDXOR-RTXOR(J))**2+
   *      (RYOR-RTYOT(J))**2)

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      *      SCB1=((PCXDT-RTXDT(J))**2+
      *      (RCYDT-RTYDT(J))**2)
      IF(IYDIS.EQ.2)
      *      PCDIS1=((PCXDR-RTXDR(J))**2+(RCYDR-RTYDR(J))**2)
      *      (PCSDT-RTXDT(J))**2+(PCADR-RTYDT(J))**2
      IF(IYDIS.EQ.3)
      *      PCDIS1=((PCXDR-RTXDR(J))**2+(RCYDR-RTYDR(J))**2)
      *      ((PCSDT-RTXDT(J))**2+(PCADR-RTYDT(J))**2)
      IDIST(I,J)=RTOL*PCDIS1*PCIST-PCOST(I)*PCJ
105 CONTINUE
      IDIST(I,IRCL+1)=0
110 CONTINUE
      IF(IPCAP.EQ.0) RETURN
      IINCL=IRCL+1
      DO 115 J=1,IINDU
      IDIST(IPCL+1,J)=0
115 CONTINUE
      RETURN
      END
      SUBROUTINE LOCAT(RCXOR,RCYOR,RCXDT,RCYDT,RTXOR,RTYOR,
      *      RTXDT,RTYDT,IONPT,IASST,IPARN,IOCAP,
      *      ITDIS,ISTOP)
      *
      DIMENSION RCXOR(50),RCYOR(50),RCXDT(50),RCYDT(50),
      *      RTXOR(50),RTYOR(50),RTXDT(50),RTYDT(50),
      *      IONPT(100),IASST(100),PCOST(50,50),
      *      RMSOR(50),RMAOR(50),RMBOR(50),RMSOT(50),
      *      RWADT(50),RWBDT(50),IPARN(7)
      DATA RTOL1/0.1/
      IRCLS=IPARN(3)
      IRYEP=IPARN(4)
      RTOL2=SQRT(RTOL1**2/FLCAT(ITDIS))
C
C      GENERATE CLUSTER WEIGHTS
C
      DO 103 I=1,IRCLS
      DO 103 J=1,IRCLP
      PCWGT(I,J)=0.0
100 CONTINUE
      IF(IRCLS.EQ.1) GO TO 110
      DO 105 I=2,IRCLS
      PCWGT(I,IONPT(I)-IRCLS)=FLOAT(IASST(I))
105 CONTINUE
110 IINCL=IRCLS+1
      IINDU=IRCLS+IRYEP
      DO 115 J=IINCL,IINDU
      PCWGT(IONPT(J),J-IRCLS)=FLOAT(IASST(J))
115 CONTINUE
C
C      COMPUTE GRADIENT
C
      RTGRA=0.0
      IINCL=IRCLS
      IF(IOCAP.GT.0) IINDU=IINCL-1
      DO 120 I=1,IINDU
      CALL WSUM1(I,RCXOR(I),RCYOR(I),PCXDT(I),RCYDT(I),RTXOR,
      *      RTYOR,RTXDT,RTYDT,PCWGT,RMSOR(I),RMAOR(I),
      *      RMBOR(I),RMSOT(I),RWADT(I),RWBDT(I),IPARN,ITDIS)
      RTGRA=RTGRA+(RMSOT(I)*RCXOR(I)-RMAOR(I))**2+
      *      (RMSOR(I)*RCYOR(I)-RMBOR(I))**2+
      *      (RMSOT(I)*RCXDT(I)-RWADT(I))**2+
      *      (RMSOT(I)*RCYDT(I)-RWBDT(I))**2
120 CONTINUE
      RTGRA=SQRT(RTGRA)
      IF(RTGRA.GT.RTOL1) GO TO 130

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```

      ISTOP=1
      RETLEN
C
C      UPDATE CLOUD POINTS
C
120 DO 150 I=1, IINDU
   IF (RMSCH(I)/51.0.GT) GO TO 140
   RDXCF(I)=RDXCF(I)+RDXCT(I)+RDXDT(I)+0.0
   GO TO 150
140 RDXCF(I)=RDXCF(I)/RMSCH(I)
   RDCYCF(I)=RDCYCF(I)/RMSCH(I)
   RDXCT(I)=RDXCT(I)/RMSCH(I)
   RDCYCT(I)=RDCYCT(I)/RMSCH(I)
   CALL MSUM1(I, RDXCF(I), RDCYCF(I), RDXCT(I), RDCYDT(I), RTXCF,
*          RTYCF, RTXCT, RTYCT, RMSCH(I), RWACF(I),
*          RWACR(I), RMSCT(I), RWACT(I), RDCR(I), IPARM, ITOIS)
   RPRGR=SQRT((RMSCH(I)+RDXCF(I)-RDCYCF(I))**2+
*          (RMSCH(I)+RDCYCF(I)-RDXCF(I))**2+
*          (RMSCT(I)+RDXCT(I)-RDCYCT(I))**2+
*          (RMSCT(I)+RDCYCT(I)-RDXCT(I))**2)
   IF (RPRGR.GT.RTOL2) GO TO 145
150 CONTINUE
   ISTOP=0
   RETLEN
   END
   SUBROUTINE MSUM1(I, RDXCF, RDCYCF, RDXCT, RDCYDT, RTXCF, RTYCF,
*          RTXCT, RTYCT, RCHGT, RMSCH, RWACF, RWACR,
*          RMSCT, RWACT, RDCR, IPARM, ITOIS)
   DIMENSION RTXCF(50), RTYCF(50), RCHGT(50), RTYDT(50), RCHGT(50,50),
*          IPARM(7)
   DATA REPSL,70.01/
   INTAP=IPARM(4)-1
C
C      COMPUTE SUMS
C
   RMSCH=RWACR+RMSOR=RMSST+RWACT=RMSOT=0.0
   DO 100 J=1, ITRIP
   IF (RCHGT(I,J).LE.0.0) GO TO 100
   IF (ITDIS.EQ.1)
*   RDIST=SQRT((RDXCF-RTXCF(J))**2+(RDCYCF-RTYCF(J))**2*REPSL)
   IF (ITDIS.EQ.2) RDIST=1.0
   IF (ITDIS.EQ.3)
*   RDIST=ABS(RDXCF-RTXCF(J))+ABS(RDCYCF-RTYCF(J))*REPSL
   RMSCH=RMSCH+RCHGT(I,J)/RDIST
   RWACR=RWACR+RCHGT(I,J)*RTXCF(J)/RDIST
   RMSCT=RMSCT+RCHGT(I,J)*RTYCF(J)/RDIST
   IF (ITDIS.EQ.1)
*   RDIST=SQRT((RDXCT-RTXCT(J))**2+(RDCYDT-RTYDT(J))**2*REPSL)
   IF (ITDIS.EQ.2) RDIST=1.0
   IF (ITDIS.EQ.3)
*   RDIST=ABS(RDXCT-RTXCT(J))+ABS(RDCYDT-RTYDT(J))*REPSL
   RMSCT=RMSCT+RCHGT(I,J)/RDIST
   RWACT=RWACT+RCHGT(I,J)*RTXCT(J)/RDIST
   RMSOT=RMSOT+RCHGT(I,J)*RTYDT(J)/RDIST
100 CONTINUE
   RETURN
   END
   SUBROUTINE ROLYE
   COMMON ITCX(50), ITCY(50), ITCXCT(50), ITCYCT(50), ITCOD(50),
*          ITCOS(50), ITCOR(50), ITCOR(50), ITCYCT(50), ITCYCT(50),
*          ITCOT(50), ITCOT(50), ITCOD(50,50), ITCOS(50),
*          ITCOR(50), ITCOR(50)
   DIMENSION ITCOS(50,50), ITCOR(50), ITCOT(50)
   DATA ISACH/999999/, ITCOS/1/

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C
C      FUNCTION 3 - ROUTING
C
C      ENTER ROUTING PARAMETERS & TRIP NUMBER IN ROUTL
C
      REAL*, IRTYP, IINDU, IENDU, ITOTP
      IINDU=IENDU+1
      DO 100 I=1, IRTYP
      READ*, IRLIN
      ITLUM(I)=ITAGN(I)+IRTRP+IRLNLN
      IF (IRLNLN.EQ.1) IINDU=I
      IF (IRLNLN.EQ.1) IENDU=I+IRTRP
100  CONTINUE
C
C      GENERATE COST MATRIX
C
      DO 110 I=1, IRTYP
      DO 110 J=1, IRTYP
      IICCS(I,J)=IRIGH
      IF (I.NE.J)
      * IICCS(I,J)=IDIST(ITDIS, ITXCR(ITLUM(I)), ITYCR(ITLUM(I)),
      *                               ITXCR(ITLUM(J)), ITYCR(ITLUM(J)))
      IICCS(I,J+IRTRP)=IDIST(ITDIS, ITXCR(ITLUM(I)), ITYCR(ITLUM(I)),
      *                               ITXCR(ITLUM(J)), ITYCR(ITLUM(J)))
      IICCS(I+IRTRP,J)=IRIGH
      IICCS(I+IRTRP,J+IRTRP)=IRIGH
      IF ((I+IRTRP).NE.(J+IRTRP))
      * IICCS(I+IRTRP,J+IRTRP)=IDIST(ITDIS, ITXCR(ITLUM(I)),
      *                               ITYCR(ITLUM(I)),
      *                               ITXCR(ITLUM(J)),
      *                               ITYCR(ITLUM(J)))
110  CONTINUE
      IINCU=2*IRTRP
      DO 120 I=1, IINDU
      IICCS(IINDU+1,I)=IRIGH
      IF (I.EQ.IINDU) IICCS(IINDU+1,I)=0
      IF ((I.NE.1) .AND. (IINDU.EQ.0)) IICCS(IINDU+1,I)=0
      IICCS(I,IINDU+1)=IRIGH
      IF (I.EQ.IENDU) IICCS(I,IINDU+1)=0
      IF ((I.GT.1) .AND. (IENDU.EQ.0)) IICCS(I,IINDU+1)=0
120  CONTINUE
      IICCS(IINDU+1,IINDU+1)=IRIGH
      INNCD=2*IRTRP+1
C
C      GENERATE ROUTE
C
      CALL SOLVE(INNCD, IICCS, ICCOS, ICTOR)
C
C      RETURN ROUTE DISTANCE & SEQUENCES
C
      IF (ITOTP.EQ.2) GO TO 175
      DO 130 J=1, INNCD
      IF (ICTOR(J).EQ.INNCD) GO TO 140
130  CONTINUE
140  DO 160 I=1, IRTYP
      J=J+1
      IF (J.GT.INNCD) J=1
      PRINT 150, ITLUM(ICTOR(J))
150  FORMAT (ID,*,*)
160  CONTINUE
      DO 170 I=1, IRTYP
      J=J+1
      IF (J.GT.INNCD) J=1
      PRINT 160, -ITLUM(ICTOR(J))

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170 CONTINUE
C
C   STORE COLUMN
C
175 IF (ICPTR.EQ.1) RETURN
DO 180 I=1, ITRP
  ISCOL(INCOL+1,ITRUP(I))=1
180 CONTINUE
  ISCOL(INCOL+1)=ISCOLS
  INCOL=INCOL+1
  RETURN
END
FUNCTION IDIST(ITDIS,IDXCR,IDYCR,IDXDT,IDYDT)
  IF (ITDIS.EQ.1)
    * IDIST=IPL*(SQRT(FLOAT((IDXCR-IDXDT)**2+(IDYCR-IDYDT)**2))+0.5)
  IF (ITDIS.EQ.2)
    * IDIST=(IDXCR-IDXDT)**2+(IDYCR-IDYDT)**2
  IF (ITDIS.EQ.3)
    * IDIST=IABS(IDXCR-IDXDT)+IABS(IDYCR-IDYDT)
  RETURN
END
SUBROUTINE SOLVE(INNOD,IICCS,IOSCS,IGTOR)
C
C   THIS SUBROUTINE SOLVES THE PROBLEM USING
C   A LEAST-LOWER-BOUND BRANCHING RULE
C
  DIMENSION IICCS(50,50),ISTOR(275),IOTOR(50),INVIS(50),
    * ISPTR(275),IASST(50),ILAND(50),IHAT(50),
    * ICHAT(50),ILIST(50),IMARK(50),IZLIS(100),
    * IREST(12)
  DATA IBICH/999999/,IMSUB/275/,IMSTO/2750/,ICMAX/19999/,
    * IMASS/100/
  RTIME=SECOND(OP)
  INASS=IMSUB=IPTR=0
  IIPTR=1
C
C   INITIALIZE SUBTOUT LIST
C
  ICPTP=1
  IINCU=IMSTO/(INNOD+5)-1
  DO 100 I=1, INNOD
    INPTR=ICPTP+I*INCU+5
    ISTOR(ICPTP)=INPTR
    ICPTP=INPTR
100 CONTINUE
    ISTOR(ICPTP)=0
    IOSCS=INNOD+ICMAX+1
    IREST(11)=0
    IREST(12)=IOSCS
C
C   SOLVE ASSIGNMENT PROBLEM
C
110 CALL HUNGARY(50,100,INNOD,IICCS,IASST,ILAND,IHAT,ICHAT,
    * ILIST,IMARK,IZLIS,IREST)
  IMCCS=IREST(9)+IREST(10)
  INASS=INASS+1
  IF (INASS.GE.IMASS) GO TO 400
115 IF (IMCCS.GE.IOSCS) GO TO 270
C
C   FIND MINIMUM CAPACITY SUBTOUT
C
  INCAP1=INCAP2=IMCCS
  INERT=1
  DO 120 I=1, INNOD

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INVIS(I)=0
120 CONTINUE
130 DO 140 I=1,INNOB
IF (INVIS(I).EQ.0) GO TO 150
140 CONTINUE
GO TO 130
150 INENT=ICENT+1
ICCAR1=0
DO 160 I=1,INNOB
INENT=IASST(INENT)
IF (INVIS(I).EQ.0) GO TO 170
INVIS(I)=1
IF (ICCAR1+INENT).LT.0) ICCAR1=ICCAR1-1
160 CONTINUE
170 ICCAR1=ICCAR1+I-1
ICCAR2=I-1
IF (ICCAR1.GE.INCAR1) GO TO 130
INCAR1=ICCAR1
INCAR2=ICCAR2
INENT=ICENT
GO TO 130
180 IF (INCAR2.LT.INNOB) GO TO 240
C
C   SAVE MINIMUM COST TOUR
C
ICCCS=IMCCS
INENT=INENT
DO 190 I=1,INNOB
INENT=IASST(INENT)
ICTCR(I)=INENT
190 CONTINUE
IF (INSLB.EQ.0) GO TO 270
C
C   REMOVE PATHOED SUBPROBLEMS
C
DO 230 I=1,INSUB
200 IF (ISTOR(ISPTR(I)+2).LY.ICCCS) GO TO 230
IRPTR=ISPTR(I)
210 IPTR=ISTOR(IRPTR)
ISTOR(IRPTR)=IRPTR
IIPTR=IRPTR
IF (ISPTR.EQ.0) GO TO 220
ISTOR(IPTR+3)=ISTOR(IPTR+3)-1
IF (ISTOR(IPTR+3).GT.0.AND.ISPTR.EQ.ISPTR) GO TO 220
IRPTR=IPTR
GO TO 210
220 ISPTR(I)=ISPTR(INSUB)
INSLB=INSUB-1
IF (I.LE.INSUB) GO TO 200
230 CONTINUE
GO TO 270
C
C   ADD SUETCUT TO LIST
C
240 IF (IIPTR.GT.0) GO TO 250
GO TO 400
250 IAPTR=IIPTR
IIPTR=ISTOR(IIPTR)
IF (INSLB.LT.INSUB) GO TO 260
GO TO 400
260 INSLB=INSUB+1
ISPTR(INSUB)=IAPTR
ISTOR(IAPTR)=ISPTR

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ISTOR(IAPTR+1)=IACD
ISTOR(IAPTR+2)=IACOS
ISTOR(IAPTR+3)=1
ISTOR(IAPTR+4)=INCAS2
IRENT=IPLAT
DO 265 I=1, INCAS2
IRENT=IRENT
IRENT=IASS(I, IRENT)
IF (IICOS(IPLAT, IRENT).LT.0) IRENT=-IRENT
ISTOR(IAPTR+4)=IRENT
265 CONTINUE
IF (IPTR.EQ.0) GO TO 315
ISTOR(IPTR+3)=ISTOR(IPTR+3)+1
C
C
C   RESTORE ARCS
270 IF (IPTR.EQ.0) GO TO 315
IIRCW=ISTOR(IPTR+ISNCD+4)
IICOL=IABS(ISTOR(IPTR+ITNCD+4))
IICOS(IIRCW, IICOL)=IICOS(IIFOW, IICOL)-IBIGM
IF ((ILAND(IIRCW)+ICHAT(IICOL)).LE.IICOS(IIRCW, IICOL))
*   GO TO 275
IREST(9)=IREST(9)+IICOS(IIRCW, IICOL)
*   -ILAND(IIRCW)-ICHAT(IICOL)
ILAND(IIFOW)=IICOS(IIRCW, IICOL)-ICHAT(IICOL)
275 IIRCW=ISNCD
ISNCD=ISNCD+1
IF (ISNCD.LE.ISCAR) GO TO 360
IINLU=ISCAR-1
DO 280 I=1, IINLU
IIRCW=ISTOR(IPTR+I+4)
IF (IIRCW.LT.0) GO TO 285
IICOL=IABS(ISTOR(IPTR+I+5))
IICOS(IIRCW, IICOL)=IICOS(IIFOW, IICOL)-IBIGM
IREST(9)=IREST(9)-IBIGM
280 CONTINUE
ISNCD=ISTOR(IPTR+1)
IPTR=ISTOR(IPTR)
285 IF (IPTR.EQ.0) GO TO 365
ISCAR=ISTOR(IPTR+4)
IIRCW=ISTOR(IPTR+ISNCD+4)
ITNCD=ISNCD+1
IF (ITNCD.GT.ISCAR) ITNCD=1
IICOL=IABS(ISTOR(IPTR+ITNCD+4))
IICOS(IIFOW, IICOL)=IICOS(IIFOW, IICOL)-IBIGM
IF ((ILAND(IIFOW)+ICHAT(IICOL)).LE.IICOS(IIFOW, IICOL))
*   GO TO 290
IREST(9)=IREST(9)+IICOS(IIFOW, IICOL)
*   -ILAND(IIFOW)-ICHAT(IICOL)
ILAND(IIFOW)=IICOS(IIFOW, IICOL)-ICHAT(IICOL)
290 IINLU=ISNCD-1
IF (IINLU.LT.1) GO TO 300
DO 295 I=1, IINLU
IIRCW=ISTOR(IPTR+I+4)
IF (IIRCW.LT.0) GO TO 295
IICOL=IABS(ISTOR(IPTR+I+5))
IICOS(IIFOW, IICOL)=IICOS(IIFOW, IICOL)-IBIGM
IREST(9)=IREST(9)-IBIGM
295 CONTINUE
300 ISNCD=ISTOR(IPTR+1)
IPTR=ISTOR(IPTR)
GO TO 235
C
C   REMOVE UNBRANCHED PROBLEM

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C
305 IPPTR=IPPTR
310 IF (ISTOR(IPPTR+2).GT.0) GO TO 315
  IPPTR=IPPTR
  IPPTR=ISTOR(IPPTR)
  ISICR(IPPTR)=IIPYR
  IIPYR=IPPTR
  IF (IPPTR.EQ.0) GO TO 315
  ISTOR(IPPTR+2)=ISTOR(IPPTR+2)-1
  GO TO 310
C
C
C
315 IF (INSUB.EQ.0) GO TO 400
  IBPTR=0
  IBCCS=IBIGH
  DO 320 I=1,INSUB
    IF (ISTOR(ISPTR(I)+2).GE.IBCCS) GO TO 320
    IBPTR=ISPTR(I)
    IBIND=I
    IBCCS=ISTOR(IBPTR+2)
320 CONTINUE
  IF (IPYR.EQ.0) GO TO 400
  ISPTR(IBIND)=ISPTR(INSUB)
  INSUB=INSUB-1
C
C
C
  ISNCD=ISTOR(IPPTR+1)
  IPPTR=ISTOR(IPPTR)
330 IF (IPPTR.EQ.0) GO TO 350
  ISCAR=ISTOR(IPPTR+3)
  IIRCW=ISTOR(IPPTR+ISNCD+4)
  ITACD=ISNCD+1
  IF (ITACD.GT.ISCAR) ITACD=1
  IICCL=IABS(ISTOR(IPPTR+ITACD+4))
  IICCS(IIRCW,IICCL)=IICCS(IIRCW,IICCL)+IBIGH
  IINEL=ISNCD-1
  IF (IINEL.LT.1) GO TO 345
  DO 340 I=1,IINEL
    IIRCW=ISTOR(IPPTR+I+4)
    IF (IIRCW.LT.0) GO TO 340
    IICCL=IABS(ISTOR(IPPTR+I+5))
    IICCS(IIRCW,IICCL)=IICCS(IIRCW,IICCL)-IBIGH
    IREST(9)=IREST(9)+IBIGH
    IF ((ILAND(IIRCW)+ICHAT(IICCL)).LT.IICCS(IIRCW,IICCL))
      * GO TO 340
    IREST(9)=IREST(9)+IICCS(IIRCW,IICCL)
    * -ILAND(IIRCW)-ICHAT(IICCL)
    ILAND(IIRCW)=IICCS(IIRCW,IICCL)-ICHAT(IICCL)
340 CONTINUE
345 ISNCD=ISTOR(IPPTR+1)
  IPPTR=ISTOR(IPPTR)
  GO TO 330
350 ISNCD=1
  IPNCD=0
  ISCAR=ISTOR(IPPTR+4)
360 IIRCW=ISTOR(IPPTR+ISNCD+4)
  IF (IIRCW.GT.0) GO TO 365
  ISNCD=ISNCD+1
  GO TO 360
365 ITACD=ISNCD+1
  IF (ITACD.GT.ISCAR) ITACD=1
  IICCL=IABS(ISTOR(IPPTR+ITACD+4))

```


C

```

C
L=1
DO 900 I=1,M
  K(1)=999
  K(2)=999
  K(3)=999
  DO 901 J=1,M
    IF (J.EQ.I) GOTO 902
    IF (S(I,J).GT.K(3)) GOTO 901
    IF (S(I,J).GT.K(2)) GOTO 901
    IF (S(I,J).GT.K(1)) GOTO 901
    K(3)=K(2)
    K(2)=K(1)
    O(3)=O(2)
    O(2)=O(1)
    K(1)=S(I,J)
    O(1)=J
  GOTO 901
110 K(3)=K(2)
  O(3)=O(2)
  K(2)=S(I,J)
  O(2)=J
  GOTO 901
140 K(3)=S(I,J)
  O(3)=J
901 CONTINUE
DO 902 J=1,3
  G(L,1)=L
  G(L,2)=I+J
  G(L,3)=O(J)
  G(L,4)=0
  G(L,5)=1
  G(L,6)=K(J)
  L=L+1
902 CONTINUE
900 CONTINUE
M3=3*M

C
C      DEFINING THE THREE DESTINATION POINTS CLOSEST TO EACH ORIGIN
C
L=1
DO 905 J=1,M
  K(1)=999
  K(2)=999
  K(3)=999
  DO 906 I=1,M
    IF (J.EQ.I) GOTO 906
    IF (S(I,J).GT.K(3)) GOTO 906
    IF (S(I,J).GT.K(2)) GOTO 906
    IF (S(I,J).GT.K(1)) GOTO 906
    K(3)=K(2)
    K(2)=K(1)
    O(3)=O(2)
    O(2)=O(1)
    O(1)=I
    K(1)=S(I,J)
  GOTO 906
210 K(3)=K(2)
  O(3)=O(2)
  O(2)=I
  K(2)=S(I,J)
  GOTO 906
240 K(3)=S(I,J)
  O(3)=J

```



```

DO 110 I=1,NCOL
  ICLHS(I)=0
110 CONTINUE
C
C  COMPUTE THE COST LIST FOR EACH COLUMN & SELECT
C  MINIMUM COST COLUMN
C
115  I=COLNBT+1;I=0
  IMIND=0
  DO 120 J=1,INTRP
    ITCV=0
    RDCS=LOCAT(RSCS(I))
    DO 125 J=1,INTRP
      IF (ISCOL(I,J).EQ.0) GO TO 120
      IF (ICLHS(J).GT.0) GO TO 125
      ITCV=ITCV+1
      RDCS=RDCS+RSCS(J)
120  CONTINUE
      IF (ITCV.GT.0) GO TO 135
      IF (RDCS.GE.RDCS) GO TO 130
      RDCS=RDCS
      IMIND=J
130  CONTINUE
      IF (IMIND.EQ.0) GO TO 370
C
C  ADD MINIMUM COST COLUMN TO SOLUTION
C
      ICCAR=ICCAR+1
      ICSOL(ICCAR)=IMIND
C
C  UPDATE LEFT-HAND-SIDE
C
      DO 140 I=1,INTRP
        IF (ISCOL(IMIND,I).EQ.0) GO TO 160
        ICLHS(I)=ICLHS(I)+1
        IF (ICLHS(I).GT.1) GO TO 140
        ITCV=ITCV+1
140  CONTINUE
        IF (ITCV.LT.INTRP) GO TO 115
C
C  REDUCE SET COVER TO PRIME COVER
C
      DO 170 I=1,ICCAR
        ITCV=0
145  DO 150 J=1,INTRP
          IF (ISCOL(I,J).EQ.0) GO TO 150
          IF (ICLHS(J).GT.1) GO TO 150
          ITCV=ITCV+1
150  CONTINUE
          IF (ITCV.GT.0) GO TO 170
          DO 160 J=1,INTRP
            IF (ISCOL(I,J).EQ.0) GO TO 160
            ICLHS(J)=ICLHS(J)-1
160  CONTINUE
            ICSOL(I)=ICSOL(ICCAR)
            ICCAR=ICCAR+1
            IF (I.EQ.ICCAR) GO TO 145
170  CONTINUE
C
C  COMPUTE COSTS FOR COVER
C
      ICCCC=0
      DO 180 I=1,ICCAR
        ICCCC=ICLHS(I)+ISCON(ICSOL(I))

```

[illegible]

B-4

Chromatics (BASIC)
Data Generation Programs
and Menu Data Sets for
Delivery

[illegible]


```

15340 PRINT "T1":
15350 RETURN
15400 REM *** 15400 DRAW UP AND DO COLOR C
15410 PRINT "COLOR: DRAWING USING " # "C":
15420 PRINT "T1":
15430 PLOT JN(100,1),JN(100,1)+500:PRINT "00/TL":CHR$(121):"0":
15440 PLOT JN(100,1)+500,JN(100,1)+10
15450 PRINT USING "###":JN(100,1)+500:PRINT "00":
15460 RETURN
15500 REM *** 15500 DRAW FRIF DO, COLOR C
15510 PRINT "FRIF: DRAWING USING " # "C":
15520 PRINT "T1":
15530 P1=TP(100,1):P2=TP(100,2)
15540 PLOT JN(P1,1),JN(P1,2),JN(P2,1),JN(P2,2)
15550 XN=(JN(P1,1)+JN(P2,1))/2
15560 YN=(JN(P1,2)+JN(P2,2))/2
15570 PRINT "TL":CHR$(121):"TL":PLOT XN,YN:PRINT USING "##":TP(100,1)
15580 PRINT "00":
15590 RETURN
15600 REM *** 15600 DISPLAY ERROR EA IN WINDOW
15610 PRINT "*****11,510110TC7":CHR$(121):CHR$(12):EA:"7320"
15620 PRINT CHR$(121):"0":
15630 RETURN
20000 REM ***** SHORTEST PATH ALGORITHM *****
20100 REM INITIALIZATION OF THE DISTANCE MATRIX
20110 DIM C(MJ,MJ)
20120 FOR I=1 TO MJ:FOR J=I TO MJ:D(I,J)=9999:IF J=I THEN D(I,J)=0:NEXT J:D(I,1)=0:NEXT I
20130 FOR K=1 TO MJ:I=TP(K,1):J=TP(K,2)
20140 D(I,J)=IP(K,3)+C(J,1)+TP(K,3)
20150 NEXT K
20160 PRINT "INITIALIZATION COMPLETE"
20170 PRINT "PJ" PASSES TO GO"
20180 REM *** SOLVE SHORTEST PATH ***
20190 FOR J=1 TO MJ:FOR I=1 TO MJ
20200 D(I,J)=1000000+I
20210 NEXT J:NEXT I
20220 FOR I=1 TO MJ:FOR J=1 TO MJ
20230 IF J=1 THEN 20320
20240 IF D(I,1)>=9900 THEN 20320
20250 FOR K=1 TO MJ
20260 IF D(I,K)=9900 THEN 20310
20270 S=(C(J,1)+D(I,K))/100+TP(J,K)/100
20280 IF S<T THEN D(I,K)=S*100+(D(I,K)-INT(D(I,K)/100)*100)
20290 NEXT K
20300 NEXT J
20310 NEXT I
20320 PRINT "PASS " # "T1": "COMPLETE"
20330 NEXT I
20340 DOS"ARYSAVE " # "S" # "0"
20350 ERASE C
20360 RETURN
20400 REM *** PRINT PATH SOLUTION ***
20410 PRINT "TAS,0,510510T00,500":CHR$(121):CHR$(12):
20420 FOR L1=1 TO MJ:FOR L2=1 TO MJ
20430 PRINT USING "###":D(L1,L2):
20440 NEXT L2:PRINT " " # "NEXT L1"
20450 INPUT "TC7CONTINUE" # "A"
20460 RETURN

```

10,16

5,10,55,4,4

5,55,55,4,2

15,55,115,40,4

65,55,115,40,3

125,15,175,40,4

125,55,175,40,2

185,15,235,40,4

185,55,235,40,2

245,15,295,40,4

245,55,295,40,3

17,13,4,"DEL"

77,13,4,"DEL"

137,13,4,"DEL"

197,13,4,"DEL"

257,13,6,"SAVE"

17,53,2,"ADD"

77,53,2,"ADD"

137,53,2,"ADD"

197,53,2,"ADD"

254,53,3,"RENEW"

65,108,7,"DELIVERY PROBLEM GENERATOR"

6,95,1,"JUNCTION"

68,95,2,"FACILITY"

134,95,4,"DEPART"

267,95,5,"ARCHIVE"

196,95,1,"HOLTF"

B-5

Chromatics (BASIC)
Display, Optimization and Data Manipulation
Programs and Menu Data Sets for
Delivery

[illegible]


```

3200 *
3205 J=1
3210 IF (J=1) THEN GOTO 3215 ELSE GOTO 3220
3215 PRINT "STARTING ROUTE 1"
3220 GOTO 3225
3225 GOTO 3230
3230 GOTO 3235
3235 GOTO 3240
3240 GOTO 3245
3245 GOTO 3250
3250 GOTO 3255
3255 GOTO 3260
3260 GOTO 3265
3265 GOTO 3270
3270 GOTO 3275
3275 GOTO 3280
3280 GOTO 3285
3285 GOTO 3290
3290 GOTO 3295
3295 GOTO 3300
3300 *
3305 MENU 2 - BUILD - BEGIN ROUTE
3310 *
3315 GOSUB 15000
3320 GOTO 3325
3325 *
3330 MENU 2 - BUILD - END ROUTE
3335 *
3340 IF RT(1)=RT(10) THEN 3345
3345 PRINT "INCOMPLETE" GOSUB 15000:GOTO 3350
3350 PRINT "CYCLE RE-ROUTING"
3355 IF RT(1)=RT(10) THEN GOTO 3360
3360 PRINT "RE-ROUTING HERE AFTER THE CHANGING"
3365 GOSUB 15000
3370 FOR J=2 TO NR-1
3375 DD=RT(J)+K*100
3380 IF TD=0 THEN TD=1
3385 JN(K,5)=(TD+TD)*2+NR-DD*RT(1)
3390 C=3:IF DS=0 THEN C=0
3395 GOSUB 7000
3400 C=0:GOSUB 15000:GOTO 3405
3405 JN(K,5)=2
3410 NEXT J
3415 GOSUB 3700
3420 NR=3:TD=0:TS=0:TS=0
3425 GOTO 3430
3430 *
3435 MENU 2 - RESTART ROUTE
3440 *
3445 GOSUB 15000
3450 TD=0:TD=0:TS=0:NR=0:AM=0:AL=0:ST=0
3455 FOR J=1 TO NJ
3460 IF JN(J,3)=2 THEN DD=J:GOTO 3465
3465 NEXT J
3470 GOTO 3475
3475 *
3480 MENU 2 - BACK-UP ROUTE
3485 *
3490 IF NR=0 THEN GOTO 3495 ELSE IF NR=1 THEN F1=1:GOTO 3495
3495 C=0:PRINT "34":GOSUB 4700:PRINT "34":F1
3500 JN(RT(NR),5)=0
3505 DD=RT(NR):C=4:GOSUB 15000
3510 NR=NR-1
3515 C=7:PRINT "34":GOSUB 4700:PRINT "34":F1
3520 F1=1:GOTO 3495
3525 *
3530 MENU 2 - SAVE ROUTE IN ARCHIVE
3535 *
3540 JN(RT(NR)+1,5)=AL+1
3545 FOR J=1 TO NR-1

```

[illegible]

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```

[illegible]

```

5140 IF J1=1 THEN GOTO 5150
5150 IF J1=2 THEN GOTO 5160
5160 GOTO 5170
5170 IF J1=1 THEN GOTO 5180
5180 GOTO 5190
5190 PRINT "*****"
5200 GOTO 5210
5210 IF J1=1 THEN GOTO 5220
5220 IF J1=2 THEN GOTO 5230
5230 GOTO 5240
5240 ON J1 GOTO 5250,5260,5270
5270 GOTO 5280
5280 *
5290 * MENU 4 - EDIT DELETE
5300 *
5310 IF J1=1 THEN GOTO 5320
5320 IF J1=2 THEN GOTO 5330
5330 GOTO 5340
5340 ON J1 GOTO 5350,5360,5370
5370 GOTO 5380
5380 *
5390 * MENU 4 - EDIT ADD FACILITY
5400 *
5410 IF J1=1 THEN GOTO 5420
5420 IF J1=2 THEN GOTO 5430
5430 IF J1=3 THEN GOTO 5440
5440 GOTO 5450
5450 ON J1 GOTO 5460,5470,5480
5480 GOTO 5490
5490 *
5500 * MENU 4 - EDIT ADD DEMAND
5510 *
5520 IF J1=1 THEN GOTO 5530
5530 IF J1=2 THEN GOTO 5540
5540 IF J1=3 THEN GOTO 5550
5550 GOTO 5560
5560 ON J1 GOTO 5570,5580,5590
5590 GOTO 5600
5600 *
5610 * MENU 4 - SPECIFY ACTIVE ROUTE AREA
5620 *
5630 IF X1<>0 THEN GOTO 5640
5640 IF X2<>0 THEN GOTO 5650
5650 X1=X1-Y1-Y2:PRINT CHR$(7):"GOTO 5660":GOTO 5660
5660 X2=X1-Y2-Y1
5670 X=X1 MAX X2:X1=X1 MIN X2:X2=X1
5680 Y=Y1 MAX Y2:Y1=Y1 MIN Y2:Y2=Y1
5690 PRINT "*****":GOTO 5690
5700 ON J1 GOTO 5710,5720,5730
5740 IF J1=1 THEN GOTO 5750
5750 GOTO 5760
5760 GOTO 5770
5770 *
5780 * MENU 4 - SPECIFY ACTIVE POINT PAIRS

```

```

5900 *
5901 *
5902 * MENU 4 - EXIT FORWARD TO MENU 2
5903 *
5904 *
5905 GOTO 4900
6000 *
6001 * MENU 5 - DISPLAY MENU SET-UP
6002 *
6003 PRINT "M1,1,510112":GOTO(12,1)"GOTO"3300,33011":
6004 GOTO 11000
6005 GOTO 11000
6006 F1=0:F2=0:F3=0:F4=0:F5=0
6007 F1=0:F2=0:F3=0:F4=0:F5=0
6008 F1=0:F2=0:F3=0:F4=0:F5=0
6009 F1=0:F2=0:F3=0:F4=0:F5=0
6010 *
6011 * MENU 5 - DISPLAY LIGHT PEN INTER-OBJECT ACQUISITION
6012 *
6013 ON ERROR GOTO 6120
6014 GOTO 6115
6015 X=0:Y=0:Z=0:V=0:W=0
6016 IF X>111 THEN 6020
6017 PRINT "M1,112100107/8":GOTO(12,1)"GOTO"
6018 GOTO 12000
6019 F1=1:IF F1=0 THEN 6000
6020 IF F1=1 THEN 6000
6021 IF F1=2 THEN 6000
6022 IF F1=3 THEN 6000
6023 GOTO 6000
6024 *
6025 * MENU 5 - DISPLAY PLOT REGION HIT ROUTINE
6026 *
6027 IF F1=4 THEN 6000
6028 GOSUB 10100:IF I=0 THEN 6000
6029 GOTO 6000
6030 *
6031 * MENU 5 - DISPLAY PRICES (ON/OFF)
6032 *
6033 DS=1-DS+0:IF DS=0 THEN 6040
6034 FOR K2=1 TO 10:GOTO(12,1)"GOTO"7400
6035 NEXT K2
6036 GOTO 3300
6037 *
6038 * MENU 5 - DISPLAY SAVINGS
6039 *
6040 DV=1-DV+0:IF DV=0 THEN 6050
6041 IF DV=1 THEN GOSUB 7000:GOSUB 9000
6042 PRINT "M1,112100107/8":GOTO(12,1)"GOTO"
6043 GOTO 6000
6044 *
6045 * MENU 5 - DISPLAY PRICE
6046 *

```


[illegible]

[illegible]

```

00000 * ***** COLOR PERU DRAW ROUTINE - MENU M ***
00010 PRINT "DRAW"
00020 FOR I=1 TO 4
00030   FOR J=1 TO 4
00040     GOTO 00050
00050   GOTO 00060
00060   GOTO 00070
00070   GOTO 00080
00080   GOTO 00090
00090   GOTO 00100
00100   GOTO 00110
00110   GOTO 00120
00120   GOTO 00130
00130   GOTO 00140
00140   GOTO 00150
00150   GOTO 00160
00160   GOTO 00170
00170   GOTO 00180
00180   GOTO 00190
00190   GOTO 00200
00200   GOTO 00210
00210   GOTO 00220
00220   GOTO 00230
00230   GOTO 00240
00240   GOTO 00250
00250   GOTO 00260
00260   GOTO 00270
00270   GOTO 00280
00280   GOTO 00290
00290   GOTO 00300
00300   GOTO 00310
00310   GOTO 00320
00320   GOTO 00330
00330   GOTO 00340
00340   GOTO 00350
00350   GOTO 00360
00360   GOTO 00370
00370   GOTO 00380
00380   GOTO 00390
00390   GOTO 00400
00400   GOTO 00410
00410   GOTO 00420
00420   GOTO 00430
00430   GOTO 00440
00440   GOTO 00450
00450   GOTO 00460
00460   GOTO 00470
00470   GOTO 00480
00480   GOTO 00490
00490   GOTO 00500
00500   GOTO 00510
00510   GOTO 00520
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00670   GOTO 00680
00680   GOTO 00690
00690   GOTO 00700
00700   GOTO 00710
00710   GOTO 00720
00720   GOTO 00730
00730   GOTO 00740
00740   GOTO 00750
00750   GOTO 00760
00760   GOTO 00770
00770   GOTO 00780
00780   GOTO 00790
00790   GOTO 00800
00800   GOTO 00810
00810   GOTO 00820
00820   GOTO 00830
00830   GOTO 00840
00840   GOTO 00850
00850   GOTO 00860
00860   GOTO 00870
00870   GOTO 00880
00880   GOTO 00890
00890   GOTO 00900
00900   GOTO 00910
00910   GOTO 00920
00920   GOTO 00930
00930   GOTO 00940
00940   GOTO 00950
00950   GOTO 00960
00960   GOTO 00970
00970   GOTO 00980
00980   GOTO 00990
00990   GOTO 01000
01000   GOTO 01010
01010   GOTO 01020
01020   GOTO 01030
01030   GOTO 01040
01040   GOTO 01050
01050   GOTO 01060
01060   GOTO 01070
01070   GOTO 01080
01080   GOTO 01090
01090   GOTO 01100
01100   GOTO 01110
01110   GOTO 01120
01120   GOTO 01130
01130   GOTO 01140
01140   GOTO 01150
01150   GOTO 01160
01160   GOTO 01170
01170   GOTO 01180
01180   GOTO 01190
01190   GOTO 01200
01200   GOTO 01210
01210   GOTO 01220
01220   GOTO 01230
01230   GOTO 01240
01240   GOTO 01250
01250   GOTO 01260
01260   GOTO 01270
01270   GOTO 01280
01280   GOTO 01290
01290   GOTO 01300
01300   GOTO 01310
01310   GOTO 01320
01320   GOTO 01330
01330   GOTO 01340
01340   GOTO 01350
01350   GOTO 01360
01360   GOTO 01370
01370   GOTO 01380
01380   GOTO 01390
01390   GOTO 01400
01400   GOTO 01410
01410   GOTO 01420
01420   GOTO 01430
01430   GOTO 01440
01440   GOTO 01450
01450   GOTO 01460
01460   GOTO 01470
01470   GOTO 01480
01480   GOTO 01490
01490   GOTO 01500
01500   GOTO 01510
01510   GOTO 01520
01520   GOTO 01530
01530   GOTO 01540
01540   GOTO 01550
01550   GOTO 01560
01560   GOTO 01570
01570   GOTO 01580
01580   GOTO 01590
01590   GOTO 01600
01600   GOTO 01610
01610   GOTO 01620
01620   GOTO 01630
01630   GOTO 01640
01640   GOTO 01650
01650   GOTO 01660
01660   GOTO 01670
01670   GOTO 01680
01680   GOTO 01690
01690   GOTO 01700
01700   GOTO 01710
01710   GOTO 01720
01720   GOTO 01730
01730   GOTO 01740
01740   GOTO 01750
01750   GOTO 01760
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01770   GOTO 01780
01780   GOTO 01790
01790   GOTO 01800
01800   GOTO 01810
01810   GOTO 01820
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01890   GOTO 01900
01900   GOTO 01910
01910   GOTO 01920
01920   GOTO 01930
01930   GOTO 01940
01940   GOTO 01950
01950   GOTO 01960
01960   GOTO 01970
01970   GOTO 01980
01980   GOTO 01990
01990   GOTO 02000
02000   GOTO 02010
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[illegible]


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165, 30, 265, 80, 7

235, 30, 275, 80, 7

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245, 30, 285, 80, 7

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185, 30, 225, 80, 7

32, 27, 5, "HEAD"

250, 27, 5, "FOOT"

268,16,2,"FILLIN"

26,16,4,"FILLIN"

101,27,1,"FILLIN"

101,16,2,"FILLIN"

173,16,1,"FILLIN"

366,16,2,"FILLIN"

30,95,7,"INTERACTIVE ROUTING - INITIALIZATION"

16,27,2,"LOCATE"

19,16,2,"LOCATE"

60,27,6,"LOCATE"

74,16,6,"LOCATE"

115,27,6,"LOCATE"

170,27,5,"INSERT"

125,27,3,"INSERT"

208,27,7,"EXIT"

67,95,7,"INTERACTIVE ROUTING - TOL BUILDING"

7,27,6,"LOCATE"

7,16,6,"INSERT"

67,27,2,"PRICE"

63,16,2,"INSERT"

125,27,4,"INSERT"

186,27,7,"DELETE"

251,27,7,"EXIT"

2,95,7,"INTERACTIVE ROUTING - DEMAND INSERTION"

7,27,6,"DELETE"

79,27,2,"ALD"

60,16,2,"FACILITY"

139,27,4,"ADD"

126,16,4,"DEMAND"

191,27,7,"EXIT"

2,95,7,"INTERACTIVE ROUTING - TOL BUILDING"

7,27,6,"DELETE"

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B-6

Cyber (FORTRAN)
Optimization Programs for
Delivery

```

PROGRAM ITS-CONVEX,OLIPOL-IPRACON,MLT)
DIMENSION ITCOS(50,50),ITCOT(2750),ITCOTN(50),ITCOTIS(50)
DATA ISIGH/99999999/,INSUE/275/,INSTO/2750/,TCHMX/99999999/,
C
C   ENTER DATA
C
10  REAL*, ITNUM
   DO 100 I=1,ITNUM
     READ*, ITCOS(I),ITCOT(I)
100 CONTINUE
C
C   GENERATE COST MATRIX
C
   DO 110 I=1,ITNUM
     DO 110 J=1,ITNUM
       ITCOS(I,J)=ITCOT(100.0*SQRT((ITCOT(I)-ITCOT(J))**2.
*                                     (ITCOT(I)-ITCOT(J))**2.))
       IF(I.EQ.J) ITCOS(I,J)=ISIGH
110 CONTINUE
C
C   SOLVE ISP
C
   CALL SOLVE1(ITNUM,ITCOS,ITCOS,ITCOT)
C
C   PRINT SOLUTION
C
   DO 120 I=1,ITNUM
     IF(ITCOT(I).EQ.1) GO TO 130
120 CONTINUE
130 CONTINUE
   DO 140 J=1,ITNUM
     WRITE(6,135) ITCOT(I)
135 FORMAT(I15)
     I=I+1
     IF(I.GT.ITNUM) I=1
140 CONTINUE
     WRITE(6,135) ITCOS
     GO TO 13
   END
   SUBROUTINE SOLVE1(INNCD,ITCOS,ITCOS,ITCOT)
C
C   THIS SUBROUTINE SOLVES THE PROBLEM USING
C   A LEAST-LOWER-BOUND BRANCHING RULE
C
   DIMENSION ITCOS(50,50),ITCOT(2750),ITCOTN(50),ITCOTIS(50),
*             ISPTR(275),IPASS(50),ILAND(50),IIPAR(50),
*             ICHAT(50),ILIST(50),IPARK(50),IZLTS(100),
*             INEST(12)
   DATA ISIGH/99999999/,INSUE/275/,INSTO/2750/,TCHMX/99999999/,
*       IPASS/10000/
   RTIME=SECOND(OP)
   INASS=INSUB=IPYR=0
   IIPR=1
C
C   INITIALIZE SUBTOUT LIST
C
   ICPTR=1
   IINCU=IPCTO/(INNOB*5)-1
   DO 100 I=1,INNOB
     INPIA=ICPTR+IINCU+5
     ITCOT(ICPTR)=INPIA
     ICPTR=INPIA
100 CONTINUE
     ISIPR(ICPTR)=0

```

```

      ICCOS=IACOS*(ICAP+1)
      ITEST(11)=0
      ITEST(12)=ICCOS
C
C      SOLVE ASSIGNMENT PROBLEM
C
110 CALL FLAGARY(100,INMOD,ICCOS,IACOS,IACAP,INMOD,ICAP,
      * ITEST,ISTOR,IPPTR,IPTR,IPTR)
      ICCOS=ITEST(11)-ITEST(12)
      INASS=IACAP+1
      IF(INASS.GE.IACOS) GO TO 115
115 IF(ICCOS.GE.ICCOS) GO TO 270
C
C      FIND MINIMUM COST SUBGRAPH
C
      IMCAR1=IMCAR2=IACOS
      IMENT=1
      DO 120 I=1,INMOD
      INVIS(I)=0
120 CONTINUE
130 DO 140 I=1,INMOD
      IF(INVIS(I).EQ.0) GO TO 150
140 CONTINUE
      GO TO 180
150 IMENT=ICENT+I
      ICCAR1=0
      DO 160 I=1,INMOD
      IPENT=IMENT
      INENT=IASST(IMENT)
      IF(INVIS(INENT).EQ.1) GO TO 170
      INVIS(INENT)=1
      IF((ICOS(IPENT,INENT).LT.0) ICCAR1=ICCAR1-1
160 CONTINUE
170 ICCAR1=ICCAR1+I-1
      ICCAR2=1-1
      IF(ICCAR1.GE.ICCAR1) GO TO 130
      IMCAR1=ICCAR1
      IMCAR2=ICCAR2
      IMENT=ICENT
      GO TO 130
180 IF(IMCAR2.LT.INMOD) GO TO 240
C
C      SAVE MINIMUM COST TOUR
C
      ICCOS=IMCOS
      IMENT=IMENT
      DO 190 I=1,INMOD
      INENT=IASST(IMENT)
      IOTCR(I)=INENT
190 CONTINUE
      IF(INMOD.EQ.0) GO TO 270
C
C      REMOVE PATHED SUBPROBLEMS
C
      DO 230 I=1,INSUB
200 IF(ISTOR(ISPTR(I)+2).LT.ICCOS) GO TO 230
      IPTR=ISPTR(I)
210 IPTR=ISTOR(IPTR)
      ISTOR(IPTR)=IPTR
      IIPTR=IPTR
      IF(IIPTR.EQ.0) GO TO 220
      ISTOR(IPTR+3)=ISTOR(IPTR+3)-1
      IF(ISTOR(IPTR+3).GE.0) IPTR=IPTR+1 GO TO 220
      IIPTR=IPTR

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      GO TO 210
200  ISPIR(I)=ISPIR(INSUB)
      INSUB=INSUB+1
      IF(I.LT.INSC) GO TO 200
230  CONTINUE
      GO TO 270
C
C      ADD SUBTCLR TO LIST
C
240  IF(IIPTR.GT.0) GO TO 240
      GO TO 400
250  IAPTR=IIPTR
      IIPTR=ISTOR(IIPTR)
      IF(IASLB.LT.IPBLS) GO TO 250
      GO TO 400
260  INSUB=INSUB+1
      ISPIR(INSUB)=IAPTR
      ISTOR(IAPTR)=IBPTR
      ISTOR(IAPTR+1)=ISACD
      ISTOR(IAPTR+2)=IMCOS
      ISTOR(IAPTR+3)=0
      ISTOR(IAPTR+4)=IMCAR2
      INENT=INENT
      DO 265 I=1,IMCAR2
      IPENT=INENT
      INENT=IASST(INENT)
      IF(IICOS(IPENT,INENT).LT.0) IPENT=-IPENT
      ISTOR(IAPTR+4)=IPENT
265  CONTINUE
      IF(IBPTR.EQ.0) GO TO 315
      ISTOR(IBPTR+3)=ISTOR(IGRIF+3)+1
C
C      RESTORE ARCS
C
270  IF(IBPTR.EQ.0) GO TO 315
      IIRCW=ISTOR(IBPTR+ISACD+4)
      IICCL=IAS(ISTOR(IBPTR+IMCD+4))
      IICOS(IIRCW,IICCL)=IICOS(IIFOW,IICOL)-IBIGH
      IF((ILAND(IIRCW)+ICHAT(IICOL)).LT.IICOS(IIRCW,IICOL))
      *      GO TO 275
      IREST(9)=IREST(9)+IICOS(IIRCW,IICOL)
      *      -ILAND(IIRCW)-ICHAT(IICOL)
      ILAND(IIRCW)=IICOS(IIRCW,IICOL)-ICHAT(IICOL)
275  IPNCD=ISACD
      ISACD=ISACD+1
      IF(ISNCD.LE.ISCAR) GO TO 350
      IINCL=ISCAR-1
      DO 280 I=1,IINCL
      IIRCW=ISTOR(IBPTR+I+4)
      IF(IIRCW.LT.0) GO TO 280
      IICCL=IAS(ISTOR(IBPTR+I+5))
      IICOS(IIRCW,IICOL)=IICOS(IIFOW,IICOL)+IBIGH
      IREST(9)=IREST(9)-IBIGH
280  CONTINUE
      ISNCD=ISTOR(IPPTR+1)
      IPPTR=ISTOR(IPPTR)
285  IF(IPPTR.EQ.0) GO TO 305
      ISCAR=ISTOR(IPPTR+4)
      IIRCL=ISTOR(IPPTR+ICD+4)
      ITNCD=ISACD+1
      IF(IIRCL.GT.ISCAR) IINCD=1
      IICCL=IAS(ISTOR(IPPTR+ITNCD+4))
      IICOS(IIRCW,IICCL)=IICOS(IIFOW,IICOL)+IBIGH
      IF((ILAND(IIRCW)+ICHAT(IICOL)).LT.IICOS(IIRCW,IICOL))

```

```

      *      GO TO 205
      IF(ST(9)-TREST(15)+IICOL(IIPROW,IICOL)
      *      -ITAC(IIPTR)-IICOL(IIPTR,IICOL)
      *      -ITAC(IIPTR)-IICOL(IIPTR,IICOL)
      *      -ITAC(IIPTR)-IICOL(IIPTR,IICOL)
205  IICOL=IICOL+1
      IF(IICOL.EQ.0) GO TO 340
      DO 295 I=1, IICOL
      IICOL=ISTOR(IIPTR+I+4)
      IF(IICOL.LT.1) GO TO 340
      IICOL=IACB(IICOL(IIPTR+I+4))
      IICOL(IIPROW,IICOL)=IICOL(IIPROW,IICOL)+IICOL
      IREST(9)=I-REST(9)+IICOL
295  CONTINUE
300  ISNCD=ISTOR(IIPTR+1)
      IIPTR=ISTOR(IIPTR)
      GO TO 285

C
C      REMOVE UNBRANCHED PROBLEM
C
305  IIPTR=IIPTR
310  IF(ISTOR(IIPTR+3).GT.0) GO TO 315
      IIPTR=IIPTR
      IIPTR=ISTOR(IIPTR)
      ISTOR(IIPTR)=IIPTR
      IIPTR=IIPTR
      IF(IIPTR.EQ.0) GO TO 315
      ISTOR(IIPTR+3)=ISTOR(IIPTR+3)+1
      GO TO 310

C
C      BRANCH ON LEAST LOWER BOUND SUBPROBLEM
C
315  IF(IASUB.EQ.0) GO TO 400
      IIPTR=0
      IICOL=IICOL
      DO 320 I=1, IASUB
      IF(ISTOR(IIPTR+I+2).GE.IICOL) GO TO 320
      IIPTR=ISTOR(IIPTR)
      IICOL=I
      IICOL=ISTOR(IIPTR+2)
320  CONTINUE
      IF(IIPTR.EQ.0) GO TO 400
      ISPTR(IICOL)=ISPTR(IASUB)
      INSLB=IASUB-1

C
C      PROHIBIT AND REQUIRE ARCS
C
      ISNCD=ISTOR(IIPTR+1)
      IIPTR=ISTOR(IIPTR)
330  IF(IIPTR.EQ.0) GO TO 350
      ISCAR=ISTOR(IIPTR+4)
      IICOL=ISTOR(IIPTR+ISNCD+4)
      IINCD=ISNCD+1
      IF(ITAC.GT.ISCAR) IINCD=1
      IICOL=IACB(ISTOR(IIPTR+IINCD+4))
      IICOL(IIPROW,IICOL)=IICOL(IIPROW,IICOL)+IICOL
      IINCD=ISNCD+1
      IF(IINCD.LT.1) GO TO 345
      DO 340 I=1, IINCD
      IICOL=ISTOR(IIPTR+I+4)
      IF(IICOL.LT.1) GO TO 340
      IICOL=IACB(ISTOR(IIPTR+I+5))
      IICOL(IIPROW,IICOL)=IICOL(IIPROW,IICOL)+IICOL
      IREST(9)=I-REST(9)+IICOL
      IF((ILAND(IIPROW)+IICOL).LE.IICOL(IIPROW,IICOL))

```



```

IF (INCH=0) GO TO 3000
KLOC=INCH
C
C-----ORIGINAL PHASE: STEP 1- MARK ROWS AND
C-----LABEL COLUMNS. (FOR FLOW LABELING)
C
      IF0=F1
      JSTRT=F0
3010 P1=P1+1
3020 TR0=LIST(0)
      DO 3100 J=1,N
      IF (MARKER(J).NE.0) GO TO 3040
      IF (100*(INCH-LAPDA*INCH)-CHAI(J).GT.0) GO TO 3100
C-----FORWARD LABEL
      MARKER(J)=INCH
C-----CHECK FOR PARTIAL BREAKTHROUGH
      IF (IAT(3) .NE. 0) GO TO 3050
      JSTRT=J
      PERK=PERK+1
      GO TO 4000
C-----REVERSE LABEL
3050 NROW=NROW+1
      LIST(NROW)=IAT(J)
3100 CONTINUE
      FROM=FROM+1
      IF (100*(1E-NACH) .GE. 0) GO TO 3010
      VAL3=KLOC
      IF ((VAL2-VAL3).GE.RESULTS(12)) GO TO 4000
      VAL3=0
C-----LABELING COMPLETE
C
C-----DUAL PHASE: STEP 1- FIND MINIMUM INCH
C-----COST IN MARKED ROWS AND UNMARKED COLUMNS
C
      DIT=DIT+1
      CMIN=99999999
      DO 3120 I=1,NROW
      INCH=LIST(I)
      DO 3150 J=1,N
      IF (MARKER(J).NE.0) GO TO 3150
      ITEST=C*(INCH,J)-LAPDA*(INCH)-CHAI(J)
      IF (ITEST<CMIN) 3120,3130,3150
3120 NZERO=1
      ZLIST(1)=INCH
      ZLIST(2)=J
      CMIN=ITEST
      FULL=.FALSE.
      JSTRT=0
      GO TO 3145
3130 IF (NZERO.LT.(ZMAX/2)) GO TO 3145
      FULL=.TRUE.
      GO TO 3145
3140 NZERO=NZERO+1
      ZLIST(2*NZERO-1)=INCH
      ZLIST(2*NZERO)=J
C-----NOTE DUAL BREAKTHROUGH IF IT OCCURS
3145 IF (IAT(J).NE.0) GO TO 3150
      JSTRT=J
      ISTD=INCH
3150 CONTINUE
3200 CONTINUE
      VAL2=KLOC
      IF ((VAL2-VAL3).GE.RESULTS(12)) GO TO 4000
      VAL2=0

```

```

C-----ORIGINAL TABLES OF 2-1000000 BY THE ASSIGNMENT
C-----ALPHABETICALLY AND NUMBER MARKINGS
C-----COLUMN MULTIPLES
DO 3400 J=1,N
IF(CHARACTER(J).EQ.'0')GO TO 3410
CHARACTER(J)=J*1000000
VAL=VAL+J*1000000
3400 CONTINUE
C-----ROW INITIALIZE
DO 3400 I=1,NROW
LAMBDA(I)=1000000+LAMBDA(LIST(I)+1)*1000000
3400 VAL=VAL+J*1000000
C-----CHECK FOR QUAL BREAKTHROUGHS
IF(JLIST(I).EQ.0)GO TO 3410
DERR=J*1000000
MARK(I)=J*1000000
GO TO 3400
3410 CONTINUE
C-----UPDATE COLUMN MARKER LABELS
DO 3400 K=1,NROW
JROW=JLIST(K)
JROW=JLIST(J*1000000)
MARKER(JROW)=JROW
IF(JROW.EQ.0)GO TO 3400
DO 3400 K=1,NROW
3440 IF(LIST(JROW+K).EQ.IHAT(JROW))GO TO 3450
3450 ADDR=ADDR+1
LIST(ADDR+JROW)=IHAT(JROW)
3500 CONTINUE
C-----CHECK TO SEE IF ALL ZERO ARE IN ZLIST
IF(.NOT.FULL)GO TO 3510
C-----START SCANNING FROM LAST ENTRY IN ZLIST
I1=ZLIST(ZMAX-1)
J1=ZLIST(ZMAX)+1
DO 3600 I=1,NROW
3600 IF(I1.EQ.LIST(I))ITER=J
I1=ITER
IF(J1.NE.N)GO TO 3610
I1=I+1
IF(I1.GT.NROW)GO TO 3900
J1=I
3610 DO 3600 K=I1,NROW
I=LIST(K)
DO 3700 J=J1,N
IF(MARKER(J).NE.0)GO TO 3700
IF((C(1,J)-LAMBDA(I)-CHAR(J)).GT.0)GO TO 3700
MARKER(J)=I
DO 3640 K=1,ADDRON
3640 IF(LIST(ADDRON+K).EQ.IHAT(J))GO TO 3700
3650 ADDR=ADDR+1
LIST(ADDRON+J)=IHAT(J)
3700 CONTINUE
J1=1
3750 CONTINUE
3800 CONTINUE
IFOK=NO
NROW=NROW-ADDRON
C-----NROW, ADDR, J, K, CONTINUE LABELING
GO TO 3000
C
C-----ORIGINAL TABLES OF 2-1000000 BY THE ASSIGNMENT

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B-7

Chromatics (BASIC)
Cobb County Data Development
Program for
Dial-A-Ride

```

30 REM ***** PROGRAM TEMPLATES *****
40 REM *****
50 REM ***** THIS PROGRAM DISPLAYS A MAP OF COCS COUNTY GEORGIA
60 REM ***** IT CAN BE USED TO CREAT OR ADD TO A MENU FILE
70 REM *****
80 DATA 425,30,455,90
90 DATA 425,100,455,110
100 DATA 420,388,480,300
110 DATA 425,310,455,310
120 DATA 420,480,455,490
130 FILE=0
140 DIM LABEL(10),PLACE(10)
150 LABEL(1)= "MARK COCS"
160 PLACE(1)=0
170 LABEL(2)= "TRUCK MAP"
180 PLACE(2)=1
190 LABEL(3)= "SAVE TRIP"
200 PLACE(3)=0
210 LABEL(4)= "OLD FILE"
220 PLACE(4)=0
230 LABEL(5)= "NEW FILE"
240 PLACE(5)=0
250 REM *****MENU PLAC*****
260 FOR I=1 TO 5
270 FOR J=1 TO 4
280 READ MENU(I,J)
290 NEXT J
300 NEXT I
310 PRINT CHR$(12):
320 REM *****MENU AND MAP*****
330 PRINT "*****COCS COUNTY GEORGIA*****"
340 PRINT "*****"
350 PRINT "*****"
360 PRINT "*****"
370 PRINT "*****"
380 PRINT "*****"
390 PRINT "*****"
400 PRINT "*****"
410 PRINT "*****"
420 PRINT "*****"
430 PRINT "*****"
440 PRINT "*****"
450 PRINT "*****"
460 PRINT "*****"
470 PRINT "*****"
480 PRINT "*****"
490 PRINT "*****"
500 PRINT "*****"
510 PRINT "*****"
520 PRINT "*****"
530 PRINT "*****"
540 PRINT "*****"
550 PRINT "*****"
560 PRINT "*****"
570 PRINT "*****"
580 PRINT "*****"
590 PRINT "*****"
600 PRINT "*****"
610 PRINT "*****"
620 PRINT "*****"
630 PRINT "*****"
640 PRINT "*****"
650 PRINT "*****"
660 PRINT "*****"
670 PRINT "*****"
680 PRINT "*****"
690 PRINT "*****"
700 PRINT "*****"
710 PRINT "*****"
720 PRINT "*****"
730 PRINT "*****"
740 PRINT "*****"
750 PRINT "*****"
760 PRINT "*****"
770 PRINT "*****"
780 PRINT "*****"
790 PRINT "*****"
800 PRINT "*****"
810 PRINT "*****"
820 PRINT "*****"
830 PRINT "*****"
840 PRINT "*****"
850 PRINT "*****"
860 PRINT "*****"
870 PRINT "*****"
880 PRINT "*****"
890 PRINT "*****"
900 PRINT "*****"
910 PRINT "*****"
920 PRINT "*****"
930 PRINT "*****"
940 PRINT "*****"
950 PRINT "*****"
960 PRINT "*****"
970 PRINT "*****"
980 PRINT "*****"
990 PRINT "*****"

```

```

600 Y=CHRSY(4)
610 IF X > 400 THEN GOTO 940
620 Y1=Y
630 PRINT "STEP 1"
640 PRINT "X="
650 PLOT X2=5,Y1=5,X1=40,Y1=5
660 OUTAH90,0
670 RESUME 740
680 PRINT CHR$(21)
690 ON ERROR #2 GOTO 770
700 GOTO 760
710 REM *****DESTINATION POINT INPUT*****
720 X2=CURSX(4)
730 Y2=CHRSY(4)
740 IF Y2 > 400 GOTO 2070
750 PRINT CHR$(27) "OA2"CHR$(12)CHR$(27) "OA3"
760 PRINT "GTL"CHR$(1)
770 PRINT "X="
780 PLOT X2=5,Y2=5,X1=5,Y1=5
790 OUTAH90,0
800 RESUME 670
810 PRINT CHR$(21)
820 PRINT "GTL"CHR$(1)
830 PRINT "X="
840 PLOT X1,Y1
850 PLOT X2,Y2
860 PRINT CHR$(21)CHR$(27)
870 GOTO 590
880 REM *****MENU LOCATE ROUTINE*****
890 IF X < 5 OR X > 510 THEN GOTO 1010
900 IF Y > 25 AND Y < 100 THEN GOTO 1030
910 IF Y > 125 AND Y < 200 THEN GOTO 1040
920 IF Y > 225 AND Y < 300 THEN GOTO 1050
930 IF Y > 325 AND Y < 400 THEN GOTO 1060
1000 IF Y > 425 AND Y < 500 THEN GOTO 1070
1010 OUTAH90,0
1020 RESUME 590
1030 REM *****MARK EOF ROUTINE*****
1040 PRINT CHR$(27) "OA3"
1050 PRINT "GTL"CHR$(1)
1060 PLOT MENU(1,1),MENU(1,2),MENU(1,3),MENU(1,4)
1070 PRINT "GTL"CHR$(1)
1080 PLOT MENU(1,1),MENU(1,2),MENU(1,3),MENU(1,4)
1090 PRINT CHR$(21)CHR$(27) "OA0"
1100 PRINT #6: CHR$(30)
1110 DOS"CLOSE 6 "+NAME$
1120 IF FILE0 = 1 THEN DOS"CL(5)
1130 FILE0=0
1140 PRINT CHR$(27)CHR$(27) "OA0"CHR$(12)CHR$(27)
1150 PRINT CHR$(21)CHR$(27) "GTL" "DO YOU WANT TO CREATE "
1160 PRINT " OR ADD TO ANOTHER FILE"
1170 INPUT ANS$
1180 IF ANS$="NO" THEN STOP
1190 PRINT " "
1200 PRINT "SELECT NEW OR OLD FILE"
1210 PRINT CHR$(27)CHR$(27) "OA0"
1220 OUTAH90,0
1230 RESUME 590
1240 REM *****MENU MAP ROUTINE*****
1250 PRINT CHR$(27) "OA2"CHR$(12)CHR$(27) "OA3"
1260 PRINT "GTL"CHR$(1)
1270 PLOT 101,400
1280 PRINT CHR$(21)

```



```

1000 PRINT "OLD FILE ROUTINE"
1010 PRINT "C1":GOTO 1020
1020 PLOT (12.5,12.5) : LINE (12.5,12.5) : LINE (12.5,14.5)
1030 PRINT "C1":GOTO 1040
1040 PLOT (12.5,14.5) : LINE (12.5,14.5) : LINE (12.5,16.5)
1050 PRINT "C1":GOTO 1060
1060 PLOT (12.5,16.5) : LINE (12.5,16.5) : LINE (12.5,18.5)
1070 PRINT "C1":GOTO 1080
1080 PLOT (12.5,18.5) : LINE (12.5,18.5) : LINE (12.5,20.5)
1090 PRINT "C1":GOTO 1100
1100 PLOT (12.5,20.5) : LINE (12.5,20.5) : LINE (12.5,22.5)
1110 PRINT "C1":GOTO 1120
1120 PLOT (12.5,22.5) : LINE (12.5,22.5) : LINE (12.5,24.5)
1130 PRINT "C1":GOTO 1140
1140 PLOT (12.5,24.5) : LINE (12.5,24.5) : LINE (12.5,26.5)
1150 PRINT "C1":GOTO 1160
1160 PLOT (12.5,26.5) : LINE (12.5,26.5) : LINE (12.5,28.5)
1170 PRINT "C1":GOTO 1180
1180 PLOT (12.5,28.5) : LINE (12.5,28.5) : LINE (12.5,30.5)
1190 PRINT "C1":GOTO 1200
1200 PLOT (12.5,30.5) : LINE (12.5,30.5) : LINE (12.5,32.5)
1210 PRINT "C1":GOTO 1220
1220 PLOT (12.5,32.5) : LINE (12.5,32.5) : LINE (12.5,34.5)
1230 PRINT "C1":GOTO 1240
1240 PLOT (12.5,34.5) : LINE (12.5,34.5) : LINE (12.5,36.5)
1250 PRINT "C1":GOTO 1260
1260 PLOT (12.5,36.5) : LINE (12.5,36.5) : LINE (12.5,38.5)
1270 PRINT "C1":GOTO 1280
1280 PLOT (12.5,38.5) : LINE (12.5,38.5) : LINE (12.5,40.5)
1290 PRINT "C1":GOTO 1300
1300 PLOT (12.5,40.5) : LINE (12.5,40.5) : LINE (12.5,42.5)
1310 PRINT "C1":GOTO 1320
1320 PLOT (12.5,42.5) : LINE (12.5,42.5) : LINE (12.5,44.5)
1330 PRINT "C1":GOTO 1340
1340 PLOT (12.5,44.5) : LINE (12.5,44.5) : LINE (12.5,46.5)
1350 PRINT "C1":GOTO 1360
1360 PLOT (12.5,46.5) : LINE (12.5,46.5) : LINE (12.5,48.5)
1370 PRINT "C1":GOTO 1380
1380 PLOT (12.5,48.5) : LINE (12.5,48.5) : LINE (12.5,50.5)
1390 PRINT "C1":GOTO 1400
1400 PLOT (12.5,50.5) : LINE (12.5,50.5) : LINE (12.5,52.5)
1410 PRINT "C1":GOTO 1420
1420 PLOT (12.5,52.5) : LINE (12.5,52.5) : LINE (12.5,54.5)
1430 PRINT "C1":GOTO 1440
1440 PLOT (12.5,54.5) : LINE (12.5,54.5) : LINE (12.5,56.5)
1450 PRINT "C1":GOTO 1460
1460 PLOT (12.5,56.5) : LINE (12.5,56.5) : LINE (12.5,58.5)
1470 PRINT "C1":GOTO 1480
1480 PLOT (12.5,58.5) : LINE (12.5,58.5) : LINE (12.5,60.5)
1490 PRINT "C1":GOTO 1500
1500 PLOT (12.5,60.5) : LINE (12.5,60.5) : LINE (12.5,62.5)
1510 PRINT "C1":GOTO 1520
1520 PLOT (12.5,62.5) : LINE (12.5,62.5) : LINE (12.5,64.5)
1530 PRINT "C1":GOTO 1540
1540 PLOT (12.5,64.5) : LINE (12.5,64.5) : LINE (12.5,66.5)
1550 PRINT "C1":GOTO 1560
1560 PLOT (12.5,66.5) : LINE (12.5,66.5) : LINE (12.5,68.5)
1570 PRINT "C1":GOTO 1580
1580 PLOT (12.5,68.5) : LINE (12.5,68.5) : LINE (12.5,70.5)
1590 PRINT "C1":GOTO 1600
1600 PLOT (12.5,70.5) : LINE (12.5,70.5) : LINE (12.5,72.5)
1610 PRINT "C1":GOTO 1620
1620 PLOT (12.5,72.5) : LINE (12.5,72.5) : LINE (12.5,74.5)
1630 PRINT "C1":GOTO 1640
1640 PLOT (12.5,74.5) : LINE (12.5,74.5) : LINE (12.5,76.5)
1650 PRINT "C1":GOTO 1660
1660 PLOT (12.5,76.5) : LINE (12.5,76.5) : LINE (12.5,78.5)
1670 PRINT "C1":GOTO 1680
1680 PLOT (12.5,78.5) : LINE (12.5,78.5) : LINE (12.5,80.5)
1690 PRINT "C1":GOTO 1700
1700 PLOT (12.5,80.5) : LINE (12.5,80.5) : LINE (12.5,82.5)
1710 PRINT "C1":GOTO 1720
1720 PLOT (12.5,82.5) : LINE (12.5,82.5) : LINE (12.5,84.5)
1730 PRINT "C1":GOTO 1740
1740 PLOT (12.5,84.5) : LINE (12.5,84.5) : LINE (12.5,86.5)
1750 PRINT "C1":GOTO 1760
1760 PLOT (12.5,86.5) : LINE (12.5,86.5) : LINE (12.5,88.5)
1770 PRINT "C1":GOTO 1780
1780 PLOT (12.5,88.5) : LINE (12.5,88.5) : LINE (12.5,90.5)
1790 PRINT "C1":GOTO 1800
1800 PLOT (12.5,90.5) : LINE (12.5,90.5) : LINE (12.5,92.5)
1810 PRINT "C1":GOTO 1820
1820 PLOT (12.5,92.5) : LINE (12.5,92.5) : LINE (12.5,94.5)
1830 PRINT "C1":GOTO 1840
1840 PLOT (12.5,94.5) : LINE (12.5,94.5) : LINE (12.5,96.5)
1850 PRINT "C1":GOTO 1860
1860 PLOT (12.5,96.5) : LINE (12.5,96.5) : LINE (12.5,98.5)
1870 PRINT "C1":GOTO 1880
1880 PLOT (12.5,98.5) : LINE (12.5,98.5) : LINE (12.5,100.5)
1890 PRINT "C1":GOTO 1900
1900 PLOT (12.5,100.5) : LINE (12.5,100.5) : LINE (12.5,102.5)
1910 PRINT "C1":GOTO 1920
1920 PLOT (12.5,102.5) : LINE (12.5,102.5) : LINE (12.5,104.5)
1930 PRINT "C1":GOTO 1940
1940 PLOT (12.5,104.5) : LINE (12.5,104.5) : LINE (12.5,106.5)
1950 PRINT "C1":GOTO 1960
1960 PLOT (12.5,106.5) : LINE (12.5,106.5) : LINE (12.5,108.5)
1970 PRINT "C1":GOTO 1980
1980 PLOT (12.5,108.5) : LINE (12.5,108.5) : LINE (12.5,110.5)
1990 PRINT "C1":GOTO 2000
2000 PLOT (12.5,110.5) : LINE (12.5,110.5) : LINE (12.5,112.5)
2010 PRINT "C1":GOTO 2020
2020 PLOT (12.5,112.5) : LINE (12.5,112.5) : LINE (12.5,114.5)
2030 PRINT "C1":GOTO 2040
2040 PLOT (12.5,114.5) : LINE (12.5,114.5) : LINE (12.5,116.5)
2050 PRINT "C1":GOTO 2060
2060 PLOT (12.5,116.5) : LINE (12.5,116.5) : LINE (12.5,118.5)
2070 PRINT "C1":GOTO 2080
2080 PLOT (12.5,118.5) : LINE (12.5,118.5) : LINE (12.5,120.5)
2090 PRINT "C1":GOTO 2100
2100 PLOT (12.5,120.5) : LINE (12.5,120.5) : LINE (12.5,122.5)
2110 PRINT "C1":GOTO 2120
2120 PLOT (12.5,122.5) : LINE (12.5,122.5) : LINE (12.5,124.5)
2130 PRINT "C1":GOTO 2140
2140 PLOT (12.5,124.5) : LINE (12.5,124.5) : LINE (12.5,126.5)
2150 PRINT "C1":GOTO 2160
2160 PLOT (12.5,126.5) : LINE (12.5,126.5) : LINE (12.5,128.5)
2170 PRINT "C1":GOTO 2180
2180 PLOT (12.5,128.5) : LINE (12.5,128.5) : LINE (12.5,130.5)
2190 PRINT "C1":GOTO 2200
2200 PLOT (12.5,130.5) : LINE (12.5,130.5) : LINE (12.5,132.5)
2210 PRINT "C1":GOTO 2220
2220 PLOT (12.5,132.5) : LINE (12.5,132.5) : LINE (12.5,134.5)
2230 PRINT "C1":GOTO 2240
2240 PLOT (12.5,134.5) : LINE (12.5,134.5) : LINE (12.5,136.5)
2250 PRINT "C1":GOTO 2260
2260 PLOT (12.5,136.5) : LINE (12.5,136.5) : LINE (12.5,138.5)
2270 PRINT "C1":GOTO 2280
2280 PLOT (12.5,138.5) : LINE (12.5,138.5) : LINE (12.5,140.5)
2290 PRINT "C1":GOTO 2300
2300 PLOT (12.5,140.5) : LINE (12.5,140.5) : LINE (12.5,142.5)
2310 PRINT "C1":GOTO 2320
2320 PLOT (12.5,142.5) : LINE (12.5,142.5) : LINE (
```


B-8

Chromatics (BASIC)
Stand Alone Programs for
Dial-A-Ride

```

100 REM *** MAIN ***
110 OPEN "DATA" FOR INPUT AS #1
120 INPUT #1, A1, A2, A3, A4, A5, A6, A7, A8, A9, A10, A11, A12, A13, A14, A15, A16, A17, A18, A19, A20, A21, A22, A23, A24, A25, A26, A27, A28, A29, A30, A31, A32, A33, A34, A35, A36, A37, A38, A39, A40, A41, A42, A43, A44, A45, A46, A47, A48, A49, A50, A51, A52, A53, A54, A55, A56, A57, A58, A59, A60, A61, A62, A63, A64, A65, A66, A67, A68, A69, A70, A71, A72, A73, A74, A75, A76, A77, A78, A79, A80, A81, A82, A83, A84, A85, A86, A87, A88, A89, A90, A91, A92, A93, A94, A95, A96, A97, A98, A99, A100
130 GOTO 140
140 REM *** INITIALIZATION ***
150 DIM F1(100)
160 DIM F2(100)
170 DIM F3(100)
180 DIM F4(100)
190 DIM F5(100)
200 DIM F6(100)
210 DIM F7(100)
220 DIM F8(100)
230 DIM F9(100)
240 DIM F10(100)
250 DIM F11(100)
260 DIM F12(100)
270 DIM F13(100)
280 DIM F14(100)
290 DIM F15(100)
300 DIM F16(100)
310 DIM F17(100)
320 DIM F18(100)
330 DIM F19(100)
340 DIM F20(100)
350 DIM F21(100)
360 DIM F22(100)
370 DIM F23(100)
380 DIM F24(100)
390 DIM F25(100)
400 DIM F26(100)
410 DIM F27(100)
420 DIM F28(100)
430 DIM F29(100)
440 DIM F30(100)
450 DIM F31(100)
460 DIM F32(100)
470 DIM F33(100)
480 DIM F34(100)
490 DIM F35(100)
500 DIM F36(100)
510 DIM F37(100)
520 DIM F38(100)
530 DIM F39(100)
540 DIM F40(100)
550 DIM F41(100)
560 DIM F42(100)
570 DIM F43(100)
580 DIM F44(100)
590 DIM F45(100)
600 DIM F46(100)
610 DIM F47(100)
620 DIM F48(100)
630 DIM F49(100)
640 DIM F50(100)
650 DIM F51(100)
660 DIM F52(100)
670 DIM F53(100)
680 DIM F54(100)
690 DIM F55(100)
700 DIM F56(100)
710 DIM F57(100)
720 DIM F58(100)
730 DIM F59(100)
740 DIM F60(100)
750 DIM F61(100)
760 DIM F62(100)
770 DIM F63(100)
780 DIM F64(100)
790 DIM F65(100)
800 DIM F66(100)
810 DIM F67(100)
820 DIM F68(100)
830 DIM F69(100)
840 DIM F70(100)
850 DIM F71(100)
860 DIM F72(100)
870 DIM F73(100)
880 DIM F74(100)
890 DIM F75(100)
900 DIM F76(100)
910 DIM F77(100)
920 DIM F78(100)
930 DIM F79(100)
940 DIM F80(100)
950 DIM F81(100)
960 DIM F82(100)
970 DIM F83(100)
980 DIM F84(100)
990 DIM F85(100)
1000 DIM F86(100)
1010 DIM F87(100)
1020 DIM F88(100)
1030 DIM F89(100)
1040 DIM F90(100)
1050 DIM F91(100)
1060 DIM F92(100)
1070 DIM F93(100)
1080 DIM F94(100)
1090 DIM F95(100)
1100 DIM F96(100)
1110 DIM F97(100)
1120 DIM F98(100)
1130 DIM F99(100)
1140 DIM F100(100)
1150 REM *** MAIN LOOP ***
1160 FOR I=1 TO 100
1170 IF F1(I)=0 THEN GOTO 1180
1180 IF F2(I)=0 THEN GOTO 1190
1190 IF F3(I)=0 THEN GOTO 1200
1200 IF F4(I)=0 THEN GOTO 1210
1210 IF F5(I)=0 THEN GOTO 1220
1220 IF F6(I)=0 THEN GOTO 1230
1230 IF F7(I)=0 THEN GOTO 1240
1240 IF F8(I)=0 THEN GOTO 1250
1250 IF F9(I)=0 THEN GOTO 1260
1260 IF F10(I)=0 THEN GOTO 1270
1270 IF F11(I)=0 THEN GOTO 1280
1280 IF F12(I)=0 THEN GOTO 1290
1290 IF F13(I)=0 THEN GOTO 1300
1300 IF F14(I)=0 THEN GOTO 1310
1310 IF F15(I)=0 THEN GOTO 1320
1320 IF F16(I)=0 THEN GOTO 1330
1330 IF F17(I)=0 THEN GOTO 1340
1340 IF F18(I)=0 THEN GOTO 1350
1350 IF F19(I)=0 THEN GOTO 1360
1360 IF F20(I)=0 THEN GOTO 1370
1370 IF F21(I)=0 THEN GOTO 1380
1380 IF F22(I)=0 THEN GOTO 1390
1390 IF F23(I)=0 THEN GOTO 1400
1400 IF F24(I)=0 THEN GOTO 1410
1410 IF F25(I)=0 THEN GOTO 1420
1420 IF F26(I)=0 THEN GOTO 1430
1430 IF F27(I)=0 THEN GOTO 1440
1440 IF F28(I)=0 THEN GOTO 1450
1450 IF F29(I)=0 THEN GOTO 1460
1460 IF F30(I)=0 THEN GOTO 1470
1470 IF F31(I)=0 THEN GOTO 1480
1480 IF F32(I)=0 THEN GOTO 1490
1490 IF F33(I)=0 THEN GOTO 1500
1500 IF F34(I)=0 THEN GOTO 1510
1510 IF F35(I)=0 THEN GOTO 1520
1520 IF F36(I)=0 THEN GOTO 1530
1530 IF F37(I)=0 THEN GOTO 1540
1540 IF F38(I)=0 THEN GOTO 1550
1550 IF F39(I)=0 THEN GOTO 1560
1560 IF F40(I)=0 THEN GOTO 1570
1570 IF F41(I)=0 THEN GOTO 1580
1580 IF F42(I)=0 THEN GOTO 1590
1590 IF F43(I)=0 THEN GOTO 1600
1600 IF F44(I)=0 THEN GOTO 1610
1610 IF F45(I)=0 THEN GOTO 1620
1620 IF F46(I)=0 THEN GOTO 1630
1630 IF F47(I)=0 THEN GOTO 1640
1640 IF F48(I)=0 THEN GOTO 1650
1650 IF F49(I)=0 THEN GOTO 1660
1660 IF F50(I)=0 THEN GOTO 1670
1670 IF F51(I)=0 THEN GOTO 1680
1680 IF F52(I)=0 THEN GOTO 1690
1690 IF F53(I)=0 THEN GOTO 1700
1700 IF F54(I)=0 THEN GOTO 1710
1710 IF F55(I)=0 THEN GOTO 1720
1720 IF F56(I)=0 THEN GOTO 1730
1730 IF F57(I)=0 THEN GOTO 1740
1740 IF F58(I)=0 THEN GOTO 1750
1750 IF F59(I)=0 THEN GOTO 1760
1760 IF F60(I)=0 THEN GOTO 1770
1770 IF F61(I)=0 THEN GOTO 1780
1780 IF F62(I)=0 THEN GOTO 1790
1790 IF F63(I)=0 THEN GOTO 1800
1800 IF F64(I)=0 THEN GOTO 1810
1810 IF F65(I)=0 THEN GOTO 1820
1820 IF F66(I)=0 THEN GOTO 1830
1830 IF F67(I)=0 THEN GOTO 1840
1840 IF F68(I)=0 THEN GOTO 1850
1850 IF F69(I)=0 THEN GOTO 1860
1860 IF F70(I)=0 THEN GOTO 1870
1870 IF F71(I)=0 THEN GOTO 1880
1880 IF F72(I)=0 THEN GOTO 1890
1890 IF F73(I)=0 THEN GOTO 1900
1900 IF F74(I)=0 THEN GOTO 1910
1910 IF F75(I)=0 THEN GOTO 1920
1920 IF F76(I)=0 THEN GOTO 1930
1930 IF F77(I)=0 THEN GOTO 1940
1940 IF F78(I)=0 THEN GOTO 1950
1950 IF F79(I)=0 THEN GOTO 1960
1960 IF F80(I)=0 THEN GOTO 1970
1970 IF F81(I)=0 THEN GOTO 1980
1980 IF F82(I)=0 THEN GOTO 1990
1990 IF F83(I)=0 THEN GOTO 2000
2000 IF F84(I)=0 THEN GOTO 2010
2010 IF F85(I)=0 THEN GOTO 2020
2020 IF F86(I)=0 THEN GOTO 2030
2030 IF F87(I)=0 THEN GOTO 2040
2040 IF F88(I)=0 THEN GOTO 2050
2050 IF F89(I)=0 THEN GOTO 2060
2060 IF F90(I)=0 THEN GOTO 2070
2070 IF F91(I)=0 THEN GOTO 2080
2080 IF F92(I)=0 THEN GOTO 2090
2090 IF F93(I)=0 THEN GOTO 2100
2100 IF F94(I)=0 THEN GOTO 2110
2110 IF F95(I)=0 THEN GOTO 2120
2120 IF F96(I)=0 THEN GOTO 2130
2130 IF F97(I)=0 THEN GOTO 2140
2140 IF F98(I)=0 THEN GOTO 2150
2150 IF F99(I)=0 THEN GOTO 2160
2160 IF F100(I)=0 THEN GOTO 2170
2170 IF F1(I)=1 THEN GOSUB 1000: RESUME 140
2180 PRINT "*****END OF PROGRAM*****"
2190 END

```

```

3260 NEXT I
3270 RETURN
3400 REM *** MACRO - DRAW TRIP (GAIN IN COLOR C)
3410 PRINT "TRIP:"
3420 PRINT USING "###":
3430 PRINT "TRIP:"
3440 PLOT TP(I,1)-5,TP(I,2)+5,TP(I,3)+5,TP(I,4)+5
3450 PRINT "TRIP:"
3460 PLOT TP(I,1)+5,TP(I,2)-5,TP(I,3)-5,TP(I,4)-5
3470 PRINT "TRIP:"
3480 PLOT TP(I,1),TP(I,2),TP(I,3),TP(I,4)
3490 RETURN
3600 REM *** MACRO - DRAW CLUSTER (CLUSTER C, COLOR C)
3610 AT=0
3620 PRINT "CL:"
3630 PRINT USING "###":C:
3640 FOR I=1 TO NT
3650 IF TC(I,2)>0 THEN GOTO 3670
3660 IF C=0 THEN TA(I)=0
3670 IF TA(I)<0 THEN GOSUB 3400:AT=AT+1
3680 IF TA(I)=0 THEN TA(I)=0
3690 NEXT I
3700 RETURN
3800 REM *** MACRO - LOCATE CLUSTER
3810 ON=0
3820 IF Y>400 THEN GOTO 3850
3830 GOSUB 3200
3840 IF Y=0 THEN RETURN
3850 ON=TC(I,2)
3860 ON=TC(I,1)
3870 RETURN
3900 REM LOCATE CLUSTER FROM COLOR
3910 K=K+1
3920 IF K>NT THEN K=0:RETURN
3930 IF TC(K,1)<0 THEN GOTO 3910
3940 IF NJ=0 THEN GOTO 3970
3950 FOR J=1 TO NJ
3960 IF TC(K,2)=TC(J) THEN GOTO 3910
3970 NJ=NJ+1:OK(NJ)=TC(K,2)
3980 ON=TC(K,2)
3990 ON=TC(K,1)
4000 RETURN
4000 REM *** MACRO - LOCATE IYTH ON MENU (MENU M)
4010 MI=0
4020 FOR I=1 TO NX(M)
4030 IF X<MENU(M,I,1) OR X>MENU(M,I,3) THEN GOTO 4060
4040 IF Y<MENU(M,I,2) OR Y>MENU(M,I,4) THEN GOTO 4060
4050 GOTO 4080
4060 NEXT I
4070 RETURN
4080 MI=I:PRINT ON(7)
4090 IF MI=0 THEN GOTO 4080
4100 PRINT "WES0405511511"ICH(12):"1F":
4110 GOTO 4080
4120 PRINT "WES0405511"ICH(12):"1F":
4130 PRINT "WES0405511"ICH(12):"1F":
4140 PLOT MENU(M,I,1),MENU(M,I,2),MENU(M,I,3),MENU(M,I,4)
4150 PRINT "MENU:"
4160 RETURN
4170 REM *** COLOR PLOT READ-IN ROUTINE
4180 PRINT "READ IN:"
4190 PRINT "READ IN:"
4200 INPUT A:G

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4330 DEF FENL(M,N,X,MENL(1,1),MENL(1,2),MENL(1,3),MENL(1,4),SHX(K))
4340 FOR I=1 TO M
4350 INPUT #5: XX(K),SHX(K)
4360 NEXT K
4370 FOR I=1 TO XX
4380 INPUT #5: FENL(K,1,1),FENL(K,1,2),MENL(1,1),MENL(K,1,3),MENL(K,1,4)
4390 NEXT I
4400 XX=SHX(K)
4410 IF XX=0 THEN 4460
4420 FOR I=1 TO XX
4430 INPUT #5: MENL(K,1,1),MENL(K,1,2),MENL(K,1,3),MENL(K,1,4)
4440 NEXT I
4450 NEXT K
4460 GOSUB 4470
4480 RETURN
4500 REM *** MENU DRAW ROUTINE
4510 PRINT "MENU":
4520 FOR I=1 TO HY(M)
4530 PRINT "MFC":
4540 PRINT USING "M";MENL(M,1,5):
4550 PRINT "M":
4560 PLOT MENL(M,1,1),MENL(M,1,2),MENL(M,1,3),MENL(M,1,4):
4570 PRINT "MFC":
4580 PLOT MENL(M,1,1),MENL(M,1,2),MENL(M,1,3),MENL(M,1,4):
4590 NEXT I
4600 PRINT CHR$(21):
4610 IF SP(M)=0 THEN RETURN
4620 FOR I=1 TO SP(M)
4630 PRINT "MFC":
4640 PLOT MENL(M,1,1),MENL(M,1,2):
4650 PRINT "MFC":
4660 PRINT USING "M";MENL(M,1,3):
4670 PRINT CHR$(21):MENL(M,1):
4680 NEXT I
4690 PRINT "MFC":
4700 RETURN
4800 REM ***** EDIT FUNCTIONS
4810 IF Y<400 THEN 5000
4820 IF X<350 THEN K=0:GOTO 5010
4830 IF X<350 THEN K=2:GOSUB 4800:IF F2=0
4840 IF X<350 THEN K=3:GOSUB 4800:IF F2=1
4850 ON F2 GOTO 5100,5100,5200,5200
4860 IF F2=0 THEN 5000
4870 PRINT "M1,401,5100"CHR$(12):"MFC":5000:5000:11":
4880 PRINT "M1,1,5100"CHR$(12):"MFC":
4890 F2=0:IF F1=0:GOTO 5000:IF F1=1:GOTO 5200
4900 REM *** EDIT - RESTORE
4910 PRINT "M1,1,5100"CHR$(12):
4920 FOR I=1 TO 11
4930 TA(I)=0
4940 C=TC(I,0)
4950 GOSUB 4900
4960 NEXT I
4970 PRINT "M1,1,5111"CHR$(12):"MFC":
4980 F2=0
4990 IF F1=4 THEN RETURN
5000 GOTO 5000
5010 REM *** EDIT - SUBROUTINE
5020 IF Y<400 THEN 5200
5030 PRINT "M1,1,5110"CHR$(12):"MFC":
5040 GOTO 5000
5050 PRINT "M1,1,5110"CHR$(12):"MFC":
5060 GOTO 5000
5070 PRINT "M1,1,5110"CHR$(12):"MFC":
5080 GOTO 5000
5090 IF F1=0 THEN 5200

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5260 PAIRN=0
5270 ON GATEATA
5280 GOSUB 3400
5290 GOTO 5900
5300 REM *** EDIT - SUBILE CLUSTER
5310 IF Y<400 OR X>350 THEN 5500
5320 K=0
5330 PRINT "7:8TW1,1,511400";CHR$(12);"7:F";
5340 GOTO 5900
5350 GOSUB 3600
5360 IF CN=0 THEN 5900
5370 CF=0
5380 GOSUB 3600
5390 GOTO 5900
5400 REM *** EDIT - HIGHLIGHT CLUSTER
5410 IF Y<400 OR X>350 THEN 5700
5420 K=0
5430 PRINT "7:8TW1,1,511400";CHR$(12);"7:F";
5440 H=0
5450 GOTO 5900
5460 GOSUB 3600
5470 IF CN=0 THEN 5900
5480 PRINT "7:8TW1,1,511400";CHR$(12);"7:F";
5490 GOSUB 3600
5500 PRINT "7:2";
5510 GOTO 5900
5520 REM *** EDIT - RESET LIGHT PEN AND REDIAL EDIT
5530 OUTAH90,0
5540 RESUME 5920
5550 ON EACOR#2 GOTO 5950
5560 OUTAH90,0
5570 GOTO 5940
5580 X=CURSY(4);Y=CURSY(4)
5590 GOTO 5900
6000 REM **** CLUSTER FUNCTIONS
6010 IF Y<400 THEN 6050
6020 IF X<350 THEN K=0:MJ=0:PRINT "7:8TW1,1,511400";CHR$(12);"7:F";
6030 IF X<350 THEN H=3:GOSUB 4000:F2=0
6040 IF X>350 THEN H=0:GOSUB 4000:CF=MJ
6050 ON F2 GOTO 6200,6300,6400,6500,6600,6700
6060 IF F2=0 THEN 6900
6070 PRINT "7W1,401510010";CHR$(12);"7:35,401250010";
6080 PRINT "7W1,1,511400";CHR$(12);"7:F";
6090 F2=0:F3=0:OUTAH90,0:RESUME 120
6200 REM *** CLUSTER - SELECT CLUSTER
6210 IF Y < 400 OR X>350 THEN 6250
6220 K=0:MJ=0:CF=0:CA=0
6230 PRINT "7:8TW1,1,511400";CHR$(12);"7:50400 511511";CHR$(12);"7:F";
6240 GOTO 6900
6250 GOSUB 3600
6260 IF CN=0 THEN 6900
6265 CA=CN:CF=0
6270 PRINT "7:8TW1,1,511400";CHR$(12);"7:F";
6280 GOSUB 3600
6290 PRINT "7:2";
6295 GOTO 6900
6300 REM *** CLUSTER - CREATE CLUSTER
6310 IF Y<400 THEN 6900
6320 IF X>350 THEN 6350
6330 GOTO 6900
6350 PRINT "7:8TW1,1,511400";CHR$(12);"7:F";
6360 CF=0:CA=CF+1:CN=CN+1
6370 GOTO 6900
6400 REM *** CLUSTER - ADD TO CLUSTER

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6415 IF OC=0 THEN PRINT "18TW1,40050511";CHR(12);"";F2=0;GOTO 6500
6417 IF Y<400 THEN 6430
6419 PRINT "18TW1,40050511";CHR(12);"";F2=0
6420 GOTO 6430
6425 GOSUB 7300
6430 IF TA=0 THEN 6440
6435 TC(TN,1)=0;TC(TN,2)=0
6440 PRINT "18TW1,40050511";CHR(12);"";F2=0
6445 GOSUB 7300
6450 PRINT "2";
6455 GOSUB 7300
6460 PRINT "2";
6465 GOTO 6500
6500 REM *** CLUSTER - DELETE FROM CLUSTER
6510 IF OC=0 THEN PRINT "18TW1,40050511";CHR(12);"";F2=0;GOTO 6590
6520 IF Y<400 THEN 6540
6525 PRINT "18TW1,40050511";CHR(12);"";F2=0
6530 GOTO 6500
6540 GOSUB 7300
6550 IF TA=0 THEN 6560
6555 IF TC(TN,2)<>0 THEN 6560
6560 TC(TN,1)=7;TC(TN,2)=8;I=TN;C=7
6570 GOSUB 7300
6580 GOTO 6500
6600 REM *** REQUEST CLUSTER INFO
6700 REM *** TRANSFER CLUSTER INFO
6701 GOTO 6900
6900 REM *** CLUSTER - RESET LIGHT FEK AND RESUME CLUSTER
6910 OUTAP90,0
6920 RESUME 6930
6930 ON EAP0842 GOTO 6960
6940 OUTAP90,0
6950 GOTO 6950
6960 X=CURSX(4);Y=CURSY(4)
6970 GOTO 6000
7000 REM ***** ROUTE FUNCTIONS
7010 IF Y<400 THEN 7200
7020 IF X<350 THEN K=0;KJ=0;PRINT "18TW1,40050511";CHR(12);"";F2=0
7030 IF X<350 THEN M=4;GOSUB 4000;F2=M
7035 IF X>350 THEN M=0;GOSUB 4000;C=M-1
7040 ON F2 GOTO 7200,6000,7900,7900
7050 IF F2=0 THEN 7900
7060 PRINT "18TW1,401510510";CHR(12);"";C7="6350460350511";
7065 GOSUB 7300
7070 PRINT "18TW1,1,510700";CHR(12);"";F2=0
7080 F2=0;F1=0;OUTAP90,0;RESUME 120
7200 REM *** ROUTE - SELECT CLUSTER
7210 IF Y<400 OR X>350 THEN 7250
7220 K=0;PJ=0
7225 IF LP=1 THEN GOSUB 7300
7230 PRINT "18TW1,1,511400";CHR(12);"";F2=0
7240 GOTO 7900
7250 GOSUB 7300
7260 IF CR=0 THEN 7900
7270 PRINT "18TW1,1,511400";CHR(12);"";F2=0
7280 GOSUB 7300
7290 PRINT "2";
7295 GOTO 7900
7300 REM *** ROUTE/SELECT ROUTE/ACTIVE CLUSTER
7305 PRINT "18TW1,1,510390";CHR(12);"";F2=0
7310 FOR I=1 TO NT
7320 IF T(I)=0 THEN 7350
7330 C=10;I,1
7340 GOSUB 7300
7350 NEXT I

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7880 PRINT "W1,1,510,359":CHP(12):
7890 LET S
7900 RETURN
7910 REM *** ROUTE/ROUTE POST RAILROAD POINT GIVING
7920 PRINT "W3,1,510,359":CHP(12):
7930 PRINT "W7,1,510,359":CHP(12):
7940 PRINT "W11,1,510,359":CHP(12):
7950 PRINT "W15,1,510,359":CHP(12):
7960 PRINT "W19,1,510,359":CHP(12):
7970 PRINT "W23,1,510,359":CHP(12):
7980 REM *** ROUTE - RESET LIGHT SET AND POINT
7990 OUT(50,0)
8000 RESUME 7930
8010 ON ERROR GOTO 7960
8020 OUT(50,0)
8030 GOTO 7950
8040 X=CURX(4):Y=CURSY(4)
8050 GOTO 7960
8060 REM *** ROUTE - ROUTE MACRO
8070 IF C=0 THEN 7930
8080 PRINT "W1,1,510,359":CHP(12):
8090 C=2:GOTO 7930
8100 PRINT "W3,1,510,359":CHP(12):
8110 C=4:GOTO 7930
8120 PRINT "W5,1,510,359":CHP(12):
8130 C=6:GOTO 7930
8140 PRINT "W7,1,510,359":CHP(12):
8150 C=8:GOTO 7930
8160 PRINT "W9,1,510,359":CHP(12):
8170 C=10:GOTO 7930
8180 PRINT "W11,1,510,359":CHP(12):
8190 C=12:GOTO 7930
8200 PRINT "W13,1,510,359":CHP(12):
8210 C=14:GOTO 7930
8220 PRINT "W15,1,510,359":CHP(12):
8230 C=16:GOTO 7930
8240 PRINT "W17,1,510,359":CHP(12):
8250 C=18:GOTO 7930
8260 PRINT "W19,1,510,359":CHP(12):
8270 C=20:GOTO 7930
8280 PRINT "W21,1,510,359":CHP(12):
8290 C=22:GOTO 7930
8300 PRINT "W23,1,510,359":CHP(12):
8310 C=24:GOTO 7930
8320 PRINT "W25,1,510,359":CHP(12):
8330 C=26:GOTO 7930
8340 PRINT "W27,1,510,359":CHP(12):
8350 C=28:GOTO 7930
8360 PRINT "W29,1,510,359":CHP(12):
8370 C=30:GOTO 7930
8380 PRINT "W31,1,510,359":CHP(12):
8390 C=32:GOTO 7930
8400 PRINT "W33,1,510,359":CHP(12):
8410 C=34:GOTO 7930
8420 PRINT "W35,1,510,359":CHP(12):
8430 PRINT "W37,1,510,359":CHP(12):
8440 PRINT "W39,1,510,359":CHP(12):
8450 PRINT "W41,1,510,359":CHP(12):
8460 PRINT "W43,1,510,359":CHP(12):
8470 PRINT "W45,1,510,359":CHP(12):
8480 PRINT "W47,1,510,359":CHP(12):
8490 PRINT "W49,1,510,359":CHP(12):
8500 PRINT "W51,1,510,359":CHP(12):
8510 PRINT "W53,1,510,359":CHP(12):
8520 PRINT "W55,1,510,359":CHP(12):
8530 PRINT "W57,1,510,359":CHP(12):
8540 PRINT "W59,1,510,359":CHP(12):
8550 PRINT "W61,1,510,359":CHP(12):
8560 PRINT "W63,1,510,359":CHP(12):
8570 PRINT "W65,1,510,359":CHP(12):
8580 PRINT "W67,1,510,359":CHP(12):
8590 PRINT "W69,1,510,359":CHP(12):
8600 PRINT "W71,1,510,359":CHP(12):
8610 PRINT "W73,1,510,359":CHP(12):
8620 PRINT "W75,1,510,359":CHP(12):
8630 PRINT "W77,1,510,359":CHP(12):
8640 PRINT "W79,1,510,359":CHP(12):
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#, C3DIAL-A-RIDE PALMAY HIGH FILE C2

A, 0, C400L00 HIGH C2

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345,460,420,500,1

430,460,455,500,2

465,460,490,500,3

360,410,385,450,4

395,410,420,450,5

430,410,455,450,6

465,410,490,450,7

A, 5, C400TRAL MENU C2

5,430,95,480,7

55,430,95,480,7

105,430,145,480,7

155,430,195,480,7

14,425,2,"EDIT"

53,425,4,"CLUSTER"

110,425,6,"ROUTE"

150,425,3,"INITIATE"

70,502,7,"DIAL-A-RIDE PRINCIPAL SELECTION"

A, 9, C4ED17 MENU C2

5,430,95,480,7

55,430,95,480,7

105,430,145,480,7

155,430,195,480,7

205,430,245,480,7

6,425,2,"RESTORE"

50,425,4,"IGNORE"

50,414,4,"CLUSTER"

107,425,6,"IGNORE"

115,414,6,"APC"

151,425,3,"SELECT"

155,414,3,"CLUSTER"

213,425,7,"EXIT"

70,502,7,"DIAL-A-RIDE EXIT SUBFUNCTION"

#,11, C4CLUSTER WITH C2

5,430,40,480,7

50,430,40,480,7

95,430,130,480,7

140,430,175,480,7

135,430,220,480,7

230,430,265,480,7

275,430,310,480,7

5,425,6,"SELECT"

5,414,6,"CLUSTER"

50,425,3,"CREATE"

50,414,3,"CLUSTER"

95,425,2,"ADD TO"

95,414,2,"CLUSTER"

130,425,4,"DEL FRM"

142,414,4,"CLUSTER"

190,425,5,"REQST"

236,425,6,"EXIT"

279,425,7,"EXIT"

70,502,7,"DIAL-A-RIDE CLUSTER SUBFUNCTION"

#,9, C4ROUTING WITH C2

5,430,15,480,7

55,430,95,480,7

105,430,145,480,7

155,430,195,480,7

205,430,245,480,7

5,425,3,"SELECT"

5,414,3,"CLUSTER"

94,420,0,"PULLY"

100,420,0,"PULLY"

102,414,0,"PULLY"

100,420,0,"PULLY"

100,420,0,"PULLY"

210,420,7,"PULLY"

70,532,7,"PULLY-4-PID PULLY SUBROUTINE"

4,3, C4PULLY SUBROUTINE C2

370,430,480,480,7

410,430,480,480,7

450,430,480,480,7

370,414,2,"START"

415,414,6,"BACK"

455,414,4,"STOP"